Technical Information

UT130, UT150/UT152/UT155 Temperature Controller



TI 05C01E02-01E

Easy-to-use Controllers for Operators

Compact Body Large Display 48 x 48mm



UT130



Compact Body Full Functions 48 x 48mm

Simple Operation Less Space 48 x 96mm



Simple Operation Large Display 96 x 96mm

Features

- Large display
- Simple operation
- Available 24V AC/DC power supply
- Dynamic Auto Tune control
- Full alarm functions
- Retransmission outputs
- Timer function
- RUN / STOP switching



<Toc> <Ind> <Rev> <Introduction>

INTRODUCTION

The UT100 Series controllers are the controllers mainly for temperature control.

The UT100 Series controllers are developed using the newest technology based on the Yokogawa Group's experience for control for years and results cultivated from many applications.

■ Document Structure

This document describes the functions of UT100 Series controllers.

The document consists of the following chapters.

Chapter 1: This c hapter e xplains what a temperature controller is.

Chapter 2: This c hapter e xplains the model and suffix codes of the contr oller and the information f or or dering.

Chapter 3: This c hapter e xplains the P arameter Flo wchart and P arameter Lists of UT 100 Series controller s.

Chapter 4: This c hapter e xplains the basic operating pr ocedures when using a UT100 Series controller at fir st

Chapter 5: This c hapter e xplains the applied operations not described in Chapter 4.

Chapter 6: This c hapter e xplains the basic functions of UT100 Series contr oller s.

Chapter 7: This c hapter explains a tr oub leshooting f or err or s before/during operation.

Chapter 8: This c hapter explains the installation, wiring and har dware specifications.

■ Intended Readers

This document is intended to the following personnel:

- Instrumentation engineers or electrical engineers planning to use a temperature controller
- Instrumentation engineers or electrical engineers who would like to know the outline of a temperature controller

■ Trademark Acknowledgements

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UT130, UT150/UT152/UT155 Temperature Controller

TI 05C01E02-01E 1st Edition

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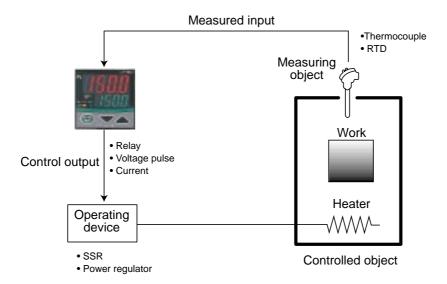
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1. DESCRIPTION OF TEMPERATURE CONTROL

■ Temperature Controller

The temperature controller is used to keep the fixed temperature of such as a furnace (controlled object). In general, the temperature controller has temperature indicating display and setpoint setting display, generates a control signal according to the difference between a indicating value (measured temperature value) and SP to finally make the temperature agree with SP.

Sensors such as thermocouple (TC) or RTD can be connected for measuring a temperature. And output types such as relay output or current output (4 to 20mA) are prepared according to the operating terminal (heater, valve, and the like) that actually controls a temperature.



■ Types of Temperature Control Action

ON/OFF action is the simplest action among the control actions. ON/OFF action of the internal thermostat keeps the optimum temperature. But the temperature control output fluctuates in the fixed cycle with ON/OFF action. If this temperature cycle causes a problem, the control action that changes the output in proportion to the deviation (the difference between the target setpoint and present value) can give a better control performance. Thus the control action that moves the function part in proportion to the deviation is referred to as a proportional action (P action). But a steady-state deviation (offset) is inherently unavoidable with proportional action alone. Though the manual reset can remove the offset, the same thing can be done using the control action together with the Integral action (I action) that will integrate the deviation as long as the deviation exists. This combination is referred to as a proportional-plus-integral action (PI action). It is the popular control method among the process control actions.

On the other hand, the derivative action (D action) is the action that changes the output in proportion to the rate-of-change of deviation. Since the output of derivative action depends on not the amount of deviation but its rate-of-change, the larger the rate-of-change is, the more intensive corrective action the controller takes to correct the process response in advance. Setting each optimum value with the PID action consisted of these three actions enables a stable control quickly.

■ Dynamic Auto Tune Control

The Dynamic Auto Tune Control is the function to automatically determine the optimum PID constants for continuing a good control when the controller is turned on or the control conditions are unstable. This control method is gentle to the controlled object itself because a disturbance needs not to be set forcibly like Auto tuning.

In Dynamic Auto Tune Control, the controller automatically monitors the behavior and determines the optimum PID constants when (1) at power on, (2) the output travels up to 100% or down to 0% and remains there after changing a setpoint, (3) process begins oscillating by disturbance and the like. The principle of Dynamic Auto Tune Control can be relied on because it is based on Geglar/Nichols's control method.

Refer to "6.5.1 Dynamic Auto Tune Control" on Page 6-6.

2. INFORMATION TO ORDER A CONTROLLER

2.1 Model and Suffix Codes

The models and suffix codes of UT130, UT150/UT152/UT155 standard types are as follows:

Туре	External Appearance	Ор	otions	Output	Standard Type Model
				Relay output	UT130-RN
UT130	170	Without alarm	Without	Voltage pulse output	UT130-VN
48x48x100mm			other options	Relay output	UT130-RN/AL
3-digit display	we death man	l		Voltage pulse output	UT130-VN/AL
Number of SP: 2	(D) TA	With 2 alarms		Relay output	UT130-RN/AL/RS
			With communication	Voltage pulse output	UT130-VN/AL/RS
					LUTIES DA
		Without alarm	ı	Relay output	UT150-RN
			1 1450	Voltage pulse output	UT150-VN
			Without other options	Current output Relay output	UT150-AN UT150-RN/AL
			Other options	Voltage pulse output	UT150-VN/AL
				Current output	UT150-AN/AL
			With	Relay output	UT150-RN/AL/RET
UT150			retransmission	Voltage pulse output	UT150-VN/AL/RET
48x48x100mm	* DOOD		output	Current output	UT150-AN/AL/RET
4-digit display	1500			Relay output	UT150-RN/AL/EX
Number of SP: 2		With 2 alarms	With external	Voltage pulse output	UT150-VN/AL/EX
		vviui z alaiifiS	contact input	Current output	UT150-AN/AL/EX
				Relay output	UT150-RN/AL/RS
			With communication	Voltage pulse output	UT150-VN/AL/RS
				Current output	UT150-AN/AL/RS
			With retransmission	Relay output	UT150-RN/AL/RET/EX
			output/external	Voltage pulse output	UT150-VN/AL/RET/EX
			contact input	Current output	UT150-AN/AL/RET/EX
		Without glorm		Relay output	UT152-RN
		Without alarm		Voltage pulse output	UT152-VN
	3880		Without	Current output	UT152-AN
			other options	Relay output	UT152-RN/AL
				Voltage pulse output	UT152-VN/AL
			With	Current output	UT152-AN/AL
			1	Relay output	UT152-RN/AL/RET
UT152	M.5- 007-		retransmission output	Voltage pulse output	UT152-VN/AL/RET
48x96x100mm 4-digit display			Output	Current output Relay output	UT152-AN/AL/RET UT152-RN/AL/EX
Number of SP: 2	Same of the last o		With external	Voltage pulse output	UT152-VN/AL/EX
		With 2 alarms	contact input	Current output	UT152-AN/AL/EX
			With communication	Relay output	UT152-RN/AL/RS
	THE REAL PROPERTY.			Voltage pulse output	UT152-VN/AL/RS
				Current output	UT152-AN/AL/RS
			With retransmission	Relay output	UT152-RN/AL/RET/EX
			output/external	Voltage pulse output	UT152-VN/AL/RET/EX
			contact input	Current output	UT152-AN/AL/RET/EX
				Relay output	UT155-RN
		Without alarm		Voltage pulse output	UT155-VN
			Without	Current output	UT155-AN
			other options	Relay output	UT155-RN/AL
				Voltage pulse output	UT155-VN/AL
	9559			Current output	UT155-AN/AL
			With	Relay output	UT155-RN/AL/RET
UT155	\$P.		retransmission	Voltage pulse output	UT155-VN/AL/RET
96x96x100mm	1888		output	Current output	UT155-AN/AL/RET
			With external	Relay output	UT155-RN/AL/EX
4-digit display	The second secon	With 2 alarms	contact input	Voltage pulse output Current output	UT155-VN/AL/EX
4-digit display Number of SP: 2				•	UT155-AN/AL/EX
			With communication	Relay output	1111155-RN/AL/RS
			With communication	Relay output Voltage pulse output	UT155-RN/AL/RS UT155-VN/AL/RS
			With communication	Voltage pulse output	UT155-VN/AL/RS
			With communication With retransmission		UT155-VN/AL/RS UT155-AN/AL/RS
				Voltage pulse output Current output	UT155-VN/AL/RS

Note 1: Heating/cooling control type is available in addition to the standard type described above. Refer to the following pages. Note 2: For options, the combinations other than those mentioned above are available. Refer to the following pages.

■ Standard type

UT130 Standard Type: Model and Suffix Codes

Model and Suffix Codes

Model	Suffix codes		odes	Description	
UT130)			Temperature controller (48 x 48 x 100mm)	
Control				Relay output (time-proportional PID or on/off control)	
output				Voltage pulse output (time-proportional PID control)	
Fixed N			Fixed		
	Options /AL Alarm outputs (2 points) (Note1) /HBA Heater disconnection alarm (includes the function of " /AL" option) /RS Communication function (Note 2)		AL_	Alarm outputs (2 points) (Note1)	
Ontions			IBA	Heater disconnection alarm (includes the function of " /AL" option) (Note 1)	
Options			Communication function (Note 2)		
			/\	/24	Power Supply 24V DC / 24V AC

Check the package contents against the list below.

- \bullet Temperature controller (of ordered model) $\cdots\cdots 1$
- Mounting bracket · · · · · · 1
 User's Manual (IM 05C01E02-01E) · · · · · · 1
- Note 1: The "/AL" and "/HBA" options cannot be specified at the same time. The "/HBA" option includes the function

Note 2: When specifying the "/RS" option, be sure to order the required number of copies of the Communication Functions User's Manual (IM05C01E12-10E) separately. (See Page 2-8.)

UT150 Standard Type: Model and Suffix Codes

Model and Suffix Codes

Model	Suffix Codes		Codes	Description
UT150	D .			Temperature controller (48 x 48 x 100 mm)
Control output	-R -V -A			Relay output (time-proportional PID or on/off control) Voltage pulse output (time-proportional PID control) 4 to 20mA output (current PID) (Note1)
Fixed	Fixed N		N	Fixed
Option			/AL /HBA /EX /RET /RS /V24	Alarm outputs (2 points) (Note2) Heater disconnection alarm (includes the function of "/AL" option) (Notes 2 and 3) SP1/SP2 switching, starting of timer, and RUN/STOP switching byexternal contacts (Notes 4 and 5) PV retransmission output in 4 to 20mA (Note 3) Communication function (Notes 4 and 6) Power Supply 24V DC / 24VAC

UT150 Table of Option	Combination
-----------------------	-------------

	/AL	/HBA	/EX	/RET	/RS	/V24
/AL		N/A	Α	Α	Α	Α
/HBA	N/A		N/A	N/A	Α	Α
/EX	Α	Α		Α	N/A	Α
/RET	Α	N/A	Α		Α	Α
/RS	Α	Α	N/A	Α		Α
/V24	Α	Α	Α	Α	Α	

Check the package contents against the list below.

A : Available N/A : Not available

- Note 1: The " /HBA" option cannot be specified when selecting "4 to 20mA output" as a control output type.
- Note 2: The "/AL" and "/HBA" options cannot be specified at the same time. The "/HBA" option includes the function of "/AL" option.
- Note 3: The "/HBA" and "/RET" options cannot be specified at the same time.
- Note 4: "/EX" and "/RS" options cannot be specified at the same time.
- Note 5: Two points of external contact inputs are available. Select 2 functions among SP1/SP2 switching, starting of timer, and RUN.STOP switching.
- Note 6: When specifying the "/RS" option, be sure to order the required number of copies of the Communication Functions User s Manual (IM05C01E12-10E) separately. (See Page 2-8)

UT152 / UT155 Standard Type: Model and Suffix Codes

Model and Suffix Codes

Model	Model Suffix codes			S Description
UT152	UT152			Temperature controller (48 x 96 x 100mm)
UT155				Temperature controller (96 x 96 x 100mm)
Control output -R -V			Relay output (time-proportional PID or on/off control) Voltage pulse output (time-proportional PID control) 4 to 20mA output (current PID) (Note1)	
Fixed N		N	Fixed	
			/AL	Alarm outputs (2 points) (Note2)
			/HB	Heater disconnection alarm (includes the function of "/AL" option) (Notes 2 and 3)
Option		/EX /RET		SP1/SP2 switching, starting of timer, and RUN/STOP switching by external contacts (Notes 4 and 5)
i i				PV retransmission output in 4 to 20mA (Note 3)
			/RS	Communication function (Notes 4 and 5)
	/V24		/V24	Power Supply 24V DC / 24VAC

- Check the package contents against the list below.
- Temperature controller (of ordered model) · · · · · · 1
- Mounting bracket · · · · · · 1
- User's Manual (IM 05C01E12-01E)1
- Note 1: The " /HBA" option cannot be specified when selecting "4 to 20mA output" as a control output type.
- Note 2: The "/AL" and "/HBA" options cannot be specified at the same time. The "/HBA" option includes the function of "/AL" option.
- Note 3: Two points of external contact inputs are available. Select 2 functions among SP1/SP2 switching, starting of timer, and RUN/STOP switching.
- Note 4: When specifying the "/RS" option, be sure to order the required number of copies of the Communication Functions User's Manual (IM 05C01E12-10E) separately. (See Page 2-8)

■ Heating/Cooling Type

UT130 Heating/Cooling Type: Model and Suffix Codes

Model and Suffix Codes

Model	Suffix codes		codes	Description
UT130				Temperature controller (48 x 48 x 100mm)
Control	Control output for heating -V			Relay output (time-proportional PID or on/off control)
for heating				Voltage pulse output (time-proportional PID control)
Control		R V		Relay output (time-proportional PID or on/off control)
output for coolin	g			Voltage pulse output (time-proportional PID control)
Option /A		/AL /HBA /RS /V24	Alarm outputs (2 points) (Note1) Heater disconnection alarm (includes the function of "/AL" option) (Notes 1 and 2) Communication function (Notes 2 and 3) Power Supply 24V DC / 24V AC	

Check the package contents against the list below.

- \bullet Temperature controller (of ordered model) $\cdots\cdots 1$
- User's Manual (IM 05C01E02-01E)

Note 1: The "/AL" and "/HBA" options cannot be specified at the same time. The "/HBA" option includes the function of "/AL" option.

Note 2: For heating/cooling type, the "/HBA" and "/RS" options cannot be specified at the same time.

Note 3: When specifying the "/RS" option, be sure to order the required number of copies of the Communication Functions User's Manual (IM05C01E12-10E) separately. (See Page 2-8)

● UT150 Heating/Cooling Type: Model and Suffix Codes

Model and Suffix Codes

	aci alia Gallix Godes							
Model	Suffix codes		odes	Description				
UT150					Temperature controller (48 x 48 x 100mm)			
Control output for heating	-R -V -V			Relay output (time-proportional PID or on/off control) Voltage pulse output (time-proportional PID control) 4 to 20mA output (current PID) (Note1)				
Control output for cooling	Control R			Relay output (time-proportional PID or on/off control) Voltage pulse output (time-proportional PID control) 4 to 20mA output (current PID) (Note1)				
Option /		AL HBA EX RS V24	Alarm outputs (2 points) (Note2) Heater disconnection alarm (includes the function of " /AL" option) (Notes 2 and 3) SP1/SP2 switching, starting of timer, and RUN/STOP switching byexternal contacts (Notes 3 and 4) PV retransmission output in 4 to 20mA Power Supply 24V DC / 24VAC					

i	IT150	Heating	/cooling	Type	Table of	Ontion	Combin	ation
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	/AL	/HBA	/EX	/RS	/V24
/AL		N/A	Α	Α	Α
/HBA	N/A		N/A	N/A	Α
/EX	Α	N/A		N/A	Α
/RS	Α	N/A	N/A		Α
/V24	Α	Α	Α	Α	

Check the package contents against the list below.

- \bullet Temperature controller (of ordered model) $\cdot\cdot\cdot\cdot\cdot 1$
- Mounting bracket · · · · · · 1
- User's Manual (IM 05C01E12-01E) · · · · · · · · · 1

A : Available N/A : Not available

- Note 1: The " /HBA" option cannot be specified when selecting "4 to 20mA output" as a control output type.
- Note 2: The "/AL" and "/HBA" options cannot be specified at the same time. The "/HBA" option includes the function of "/AL" option.
- Note 3: The "/HBA", "/EX" and "/RS" options cannot be specified at the same time.
- Note 4: Two points of external contact inputs are available. Select 2 functions among SP1/SP2 switching, starting of timer, and RUN/STOP switching.
- Note 5: When specifying the "/RS" option, be sure to order the required number of copies of the Communication Functions User's Manual (IM05C01E12-10E) separately. (See Page2-8)

● UT152 / UT155 Heating/Cooling Type: Model and Suffix Codes

Model and Suffix Codes

Model	Suf	fix	codes	Description
UT152				Temperature controller (48 x 96 x 100mm)
UT155				Temperature controller (96 x 96 x 100mm)
Control	-R			Relay output (time-proportional PID or on/off control)
output	<u>-</u> y			Voltage pulse output (time-proportional PID control)
for heatin	9 -A			4 to 20mA output (current PID) (Note1)
Control	F		<u> </u>	Relay output (time-proportional PID or on/off control)
output		Į۷	'	Voltage pulse output (time-proportional PID control)
for cooling	g	Α	<u> </u>	4 to 20mA output (current PID) (Note1)
			/AL_	Alarm outputs (2 points) (Note2)
	/HB		/HBA	Heater disconnection alarm (includes the function of "/AL" option) (Note 2)
Option			/EX	SP1/SP2 switching, starting of timer, and RUN/STOP switching by external contacts (Note 3)
			/RS	Communication function (Note 4)
			/V24	Power Supply 24V DC / 24V AC

Check the package contents against the list below.

- Temperature controller (of ordered model) · · · · · 1
- Mounting bracket · · · · · · · 1
- User's Manual (IM 05C01E12-01E)
- Note 1: The " /HBA" option cannot be specified when selecting "4 to 20mA output" as control output type.
- Note 2: The "/AL" and "/HBA" options cannot be specified at the same time. The "/HBA" option includes the function of "/AL" option.
- Note 3: Two points of external contact inputs are available. Select 2 functions among SP1/SP2 switching, starting of timer, and RUN/STOP switching.
- Note 4: When specifying the "/RS" option, be sure to order the required number of copies of the Communication Functions User's Manual (IM05C01E12-10E) separately. (See Page 2-8)

2.2 Mandatory Items to Specify

Specify the following necessary items on ordering

Specify the power supply voltage

When using 100 to 240V AC, no need to specify the item.

When using 24V AC/DC, specify the "/V24" option.

The frequency for both of them is 50/60Hz.

Specify the control output

<Example 1>

Specify "UT150-RN" for UT150 standard type with relay output.

<Example 2>

Specify "UT150-RV" for UT150 heating/cooling type with heating-side relay output and cooling-side voltage pulse output.

2.3 Optional Suffix Codes to Specify

The following options are available. But some of them are not available according to the model. See "2.1 Model and Suffix Codes" for combinations of options.

● When using one or two Alarms, specify the "/AL" option.

<Example> Model and Suffix Codes: UT130-RN/AL

● When using Heater Disconnection Alarm, specify the "/HBA" option. The "/HBA" option includes the function of "/AL" option.

<Example> Model and Suffix Codes: UT150-RN/HBA

When using Retransmission Output, specify the "/RET" option.

<Example> Model and Suffix Codes: UT150-AN/RET

• When using two Target Setpoints, specify the "/EX" option.

<Example> Model/Suffix Codes: UT150-RN/EX

• When using Timer Function, specify the "/AL/EX" or "/HBA/EX" options.

<Example> Model/Suffix Codes: UT150-VN/AL/EX

● When using RUN/STOP Switching Function, specify the "/EX" option.

<Example> Model/Suffix Codes: UT150-RN/EX

When using Communication Function, specify the "/RS" option.

<Example> Model/Suffix Codes: UT150-RN/RS

2.4 Other Items to Specify

■ Quality Inspection Certificate (QIC) and Traceability

The Quality Inspection Certificate (QIC) of the product at shipping is prepared.

And the Traceability, which certificates that the measuring instruments and generator used for the product inspection conforms to the inspection of national standards, is also prepared.

Quality Inspection Certificate(QIC)

Model: DOCTC

Calibration certificate (traceability)

"Traceability declaration to the national standards" and "Explanation of the Yokogawa's internal system for traceability"

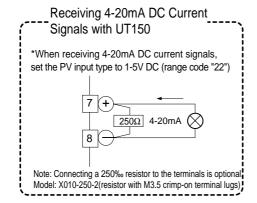
Model: Q62188-B

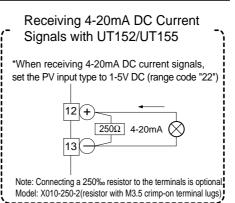
■ Auxiliary Equipment and Spare Parts

ullet 250 Ω Resistor

When a measured input signal is 4 to 20mA DC, the temperature controllers (UT150/UT152/UT155) receive it after converting to a 1 to 5V DC signal.

Model	Description
X010-250-2	Resistor with M3.5 crimp-on terminal lugs





Heater Disconnection Sensor (for 1 to 80A)

The heater current sensor used here is the "CTL-6-S-H" or "CTL-12-S36-8" sensor of U.R.D., Ltd.

This sensor is to be purchased by the users themselves.

Model: CTL-6-S-H or CTL-12-S36-8

Terminal Cover

Model	Description
L4000FB	Terminal cover for models UT130 and UT150 (1 set)
T9115YE Terminal cover for model UT152 (1 piece)	
T9115YD	Terminal cover for model UT155 (1 piece)

Mounting Bracket

Model	Description
L4000FA	Mounting bracket for models UT130 and UT150 (1 piece)
T9115NK	Mounting bracket for model UT152 (1 set)
T9115NL	Mounting bracket for model UT155 (1 set)

■ Measured Input Type, Scaling and Direct/Reverse Action can be Specified on Ordering

Measured input type, displayed scale at voltage input, and direct/reverse action for the temperature controller can be specified on ordering.

Items to specify	Description
Measured input type	Specify "1" to "7", "12", "13", and "15 to "19" for UT130. Specify "1" to "23" for UT150/UT152/UT155. If no input type is specified at the time of ordering, the temperaturecontroller is shipped with the parameter set to OFF (unidentified). In this case, set the input type on customer side. See "4.1 Setting Measured Input Type and Scale (Setting First)" for details.
Scaling (at voltage input)	The displayed scale can be specified when specifying "20" to "23" for UT150/UT152/UT155. If no scaling is specified, the temperature controller is shipped with the parameter set to "0.1 to 100.0".
Direct/reverse action	Specify "1" for direct action. If no action is specified, the temperature controller is shipped with the parameter set to "0" (reverse action).

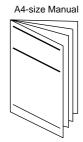
2.5 User's Manual

User's Manuals in A-2 size and A-4 size are prepared.

User's Manuals supplied along with the product is in A-2 size. Both Manuals in A-4 size and A-2 size have the same contents except for their appearances.

When specifying the "/RS" option, be sure to order the required number of copies of Communication Functions User's Manual separately.

The following User's Manuals can be purchased separately.



User's Manual for UT130 (A4 size)

Document Number: IM05C01E02-41E

● User's Manual for UT150/UT152/UT155 (A4 size)

Document Number: IM05C01E12-41E

● Communication Functions User's Manual for UT130, UT150/UT152/UT155 (A4 size)

Document Number: IM05C01E12-10E

3. NAMES AND FUNCTIONS OF EACH PART /PARAMETER

3.1 UT130 Names and Functions of Each Part (Principles of Key Operation)

SP display lamp (orange)

- Lit when SP is displayed or being changed.
- Flashes slowly (approx. once every second) when a parameter code is displayed.
- Flashes fast when a parameter value is being changed.



Al 1: Lit when the alarm 1 is activated AL2: Lit when the alarm 2 is activated.

SET /ENT key (data registering key)

- In the operating display, it switches between the PV (measured value) and SP (target setpoint) displays.
- Registers the data value changed using the data change keys.
- · Switches between operating displays or parameter setting display sequentially.
- Pressing the key for 3 seconds or more in the operating display retrieves the operating parameter setting display. You can transfer to the setup parameter setting display form the operating parameter
- Pressing the key for 3 seconds or more in either an operating or setup parameter setting display transfers back to the operating display.

Data display (red)

- In the operating display, either PV (measured value) or SP (target setpoint) is indicated. Which parameter takes precedence over the other
- depends on the parameter "DSP" value.
- In the parameter setting display, either the parameter codes or parameter value is indicated.
- If an error occurs, the error code is displayed.

Output (OUT) display lamps (Left: orange; right: green)

Lit while control output is being output.
Flashes according to the control output value during timeproportional output. (Flashes slowly when control output value is small; flashes fast when control output value is large.)

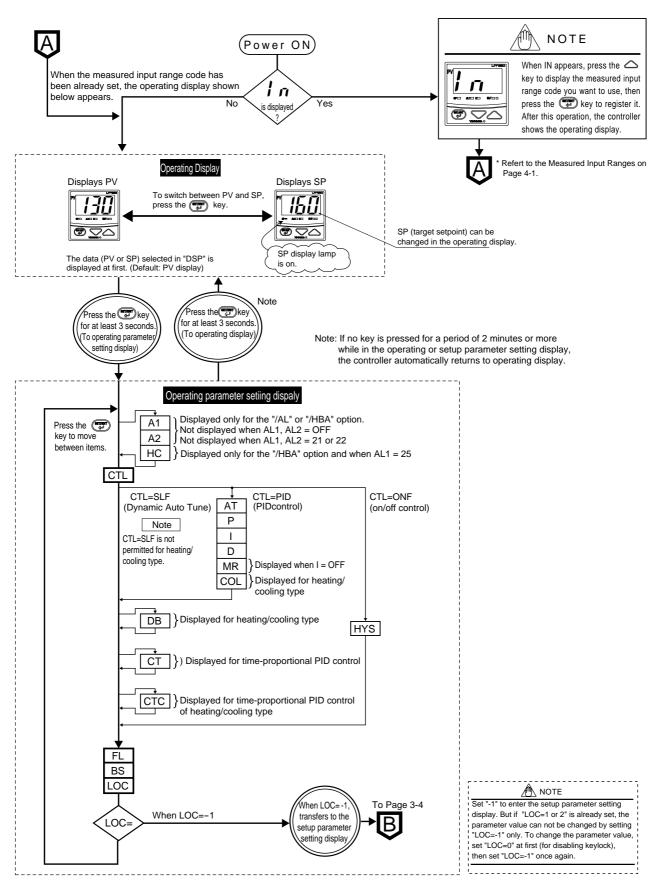
- The left lamp lights up in orange during control output of standard type.
- In heating/cooling control, the left lamp lights up in orange when the heating-side output is active; while the right lamp lights up in green when the cooling-side output is active.

Data change keys

- When PV is displayed in the operating display, a press of
- the or key switches to the SP display.

 When a parameter code is displayed, pressing either key once displays the parameter value (which can then be changed).
- Changes SP and the parameter values.
 Pressing the key decreases the data value and pressing the key increases it. Holding down the key will gradually increase the speed of the change.

3.2 UT130 Parameter Flowchart and Description



(1) Target Setpoint (SP)

Code	Name	Setting range and unit	Default	User setting	Reference page
(SP value display)	Target setpoint	Minimum value (SPL) to maximum value (SPH) of target setpoint range	SPL		P.4-9

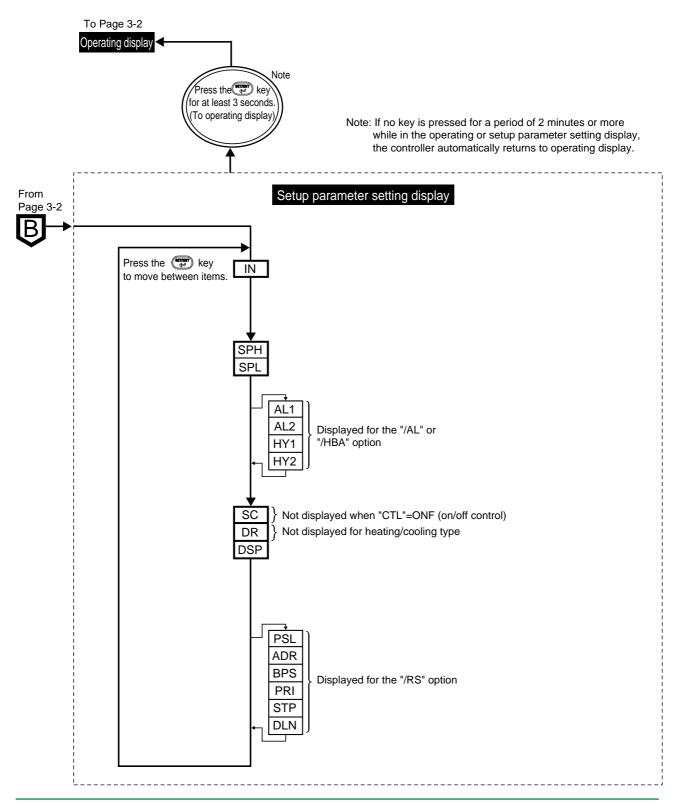
Numbers in () are the parmeter setpoints that apply when the communication function is used. Ex. $\,$ OFF(0), ON(1)

(2) Operating Parameters: Parameters changed rather frequently during operation.

Ľ	Code	Name	Setting range and unit	Default	User setting	Reference page
A1	R !	Alarm 1 setpoint	■ PV alarm Unit: °C/°F Setting range: Minimum value to maximum value of measured input range ■ Deviation alarm Unit: °C/°F Setting range: —100 to 100% of measured input range	Max. value of measured input range (PV alarm)		
A2	82	Alarm 2 setpoint	span ■ Heater disconnection alarm Unit: A (ampere) Setting range: OFF(0), 1 to 80 (can be set for the alarm 1 setpoint only)	Min. value of measured input range (PV alarm)		P.4-12 P.4-16 P.4-17
нс	HΣ	Heater disconnection current measured value	HC is not a parameter to be set. The current value (0 to 80 disconnection detector is displayed. Unit: A (ampere) Settings: When the display value is — —, the heater curren	·	d.	
CTL	[LL	Control mode	ONF(0): On/off control PID(1): PID control SLF(2): Dynamic auto tune control (cannot be set for heating/cooling control)	SLF(2) : standard type; PID(1) : heating/cooling type		P.4-5 P.6-1 P.6-6
АТ	ÄŁ	Auto-tuning	OFF(0): Stop auto-tuning(AT) ON(1): Start auto-tuning(AT)	OFF(0)		P.6-7
Р	F	Proportional band	1°C/°F to the temperature that corresponds to 100% of the measured input range span	5% of measurd input range span		P.6-2
ı	1	Integral time	1 to 999 seconds; OFF(0): no integral action	240 seconds		P.6-4
D	d	Derivative time	1 to 999 seconds; OFF(0): no derivative action	60 seconds		P.6-5
MR	ñ٢	Manual reset	-19.9 to 99.9 % : Standard type -100 to 100 % : Heating/cooling type	50.0% : Standard type; 0.0% :Heating/cooling type		P.6-4
COL	LoL	Cooling-side gain	0.01 to 9.99 times	1.00 time		P.5-8
DB	db	Dead band	■ PID control Unit: °C/°F Setting range: —(proportional band setting) to +(proportional band setting) ■ On/off control Unit: °C/°F Setting range: —50 to +50% of measured input range span	0% of measured input range span		P.5-8
HYS	H45	Hysteresis for on/off control	$0^{\circ}\text{C}/^{\circ}\text{F}$ to the temperature that corresponds to 100% of the measured input range span	0.5% of measured input range span		P.6-1
СТ	[Ŀ	Control output cycle time	1 to 240 seconds	30 seconds		P.4-8 P.6-8
стс	[LL[Cooling-side control output cycle time	1 to 240 seconds	30 seconds		P.6-8
FL	FL	PV input filter	OFF(0), 1 to 120 seconds	OFF(0)		P.5-2
BS	65	PV input bias	—100 to 100% of measured input range span	0% of measured input range span		P.5-1
LOC	LoC	Key lock	O: No key lock 1: Prevents operations from being changed except for the changing of SP in the operating display 2: Prevents all parameter changing operations —1: Set -1 to enter the setup parameter setting display. But if LOC=1 or 2 is already set, the parameter value can not be changed by setting LOC=1 only. To change the parameter value, set LOC=0 at first (for disabling keylock), then set LOC=1 once again.	0		P.5-7



Changing certain setup parameter may automatically initialize the operating parameters. Therefore, after you change the setup parameters, always check the operating parameter settings to find out if appropriate values have been set for them. If the operating parameters have been initialized, set them to their appropriate values.



3-5

Numbers in () are the parmeter setpoints that apply when the communication function is used. Ex. $\,$ OFF(0), ON(1)

(3) Setup Parameters: Parameters rarely changed in normal use after once having been set.

Code	Name	Setting range and unit	Default	User setting	Reference page
IN I I	Measured input type	1 to 7, 12, 13, 15 to 19, 31 to 37, 42, 43, 45 to 48 (See the measured input range code list.) OFF(0): No input (If no input type is specified at the time of ordering, you must set the input type.)	OFF(0), or the input range code specified with		P.4-1 P.5-1
SPH 5 PH	Maximum value of target setpoint range	(SPL+1°C) to the maximum value of measured input range; Unit: °C/°F	Maximum value of measured input range		P.5-2
SPL SPL	Minimum value of target setpoint range	Minimum value of measured input range to (SPH—1°C) Unit: °C/°F	Minimum value of measured input range		1.02
AL1 7	Alarm 1 type	OFF(0), 1 to 22 (See the alarm function list.) 25 (for the heater disconnection alarm /HBA option only)	1 (PV high limit alarm)		
	Alarm 2 type	OFF(0), 1 to 22 (See the alarm function list.)	2 (PV low limit alarm)		P.4-12 P.4-16
HY1 #4 1	Alarm 1 hysteresis	0 to 100% of measured input range span	0.5% of measured		P.4-17
HY2	Alarm 2 hysteresis	Unit: °C/°F	input range span		
sc 5 [SUPER function	ON(1): Uses the SUPER function OFF(0): Does not use SUPER function Note: Not displayed when on/off control	OFF(0)		P.6-10
DR J	Direct/reverse action	Reverse action Direct action Note: Not displayed for heating/cooling type	0		P.4-6
DSP 457	Priority of PV/SP display	0: Displays PV 1: Displays target setpoint (SP)	0		P.
PSL P5 L	Protocol selection	O: PC-link communication 1: PC-link communication with sum check 2: Ladder communication 3: MODBUS in ASCII mode 4: MODBUS in RTU mode	0		
ADR HIGH	Controller address	1 to 99 However, the number of controllers that can be connected per host device is 31 at the maximum.	1		
BPS 575	Baud rate	2.4(0): 2400 bps 4.8(1): 4800 bps 9.6(2): 9600 bps	9.6(2)		P.5-9
PRI FI- I	Parity	NON(0): Disabled EVN(1): Even parity ODD(2): Odd parity	EVN(1)		
STP 5 LP	Stop bit	1 or 2 bits	1 bit		
	Data length	7 or 8 bits • 8 bits when ladder, MODBUS (RTU) • 7 bits when MODBUS (ASCII)	8 bits		

UT150

SP2 DDD

UT152

OUT

3.3 UT150/UT152/UT155Names and Functions of **Each Part (Principles of Key Operation)**

SP2 lamp (green)

Lit when SP2 is being used for control operation.

Alarm 1 (AL1), Alarm 2 (AL2) lamps (red)

AL1: Lit when the alarm 1 is activated. AL2: Lit when the alarm 2 is activated

Output (OUT) display lamps (Left: orange; right: green)

Lit while control output is being output.
Flashes according to the control output value during time-proportional output or current output. (Flashes slowly when current control output value is small; flashes fast when it is large.)

The left lamp is lit in orange during control output of standard type.
In heating/cooling control, the left lamp lights up in orange when the heating-side output is active; while the right lamp lights up in green when the cooling-side output is active.

SET / ENT key (data registering key)

- Registers the data value changed using the data change keys.
- Switches between operating displays or parameter setting displays sequentially.
- Pressing the key for 3 seconds or more in the operating display retrieves the operating parameter setting display. You can transfer to the setup parameter setting display form the operating parameter setting display.
- Pressing the key for 3 seconds or more in either an operating or setup parameter setting display transfers back to operating display.

PV display (red)

Indicates PV (measured value) and character information such as parameter codes and error codes.

SP display (green)

Indicates SP (target setpoint) and parameter values.

Data change keys

- Change SP and the parameter values.
- Pressing the key decreases the data value and pressing the key increases it. Holding down the key will gradually increase the speed of the change.

SP2 lamp (green)

Lit when SP2 is being used for control operation.

Alarm 1 (AL1), Alarm 2 (AL2) lamps (red)

AL1: Lit when the alarm 1 is activated. AL2: Lit when the alarm 2 is activated.

Output (OUT) display lamps (Upper: orange: lower: green)

Lit while control output is being output.

Flashes according to the control output value during timeproportional output or current output. (Flashes slowly when current control output value is small; flashes fast when it is large.)

- The uppert lamp is lit in orange during control output of standard type • In heating/cooling control, the upper lamp lights up in orange
- when the heating-side output is active; while the lower lamp lights up in green when the cooling-side output is active.

SET / ENT key (data registering key)

- Registers the data value changed using the data change keys.
 Switches between operating displays or parameter setting displays sequentially.
- Pressing the key for 3 seconds or more in the operating display retrieves the operating parameter setting display. You can transfer to the setup parameter setting display form the
- operating parametersetting display.
 Pressing the key for 3 seconds or more in either an operating or setup parameter setting display transfers back to operating display.

PV display (red)

Indicates PV (measured value) and character information such as parameter codes and error codes.

SP display (green)

Indicates SP (target setpoint) and parameter values.

Data change keys

- Change SP and the parameter values.
- increase the speed of the change.

SP2 lamp (green)

Lit when SP2 is being used for control operation.

Alarm 1 (AL1), Alarm 2 (AL2) lamps (red)

AL1: Lit when the alarm 1 is activated. AL2: Lit when the alarm 2 is activated.

Output (OUT) display lamps (Upper: orange; lower: green)

Lit while control output is being output.

Flashes according to the control output value during time-proportional output or current output. (Flashes slowly when current control output value is small; flashes fast when it is large.)

The upper lamp is lit in orange during control output

- of standard type.
- In heating/cooling control, the upper lamp lights up in orange when the heating-side output is active; while the lower lamp lights up in green when the coolingside output is active.

SET / ENT key (data registering key)

- Registers the data value changed using the data change keys.
- Switches between operating displays or parameter setting
- displays sequentially.

 Pressing the key for 3 seconds or more in the operating display retrieves the operating parameter setting display. You can transfer to the setup parameter setting display form the operating parameter setting display.
- Pressing the key for 3 seconds or more in either an operating or setup parameter setting display transfers back to operating display.

PV display (red)

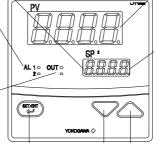
Indicates PV (measured value) and character information such as parameter codes and error codes.

SP display (green)

Indicates SP (target setpoint) and parameter values.

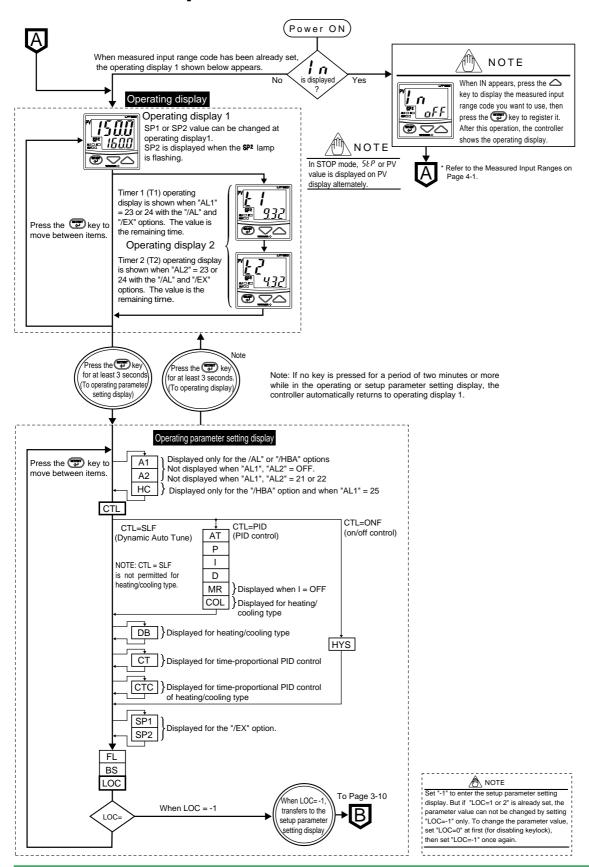
Data change keys

- Change SP and the parameter values.
- Pressing the key decreases the data value and pressing the key increases it. Holding down the key will gradually increase the speed of the change.



UT155

3.4 UT150/UT152/UT155 Parameter Flowchart and Description



(1) Target Setpoint (SP) and Timer Settings 1 and 2

Code		Name	Setting range and unit	Default	User setting	Reference page
(SP	value display)	Target setpoint	Minimum value (SPL) to maximum value (SPH) of target setpoint range	SPL		P.4-10
T1	Ł!	setting 1	0.0 to 99.59 Unit: minutes and seconds or hours and minutes Set the timer time unit using the parameter TTU.	0.00		P.5-6
T2	F2	Timer	For example, 15.25 sets 15 minutes and 25 seconds when the unit is minutes and seconds.(T1 is for AL1, and T2 is for AL2)	0.00		7.5-0

Numbers in () are the parmeter setpoints that apply when the communication function is used. Ex. $\,$ OFF(0), ON(1)

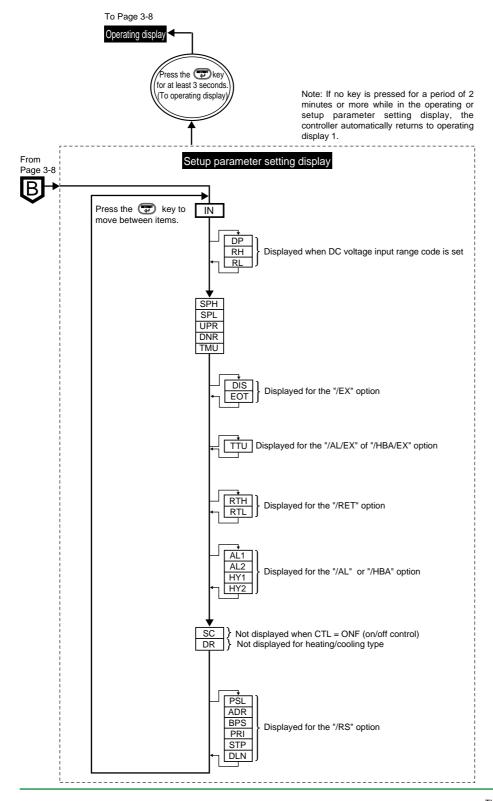
(2) Operating Parameters: Parameters changed rather frequently during operation.

	Code	Name	Setting range and unit	Default	User setting	Reference page
A1	R I	Alarm 1 setpoint	■ PV alarm Unit: °C/°F Setting range: minimum value to maximum value of measured input range (scale) ■ Deviation alarm Unit: °C/°F	Max. value of measured input range (scale) (PV alarm)		P.4-12
A2	<i>R2</i>	Alarm 2 setpoint	Setting range: —100 to 100% of measured input range (scale) span ■ Heater disconnection alarm Unit: A (ampere) Setting range: OFF(0), 1 to 80 (can be set for the alarm 1 setpoint only)	Min. value of measured input range (scale) (PV alarm)		P.4-16 P.4-17
НС	HΣ	Heater disconnection current measured value	HC is not a parameter to be set. The current value (0 to 80) of detector is displayed. Unit: A (ampere) Settings: When the display value is — — —, the heater curre	ent is not being measur	ed.	
CTL	[ŁL	Control mode	ONF(0): On/off control PID(1): PID control SLF(2): Dynamic auto tune control (cannot be set for heating/cooling control)	SLF(2) :for standard type; PID(1) : for heating/cooling type		P.4-5 P.6-1 P.6-6
АТ	ЯĿ	Auto-tuning	OFF(0): Stop auto-tuning ON(1): Start auto-tuning	OFF(0)		P.6-7
Р	P	Proportional band	$1^{\circ}\text{C}/^{\circ}\text{F}$ to the temperature that corresponds to 100% of the measured input range (scale) span	5% of measured input range (scale)		P.6-2
ı	<i>i</i>	Integral time	1 to 3600 seconds; OFF(0): no integral action	240 seconds		P.6-4
D	d	Derivative time	1 to 3600 seconds; OFF(0): no derivative action	60 seconds		P.6-5
MR	ñr	Manual reset	—100 to 100%	50.0% for standard type; 0.0% for heating/cooling type		P.6-4
COL	<u> LoL</u>	Cooling-side gain	0.01 to 9.99 times	1.00 times		P.5-8
DB	db	Dead band	■ PID control Unit: °C/°F Setting range: —(proportional band setting) to +(proportional band setting) ■ On/off control Unit: °C/°F Setting range: —50 to +50% of measured input range (scale)span	0% of measured input range (scale) span		P.5-8
HYS	HY5	Hysteresis for on/off control	$0^{\circ}\text{C}/^{\circ}\text{F}$ to the temperature that corresponds to 100% of the measured input range (scale) span	0.5% of measured input range (scale) span		P.6-1
СТ	[Ł	Control output cycle time	1 to 240 seconds	30 seconds		P.4-8 P.6-8
стс		Cooling-side control output cycle time	1 to 240 seconds	30 seconds		P.6-8
SP1	5P I	Target setpoint 1	Minimum value (SPL) to maximum value (SPH) of target setpoint range	SPL		P.4-10
SP2	5P2	Target setpoint 2	Unit: °C/°F There are also optional engineering units for voltage input.	SPL		P.5-4
FL	FL	PV input filter	OFF(0), 1 to 120 seconds	OFF(0)		P.5-2
BS	<i>b</i> 5	PV input bias	—100 to 100% of measured input range (scale) span	0% of measured input range (scale) span		P.5-1
LOC	Lo[Key lock	O: No key lock Prevents operations from being changed except for the changing of SP in the operating display Prevents all parameter changing operations Prevents all parameter changing operations But if LOC=1 or 2 is already set, the parameter value can not be changed by setting LOC=1 only. To change the parameter value, set LOC=0 at first (for disabling keylock), then set LOC=1 once again.	0		P.5-7



NOTE

Changing certain setup parameter may automatically initialize the operating parameters. Therefore, after you change the setup parameters, always check the operating parameter settings to find out if appropriate values have been set for them. If the operating parameters have been initialized, set them to their appropriate values.



3-11

(3) Setup Parameters: Parameters rarely changed in normal use after once having been set.

	Code	Name	Setting range and unit	Default	User setting	Reference page
IN	l n	Measured input type	1 to 23, 31 to 48 (See input range code list.) OFF(0): No input (If no input type is specified at the time of ordering, you must set the input	OFF(0), or the input range code specified with order		
DP	dР	Decimal point position of measured input	No decimal place (nnnn) (Displayed at voltage input) One decimal place (nnn.n) Three decimal places (nn.nn)	1		P.4-1 P.5-1
RH	гH	Maximum value of measured input scale	(RL + 1) to 9999 (Displayed at voltage input)	100.0		
RL	rL	Minimum value of measured input scale	—1999 to (RH —1) (Displayed at voltage input)	0.0		
SPH	5PH	Maximum value of target setpoint range	(SPL+1°C) to the maximum value of measured input range (scale) ; Unit: °C/°F	Maximum value of measured input range (scale)		DEO
SPL	5PL	Minimum value of target setpoint range	Minimum value of measured input (scale) range to (SPH −1°C) Unit: °C/°F	Minimum value of measured input range (scale)		- P.5-2
UPR	UPr	Setpoint ramp-up-rate	OFF(0) or a value from the minimum to the maximum value of t measured input range (scale)	OFF(0)		
DNR	dnr	Setpoint ramp-down- rate	Unit: °C/min or °C/hour, °F/min or °F/hour Set the ramp-rate time unit using parameter TMU.	OFF(0)		P.5-3
TMU	ŁňU	Setpoint ramp- rate time unit	0:°C or °F / hour 1:°C or °F / min	1		
DIS	dI 5	DI-function selection	External Contact Inputs	0		P.5-4 P.5-5 P.5-6
EOT	Eot	Output in STOP mode	In STOP mode by contact input, fixed control output can be generated. 0:0%, 1:100%	0		P.5-5
TTU	EEU	Timer time unit	0 : hour, minute 1 : minute, second	1		P.5-6
RTH	rŁH	Maximum value of retransmission output	Temperature input : Within measured input range Voltage input : RTL+1digit to max. value of measured	Maximum value of measured input range (scale)		P.5-4
RTL	rŁL	Minimum value of retransmission output	input scale (RH) Min. value of measured input scale (RL) to RTH-1digit However, RTL <rth< td=""><td>Minimum value of measured input range (scale)</td><td></td><td>7.5-4</td></rth<>	Minimum value of measured input range (scale)		7.5-4
AL1	RL I	Alarm 1 type	OFF(0) or a value from 1 to 22 (see the table of alarm function list), and either 23 or 24 (if the timer function [/EX option] is included), and 25 (if the heater disconnection function [/HBA option] is included)	1 (PV high limit alarm)		
AL2	AL Z	Alarm 2 type	OFF(0) or a value from 1 to 22 (see the table of alarm function list), and either 23 or 24 (if the timer function [/EX option]) is included)	2 (PV low limit alarm)		P.4-12 P.4-16
HY1	HY !	Alarm 1 hysteresis	0 to 100% of measured input range (scale) span	0.5% of measured input range (scale)		P.4-17 P.5-6
HY2	H75	Alarm 2 hysteresis	Unit: °C/°F	span		
sc	5[SUPER function	ON(1): Uses the SUPER function OFF(0): Does not use SUPER function Note: Not displayed when on/off control	OFF(0)		P.6-10
DR	dr	Direct/reverse action	Reverse action Direct action Note: Not displayed for heating/cooling type	0		P.4-6
PSL	P5L	Protocol selection	PC-link communication PC-link communication with sum check Ladder communication MODBUS in ASCII mode MODBUS in RTU mode	0		
ADR	Rdr	Controller address	1 to 99 However, the number of controllers that can be connected per host device is 31 at the maximum.	1		
BPS	<i>6P5</i>	Baud rate	2.4(0): 2400 bps 4.8(1): 4800 bps 9.6(2): 9600 bps	9.6(2)		P.5-9
PRI	Pr I	Parity	NON(0): Disabled EVN(1): Even parity ODD(2): Odd parity	EVN(1)		
STP	5EP	Stop bit	1 or 2 bits	1 bit		
DLN	dLn	Data length	7 or 8 bits • 8 bits when ladder, MODBUS (RTU) • 7 bits when MODBUS (ASCII)	8 bits		

4. BASIC OPERATIONS

This chapter describes an operating procedure using temperature controllers UT130 and UT150 of standard type with the alarm option as an example. Regarding the operating procedure for the heating/cooling type controller or for the controller with the options other than the alarm, confirm whether the some parameters appear or not referring to the parameter flowchart in "3. NAMES AND FUNCTIONS OF EACH PART / PARAMETERS." The operating procedure for UT152/UT155 is the same as that for UT150.

4.1 Setting Measured Input Type and Scale (Setting First)

The operating procedure to set first after purchasing a controller is described in this section. The procedure is for the parameter "IN" (measured input type) = OFF.

UT130 Measured	Input	Ranges
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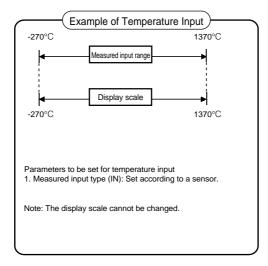
I have the second of the secon						
Input type		Range (°C) Range code (°C)		Range (°F)	Range code (°F)	
		Unspecified	OFF			
Thermocouple	К	—199 to 999°C	1	—199 to 999°F	31	
		0 to 600°C	2	32 to 999°F	32	
		0 to 400°C	3	32 to 750°F	33	
		—199 to 200°C	4	—199 to 400°F	34	
	J	—199 to 999°C	5	—199 to 999°F	35	
	T	—199 to 400°C	6	—199 to 750°F	36	
	E	—199 to 999°C	7	—199 to 999°F	37	
	L	—199 to 900°C	12	—199 to 999°F	42	
	U	—199 to 400°C	13	—199 to 750°F	43	
RTD	Pt100	—199 to 850°C	15	—199 to 999°F	45	
		0 to 400°C	16	32 to 750°F	46	
		—199 to 200°C	17	—199 to 400°F	47	
		—19.9 to 99.9°C	18	—199 to 999°F	48	
	IPt100	100 to 500°C	10			

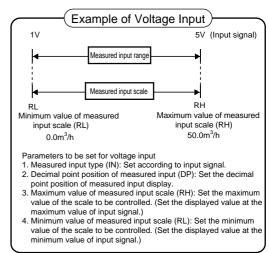
	nput type	Range (°C)	Range code (°C)	Range (°F)	Range code (°F)
		Unspecified	OFF		
	К	—270 to 1370°C	1	—300 to 2500°F	31
		0.0 to 600.0°C	2	32.0 to 999.9 °F	32
		0.0 to 400.0°C	3	32.0 to 750.0°F	33
		—199.9 to 200.0°C	4	—300 to 400°F	34
<u>o</u>	J	—199.9 to 999.9°C	5	—300 to 2100°F	35
Thermocouple	T	—199.9 to 400.0°C	6	—300 to 750°F	36
	E	—199.9 to 999.9°C	7	—300 to 1800°F	37
lξ	R	0 to 1700°C	8	32 to 3100°F	38
Ιĕ	S	0 to 1700°C	9	32 to 3100 °F	39
Ė	В	0 to 1800°C	10	32 to 3200 °F	40
	N	—200 to 1300°C	11	—300 to 2400°F	41
	L	—199.9 to 900.0°C	12	—300 to 1600°F	42
	U	—199.9 to 400.0°C	13	—300 to 750°F	43
	Platinel 2	0 to 1390°C	14	32 to 2500 °F	44
RTD	Pt100	—199.9 to 850.0°C	15	—199.9 to 999.9°F	45
		0.0 to 400.0°C	16	32.0 to 750.0°F	46
		—199.9 to 200.0°C	17	—300 to 400°F	47
		—19.9 to 99.9°C	18	—199.9 to 999.9°F	48
	JPt100	—199.9 to 500.0°C	19		
voltage	0 to 100mV	0.0 to 100.0	20		
	0 to 5V	0.000 to 5.000 User-scalable	21		
	1 to 5V	1 000 to 5 000	22		

UT150/UT152/UT155 Measured Input Ranges

The following operating procedure describes an example of setting "K-type thermocouple" (0.0 to 400.0°C) for the measured input type. For voltage input of UT150/UT152/UT155, the display scale can be set using the parameters "DP" (decimal point position of measured input), "RH" (maximum value of measured input scale) and "RL" (minimum value of measured input scale).

1 to 5V 1.000 to 5.000 0 to 10V 0.00 to 10.00

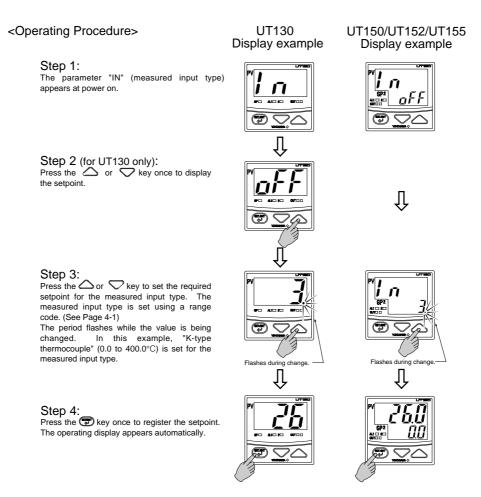




4-2

Setting a Type of Temperature Input

The following operating procedure describes an example of setting "K-type thermocouple" (0.0 to 400.0°C) for the measured input type.



Setting a Voltage Input Type and Display Scale (for UT150/UT152/UT155 only)

The following operating procedure describes an example of setting "1 to 5V DC voltage input signals" for the measured input type, and "0.0 to 500.0" for the display scale.

<Operating Procedure>

Step 1:

The parameter "IN" (measured input type) appears at power on.

Step 2:

Press the \triangle or ∇ key to set the required setpoint for the measured input type. The measured input type is set using a range code. (See Page 4-1)

The period flashes while the value is being changed. In this example, "1 to 5V DC" (setpoint: 22) is set for the measured input type.

Step 3:

Press the key once to register the setpoint. The operating display appears automatically.

The Step 4 onwards describes the procedure to set a display scale. The display scale is changed from "0.0 to 100.0 "(factory-set default) to "0.0 to 500.0".

Press the key for 3 seconds or more to display

the parameter "A1".
The parameter "A1" appears only for the controller with the "/AL" or" /HBA" option.

The parameter "CTL" appears for the controller

without the "/AL" or" /HBA" option.

Step 5:

Press the key several times to display the parameter "LOC."

MOTE

Set "-1" to enter the setup parameter setting display. But if "LOC" = 1 or 2 is already set, the parameter value can not be changed by setting "LOC" = -1 only. To change the parameter value, set "LOC" = 0 at first (for disabling key lock), then set "LOC" = -1 once again

Press the or key to display "-1."

UT150/UT152/UT155 Display example







Step 7:

Press the key once to display the parameter "IN" (measured input type). The value set in steps 1 to

Step 8:

Press the key once. In this example, the parameter "DP" (decimal point position) is set to "1" (one decimal place).

When DP = 1 (one decimal place), When DP = 2 (two decimal places), When DP = 3 (three decimal places), ______

Step 9:

Press the key once to display the parameter "RH" (maximum value of measured input scale). The factory-set default "100.0" appears on SP display.

Step 10: Press the \bigcirc or \bigcirc key to display the setpoint

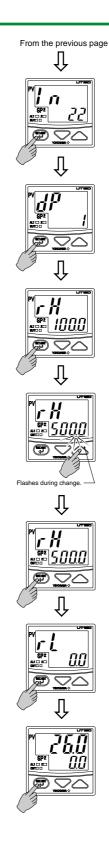
The period flashes while the value is being

Step 11:
Press the key once to register the setpoint. The period is lit when the registration is completed.

Step 12:

Press the key once to display the parameter "RL" (minimum value of measured input scale). The factory-set default "0.0" is displayed on SP display. In this example, "0.0" is set for the minimum value of measured input scale.

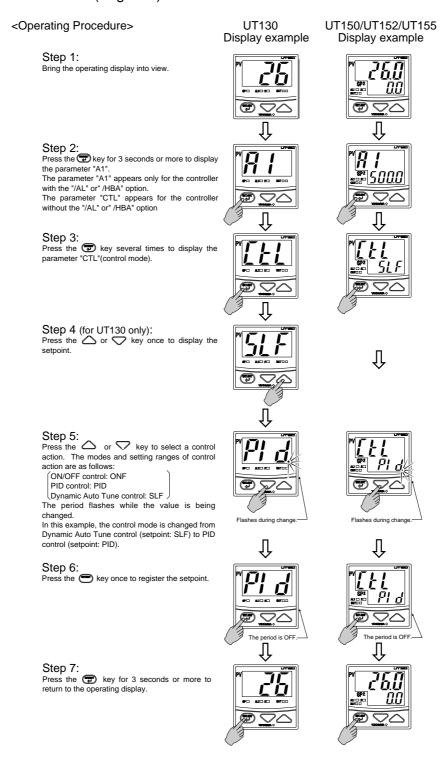
Step 13: Press the key for 3 seconds or more to return to the operating display.



4.2 Setting Control Action

4.2.1 Selecting a Control Mode (Dynamic Auto Tune Control / PID Control / ON-OFF Control)

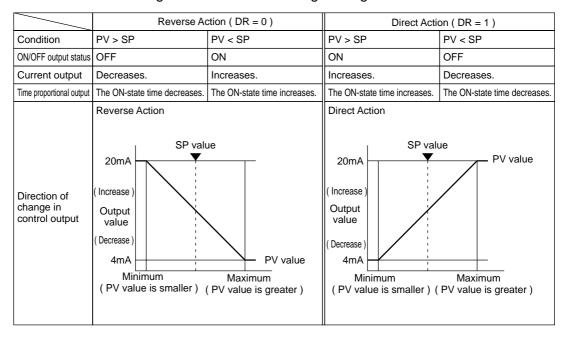
The following operating procedure describes an example of changing Dynamic Auto Tune control to PID control. When PID control is selected, PID should be obtained by Auto tuning or PID should be set manually. Refer to "6. DESCRIPTION OF EACH FUNCTION" (Page 6-1) for the function of control mode.

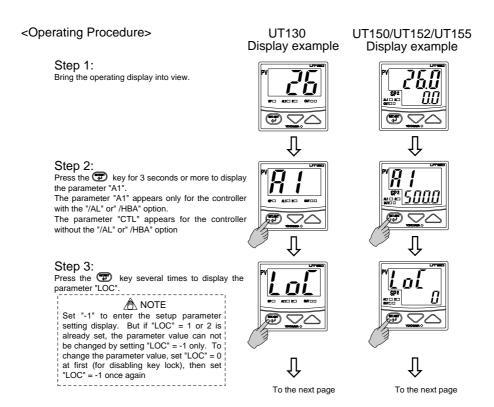


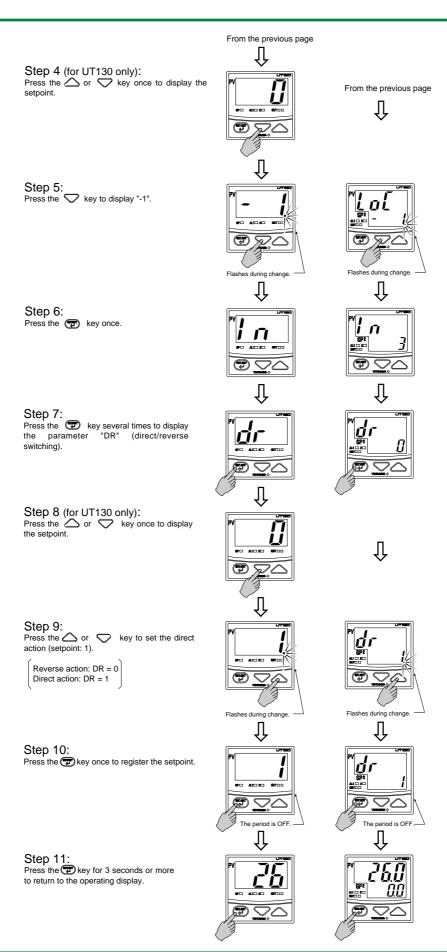
4.2.2 Switching Direct / Reverse Action

Direct and reverse action define the direction in which output increase or decrease, according to whether deviation of target setpoint (SP) and measured input vb0}e (PV) is positive or negative. Reverse action is used for temperature control in a heating control, and direct action for cooling control. Factory set to Reverse action.

Direct/reverse switching is unavailable in heating/cooling control.



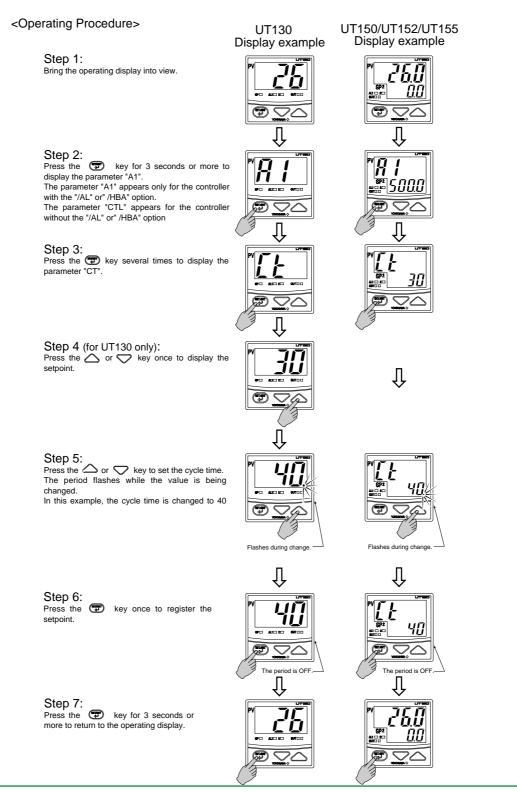




4.2.3 Setting Cycle Time (Control Output Renewal Period)

The cycle time can be set when the control output type is time-proportional relay output or voltage pulse output. The parameter to set a cycle time does not appear in ON/OFF control (CTL = ONF) or in Dynamic Auto Tune control (CTL = SLF). Refer to "6.6.2 Cycle Time" on Page 6-8 for the functional description of cycle time.

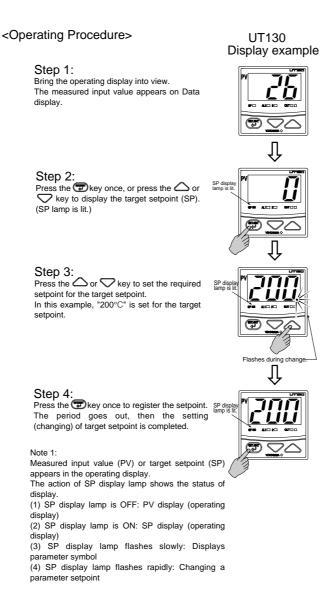
The following operating procedure describes an example of changing the cycle time form 30 seconds to 40 seconds.



4.3 Setting Target Setpoint (SP)

4.3.1 Setting Target Setpoint (SP) of UT130

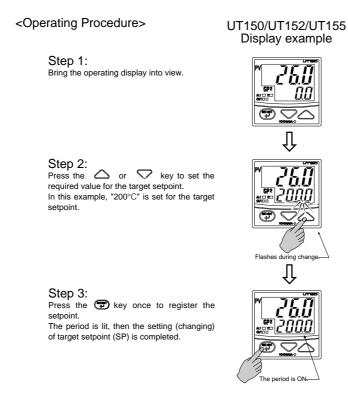
The following operating procedure describes an example of setting "200°C" for the target setpoint.



4.3.2 Setting Target Setpoint (SP) of UT150/UT152/UT155

■ Setting / Changing SP in Operating Display (for Target Setpoint 1: SP1 only)

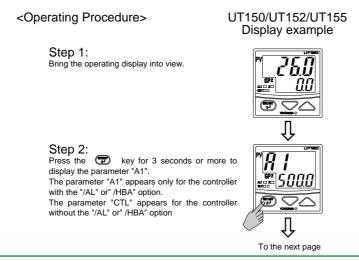
The following operating procedure describes an example of setting "200°C" for the target setpoint 1.



■ Setting / Changing SP in Operating Parameter Setting Display (for SP1 and SP2)

SP can be set or changed in the operating parameter setting display only for the controller with the "/EX" option. And the SP is switched using the external contact input. Refer to "5.6 Using Two Target Setpoints" (Page 5-4).

The following operating procedure describes an example of setting "200.0°C" for the target setpoint 1(SP1) and "300.0°C" for the target setpoint 2 (SP2).



From the previous page Û Step 3: Press the press the key several times to display the parameter "SP 1" (target setpoint 1). The parameter "SP 1" appears only for the controller with the "/EX" option. Step 4 Press the or key to set the target setpoint 1 (SP 1). *** 2000 The period flashes while the value is being changed. In this example, "200.0°C" is set for the target setpoint 1. during cha Step 5: Press the 🕝 key once to register the setpoint. Step 6: Press the press the key several times to display the parameter "SP 2" (target setpoint 2). The parameter "SP 2" appears only for the controller with the "/EX" option. The period flashes while the value is being changed. In this example, "300.0°C" is set for the target setpoint 2. Step 8: Press the key once to register the setpoint. Step 9: Press the key for 3 seconds or

more to return to the operating display.

4.4 Setting Alarms

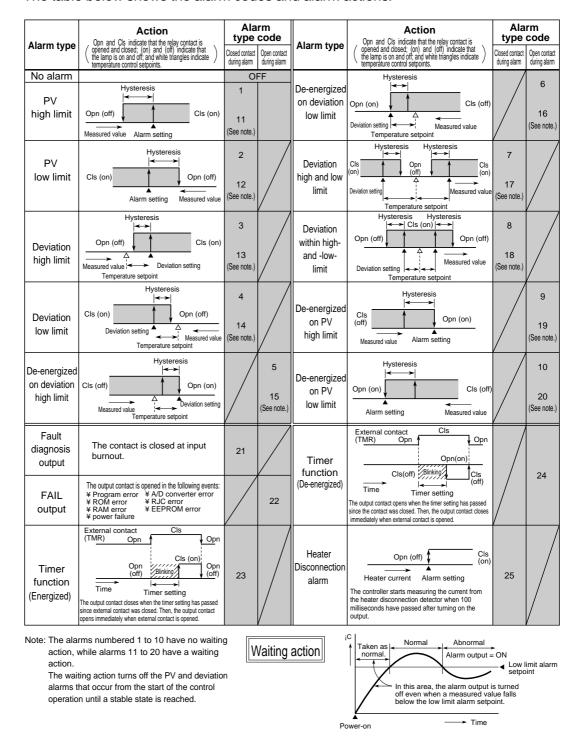
Alarm function is available only for the controller with "/AL" or "HBA" option.

Heater disconnection function is available only for the controller with "/HBA" option.

Timer function is available only for the controller with "/AL/EX" or "/HBA/EX" option.

4.4.1 Setting Alarm Type and Hysteresis

The table below shows the alarm codes and alarm actions.

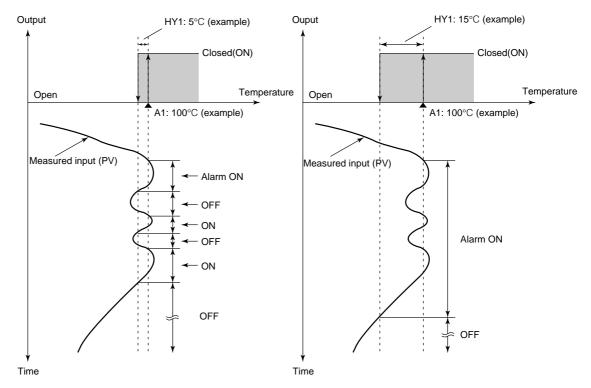


The alarm hysteresis (ON/OFF band) is effective when used as the figure below.

The alarm hysteresis can be set between 0.0 to 100% of measured input range. The setting is a temperature setting.



Alarm 1 type (AL1): PV high limit alarm Alarm 1 hysteresis (HY1): 5°C A1 (Alarm 1 setpoint): 100°C Alarm 1 type (AL1): PV high limit alarm Alarm 1 hysteresis (HY1): 15°C A1 (Alarm 1 setpoint): 100°C

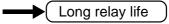


"Open" and "Closed" above show the status of relay output of external contact.

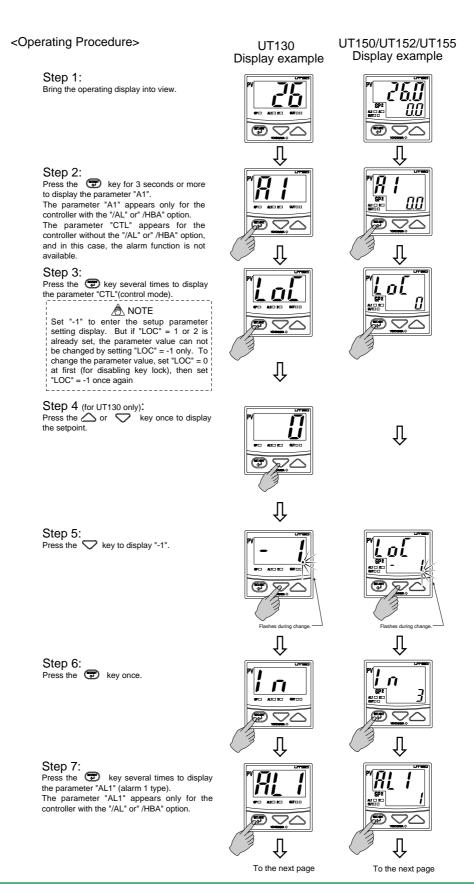
When HY1 = 5° C, the alarm turns on and off too often, and the relay chattering occurs.

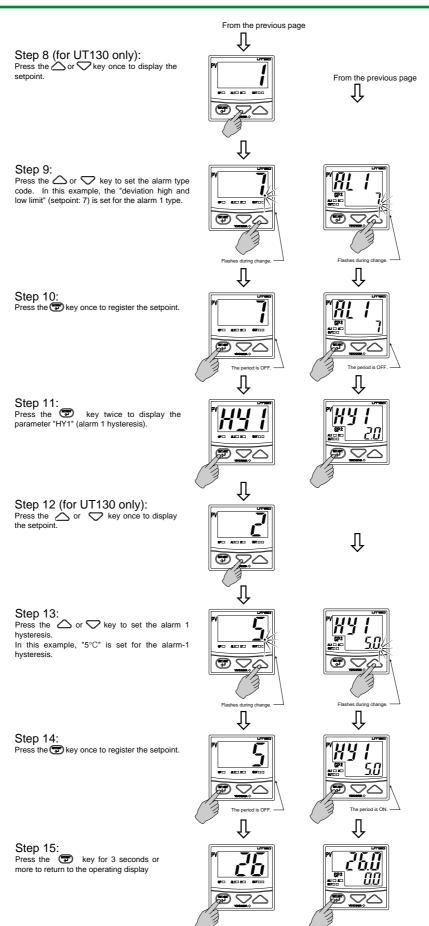


When HY1 = 15° C, the alarm does not turn on and off too often, and the relay chattering does not occur.



The following operating procedure describes an example of setting the "deviation high and low limit" (setpoint: 7) for the alarm-1 type, and "5°C" for the alarm 1 hysteresis.





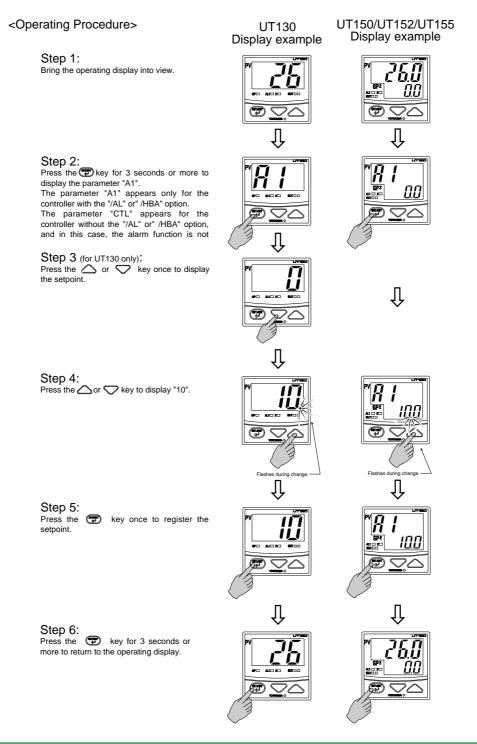
4.4.2 Setting Alarm Setpoint



NOTE

Be sure to confirm the alarm type before setting the alarm setpoint. If the alarm type is changed after setting the alarm setpoint, the alarm setpoint is initialized.

The following operating procedure describes an example of setting "10°C" for the alarm 1 setpoint.



4.4.3 Heater Disconnection Alarm Function

The heater disconnection alarm is the function to detect the deterioration or disconnection of heater by the current value at ON output in ON/OFF control or in time-proportional control.

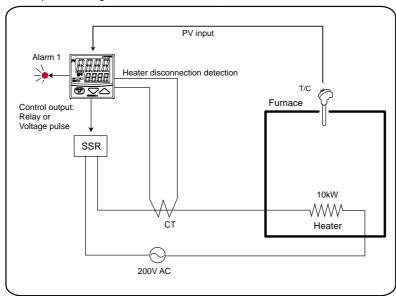
This function is available for the controller with the "/HBA" option.

Heater disconnection alarm can be used for the alarm 1 only. The heater disconnection alarm is output using the alarm

The heater current sensor used here is the "CTL-6-S-H" or "CTL-12-S36-8" sensor of U.R.D., Ltd.

This sensor is to be purchased by the users themselves.

< Example 1> Using one heater of 200V AC, 10kW



Heater current in normal state $\frac{10000W}{200V} = 50A$

Detecting current error = -5% - 1digit

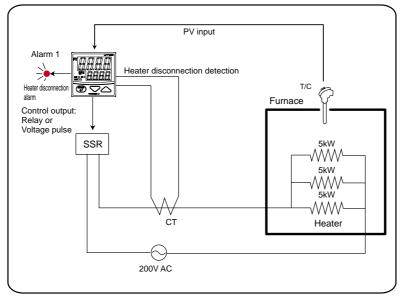
The setpoint for heater detecting current is —10% of the current value at normal state

Alarm 1 type (AL1) = 25 Alarm 1 setpoint (A1) = 45A

The controller outputs the heater disconnection alarm when the heater current is 45A or less.

The current value at present can be read in the parameter "HC" (heater current measured value)

< Example 2 > Using three heaters of 200V AC, 5kW



Heater current in normal state:

 $\frac{5000W}{200V}$ x 3 = 75A

Heater current in one wire disconnection:

 $\frac{5000W}{200V}$ x 2 = 50A

Detecting current error = -5% - 1digit

The setpoint for heater detecting current is —10% of the current value at normal state

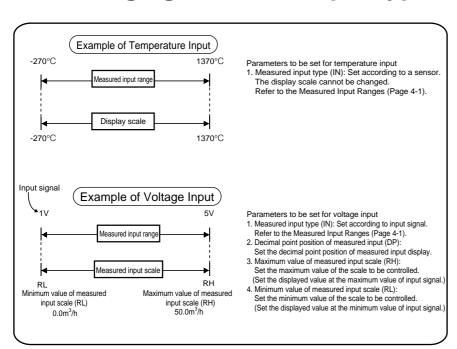
Alarm 1 type (AL1) = 25 Alarm 1 setpoint (A1) = 60A

The controller outputs the heater disconnection alarm when the heater current is 45A or less.

The current value at present can be read in the parameter "HC" (heater current measured value)

5. APPLIED OPERATIONS

5.1 Changing Measured Input Type and Scale

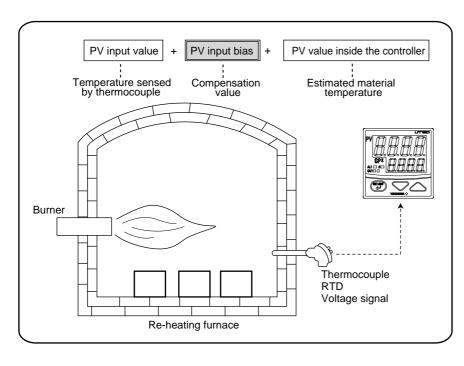


- The measured input range is decided by setting the range code for measured input.
- For voltage input, any display scale for measured input can be set.
- The voltage input is available for UT150/UT152/UT155.

Parameter Range

IN	OFF, 1 to 23
DP	Display for voltage input (IN= 20 to 23) 0: No decimal place 1: One decimal place 2: Two decimal places 3: Three decimal places
RH RL	Display for voltage input (IN= 20 to 23) -1999 to 9999 However,RL <rh< td=""></rh<>

5.2 Correcting Measured Input Value

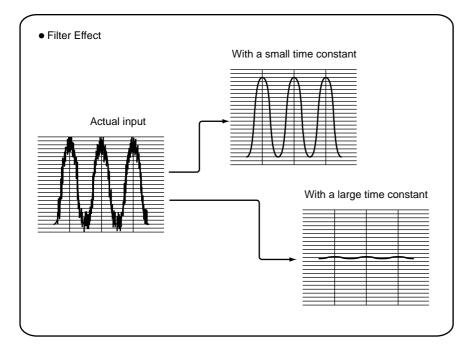


- This function allows bias to be summed with input to develop a PV (measured) value for display and control use inside the controller.
- An application example for this function would be measure furnace atmospheric temperature or furnace wall temperature, and add a correction for use as substitute for the heated material temperature.
- This function can also be used for fine adjustment to compensate for small interinstrument differences in measurement reading that can occur even if all are within the specified instrument accuracy.
- Bias is set using the operating parameter "BS" (PV input bias).

Parameter Range

	Temperature corresponding	
BS	to -100 to 100% of PV input	
	range (scale) span	

5.3 Reducing Input Variations

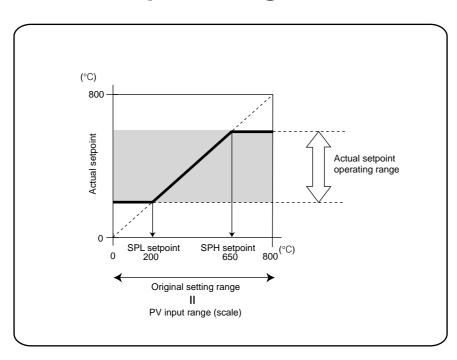


- If input noise or variations cause the low-order display digits to fluctuate so that the displayed value is difficult to read, filtering of inputs will reduce the variations.
- Filtering is used by setting a 1st-order lag time constant; this is set using the parameter "FL" (PV input filter).

Parameter Range

FL OFF, 1 to120 seconds

5.4 Setting Maximum and Minimum Values of Target Setpoint Range

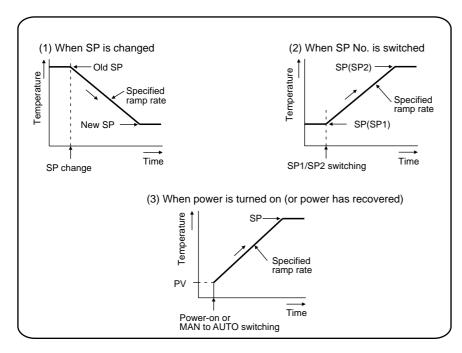


- To stabilize operation or protect equipment, it may be necessary not to allow use of the full setpoint operating range, but rather to some narrower range.
- In such cases, the minimum value and maximum value of target setpoint can be set to restrict the setpoint to the range between those values.
- The minimum value and maximum value of target setpoint are set using the parameters "SPL" (minimum value of target setpoint) and "SPH" (maximum value of target setpoint).

Parameter Range

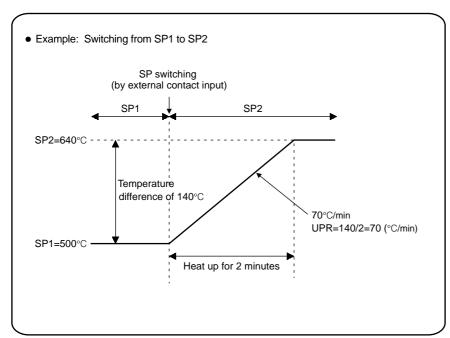
SPL	Minimum value of PV input range (scale) to (SPH — 1°C)	
SPH	(SPL + 1°C) to Maximum value of PV input range (scale)	

5.5 Setting Target Sepoint Ramp Rate (Rate-of-Change)



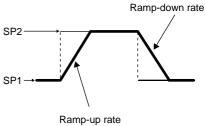
- This function is available for UT150/UT152/UT155.
- To prevent the target setpoint (SP) from changing suddenly or to change it at a constant rate, set the ramp-up rate (UPR) and ramp-down-rate (DNR) for SP. Set the temperature for heat up or heat down per hour or minute for ramp
- The ramp-up rate and ramp-down rate are set using the setup parameters "DNR"and "UPR". Parameter Range

DNR UPR	value to maximum value of measured input range (scale) (°C or °F)
TMU	0: °C or °F / hour 1: °C or °F/ minute

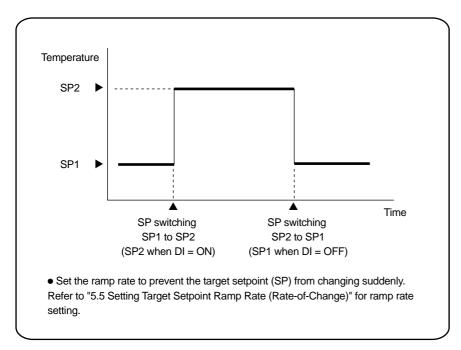


• When switching from SP1 to SP2, SP changes suddenly without setting a ramp

This function is used for changing SP at a constant rate.



5.6 Using Two Target Setpoints



- This function is available for UT150/UT152/UT155 with the "/EX" option.
- SP is switched using the external contact inputs. The external contact input terminals for SP switching are different according to the parameter "DIS" setting.

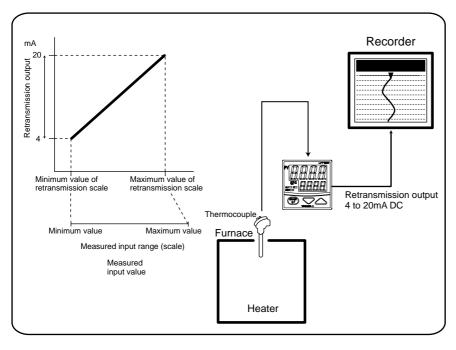
Refer to "8.3 Wiring" on Page 8-7.

• Set "0" or "2" for the setup parameter "DIS" to switch SP.

Parameter Range

SP1 SP2	Minimum value (SPL) to maximum value (SPH) of target setpoint range (°C or °F)
DIS	0:Timer starts/stops, SP switching 1:Timer starts/stops, RUN/STOP switching 2: RUN/STOP switching. SP switching

5.7 Retransmission of Measured Input Value in Current Signal

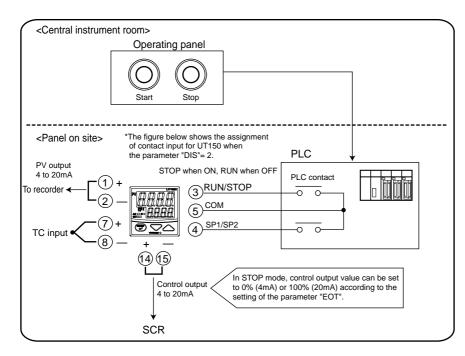


- This function is available for UT150/UT152/UT155 with the "/RET" option.
- The retransmission output range is factory-set to between the maximum and minimum values of measured input range (scale).
- The retransmission output range is changeable. The retransmission output range is set using the parameters "RTL" (minimum value of retransmission output) and "RTH" (maximum value of retransmission output).

Parameter Range

	Within measured input range
RTL RTH	<voltage input=""> RTL + 1digit to maximum value of measured input scale (RH) Minimum value of measured input scale (RL) to RTH —1digi however, RTL < RTH</voltage>

5.8 Switching RUN/STOP



- This function is available for UT150/UT152/UT155 with the "/EX" option.
- RUN/STOP is switched using the external contact inputs.
 The external contact input terminals for RUN/STOP switching are different according to the parameter "DIS" setting.
 Refer to the table below.
- Set "1" or "2" for the setup parameter "DIS" to switch RUN/STOP.
- The symbol " STP " and PV value appears alternately on PV display in STOP mode.

Parameter Range

DIS	0:Timer starts/stops, SP switching 1:Timer starts/stops, RUN/STOPswitching 2: RUN/STOP switching, SP switching
EOT	0: 0% (4mA DC) 1: 100% (20mA DC)

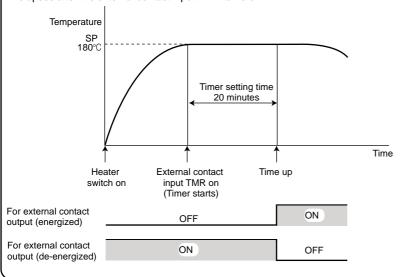
• External contact input terminals for RUN/STOP switching (for UT150/UT152/UT155 only)

	Parameter "DIS" setpoint	Operating status	Terminal number
UT150	Setup parameter DIS = 1	STOP	(4) (5) ON
		RUN	(4) OFF
	Setup parameter DIS = 2	STOP	3 5 ON
		RUN	③ OFF
UT152/ UT155	Setup parameter DIS = 1	STOP	22 23 ON
		RUN	21 OFF
	Setup parameter DIS = 2	STOP	22 23 ON
		RUN	②1 OFF

• The external contact input terminals for RUN/STOP switching are different according to the setup parameter "DIS" setting.

5.9 Using Timer Function (Turning on External Contact Outputs after the Set Time Elapses)

• The timer function turns on or off external contact outputs when the timer setting time elapses after the external contact input TMR turns on.



- This function is available for UT150/UT152/UT155 with the "/EX/AL" or "/EX/HBA" option.
- Set "0" or "1" for the setup parameter "DIS" to use Timer.

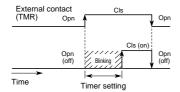
The external contact terminals for startingTimer are different according to the parameter "DIS" setting. Refer to "8.3 Wiring".

- "Energized" or "De-energized" is set using the setup parameters "AL1" and "AL2".
- Time unit is set using the setup parameter "TTU".
- Timer time is set using the operating parameters "T1" and "T2".
- The parameter "T1" is for "AL1", and "T2" is for "AL2".

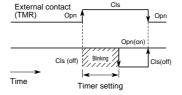
Parameter Range

T1 T2	Timer time 0.00 to 99.59(hour and minute or minute and second) Timer time unit is set by "TTU"
AL1 AL2	Timer function (energized): 23 Timer function (de-energized): 24
TTU	Timer time unit 0: hour and minute 1: minute and second

• Timer function (Energized)



Timer function (De-energized)



The output contact closes when the timer setting has passed since external contact was closed. Then, the output contact opens immediately when the external contact is opened.

The output contact opens when the timer setting has passed since external contact was closed. Then, the output contact closes immediately when the external contact is opened.

DIS

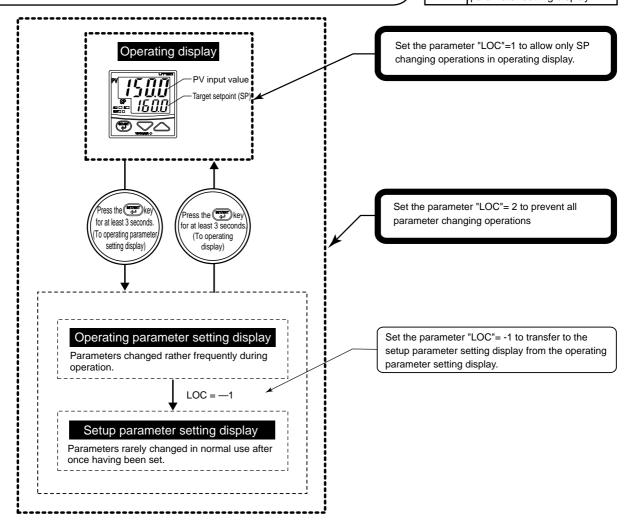
0: Timer Starts / Stops, SP switching
1: Timer Starts / Stops,
RUN / STOP switching
2: RUN / STOP switching, SP switching

5.10 Setting Key Lock

- The Lock can be set for the parameters of UT100 series controllers.
 Setting key lock prevents the parameters from being changed intentionally by outsider.
- 0: No key lock
- 1: Prevents the parameters from being changed except for the SP in the operating display.
- 2: Prevents all parameters from being changed.
- -1: Set "-1" to enter the setup parameter setting display. But if "LOC" = 1 or 2 is already set, the parameter value can not be changed by setting "LOC" = -1 only. To change the parameter value, set "LOC" = 0 at first (for disabling key lock), then set "LOC" = -1 once again.

Parameter Range

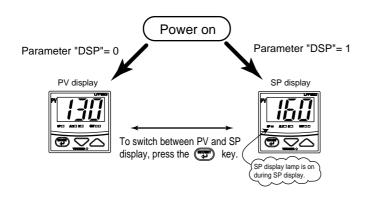
LOC 0: No key lock
1, 2: Set key lock (refer to the left)
-1: Transfer to the setup
parameter setting display



5.11 Selecting Priority of PV/SP Display at Power on (for UT130 Only)

The priority of PV or SP display on operating display can be selected because UT130 has only one data display.

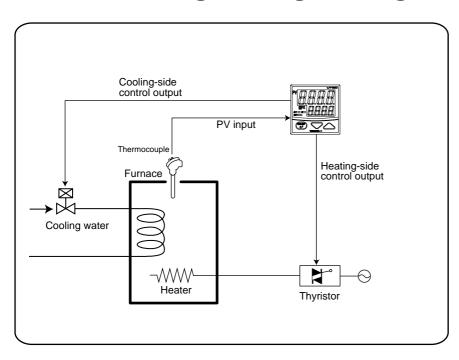
The data (PV or SP) selected in the parameter "DSP" is displayed at power on or when returning to the operating display from the parameter setting display by pressing the key for at least 3 seconds.



Parameter Range

DSP 0: Measured value (PV) display
1: Target setpoint (SP) display

5.12 Performing Heating/Cooling Control



 In heating/cooling control, the controller outputs the result of PID computation after splitting it into heating-purpose and cooling-purpose signals.

It is used for the control of heater with heater and cooler.

100%

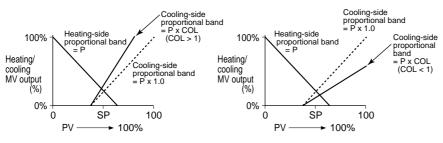
• Dead band and hysteresis

2. When both the heating and cooling sides are 1. When the dead band in heating/cooling sides is positive (P control) under on/off control. 100% ON Dead band(+) Dead band(-Heating/cooling MV output Heating/cooling MV output Cooling 0% 0 SP 100 0 SP 100

► 100%

In a positive dead band, there are neither heating-side nor cooling-side outputs.

In a negative dead band, there are both heating-side and cooling-side outputs, which overlap each other.



Parameter Range

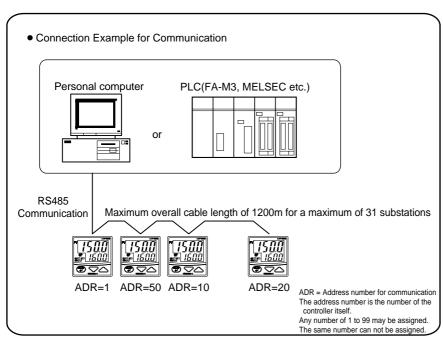
DB	<pre>< PID control ></pre>
	<on control="" off=""> —50% to +50% of measured input range (scale) span</on>
HYS	0°C /°F to the temperature corresponding to 100% of measured input range (scale) span
COL	0.01 to 9.99 times

Heating-side proportional band =
 Parameter "P" (proportional band)

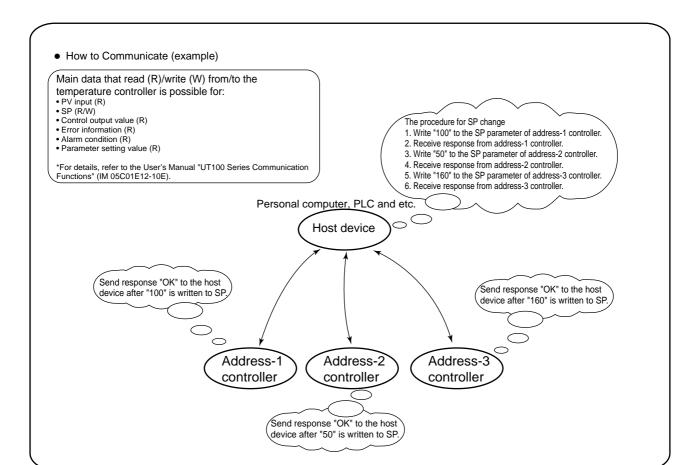
Cooling-side proportional band = Parameter "P" x Parameter "COL"

• For example, if you set COL=2.0 and the heating-side output is 10% at a certain deviation (SP — PV), then the cooling-side output will be 20% when the cooling-side also reaches that deviation (reverse).

5.13 Communicating with PC or PLC



- This function is available for the controller with the "/RS" option.
- For communicating with a PC, RS232C/RS485 converter (model ML1) is necessary.
- Communication with a PLC (FA-M3) manufactured by Yokogawa is through ladder communication module (F3RZ91-0N) or personal computer link module (F3LC11-2N). The communication protocol is ladder or personal computer link.
- Communication with a PLC (MELSEC) manufactured by Mitsubishi is through computer link unit (A1SJ71C24-R24 or A1SJ71C24-R4). The communication protocol is non-procedural ladder.



• Communication Protocol

Communication Hardware	2-wire RS-485 communication system
Terminal	Terminal numbers: 3 to 5 (UT130/UT150), 26 to 28 (UT152/UT155)
Communication Protocol Specifications	PC link communication without sum check PC link communication with sum check Ladder communication MODBUS communication (ASCII mode) MODBUS communication (RTU mode)
Maximum Baud Rate	9600 bps

• RS-485 Communication Interface

Item	Specifications
Standard	EIA RS-485 compliant
Maximum number of devices to be connected	31
Communication System	2-wire, half duplex
Synchronization	Start-stop synchronization
Communication protocol	Non-procedural
Maximum communication distance	1200 m
Baud rate	2400, 4800, 9600

• Parameters to be Set for Communication Functions

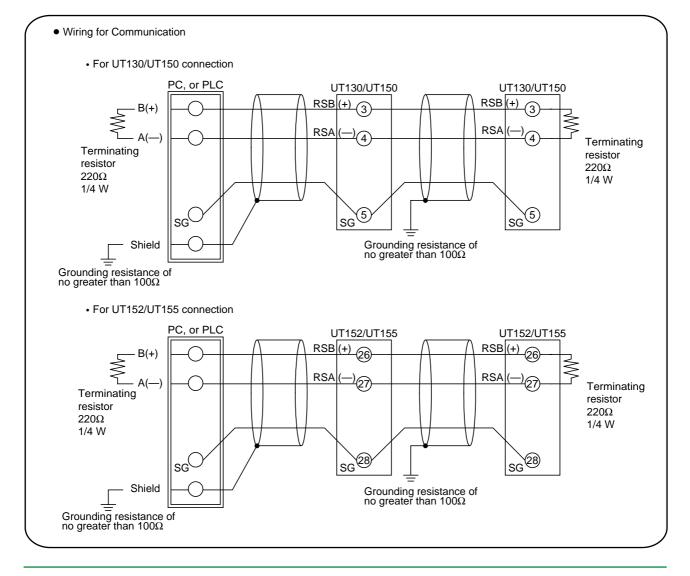
Parameter Name	Symbol	Setting Range		Default
Protocol selection	PSL	PC link communication	0: without sum check 1: with sum check	0
		Ladder communication	2: Ladder	
		MODBUS communication	3: ASCII mode 4: RTU mode	
Address	ADR	1 to	99	1
Baud rate	BPS	0: 2400, 1: 4	1800, 2: 9600	2: 9600
Parity	PRI	0: NON 1: EVE 2: ODE	N	1: EVN
Stop bit	STP		1, 2	1
Data length	DLN	7,	8 (*1)	8

• The details of UT100 Series communication functions need to be the same as those of the communication functions of the host devices to be connected.

*1: When "2: Ladder" is selected, it is fixed to "8".

When "3: ASCII mode" is selected for MODBUS communication in protocol selection, the data length is fixed to "7".

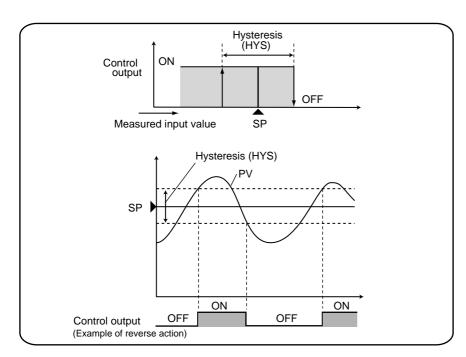
When "4: RTU mode" is selected, it is fixed to "8".



6. DESCRIPTION OF EACH FUNCTION

6.1 ON/OFF Control

6.1.1 ON/OFF Control and Hysteresis

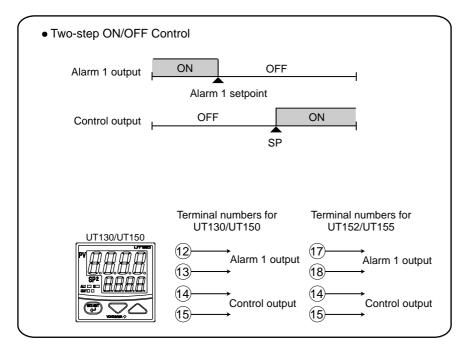


IN ON/OFF control, since the only two possible output states are ON and OFF, the control output cycles are as shown in the accompanying figure. ON/OFF becomes quite narrow, so that if relay output is used, chattering occurs. In this case, the hysteresis should be set wider to prevent relay chattering and for the service life of the relay.

Parameter Range

CTL	ONF: ON/OFF control PID: PID control SLF: Dynamic Auto Tune control	
HYS	0 ¡C/¡F to the temperature corresponding to 100% of the measured input range (scale) span	

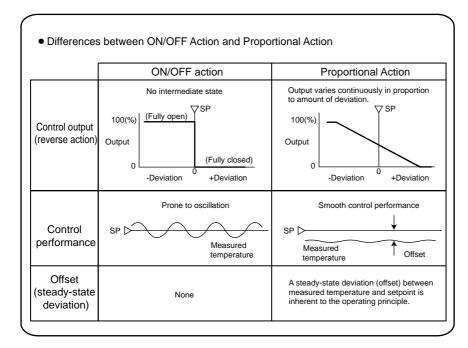
6.1.2 ON/OFF Control Application Example



- An example on the left figure shows two-step ON/OFF control using ON/OFF control output and alarm output.
- Alarm 1 is set to PV low limit alarm.

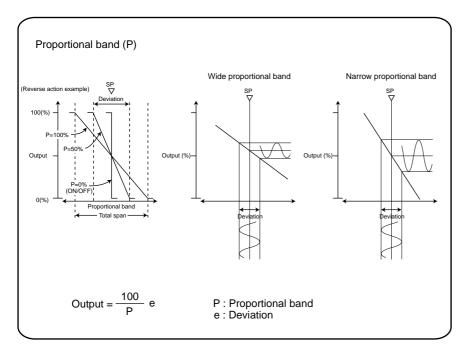
6.2 Proportional (P) Action

6.2.1 Differences between ON/OFF Action and Proportional Action



- The proportional band is the parameter that determines the effectiveness of proportional action.
- The figure on the left shows a proportional action by comparison to the simplest control action: ON/OFF action.

6.2.2 Proportional Band (P) Details

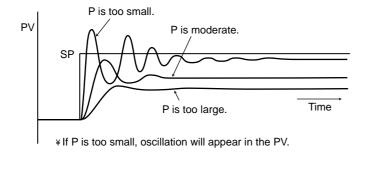


- "Proportional band" is defined as the amount of change* in input (or deviation), as a percent of span, required to cause the control output to change from 0% to 100%.
- Because a narrower proportional band gives greater output change for any given deviation, it therefore also makes the control performance more susceptible to oscillation. At the same time, a narrower proportional band reduces the offset.
- Reducing the proportional band to its smallest limit (proportional band = 0%) results in ON/OFF control. UT100 series controllers select ON/OFF control using the parameter "CTL".
- Note that the unit of proportional band is the percent of PV input span, or actual temperature in engineering units. For UT100 series, set the actual temperature.

6.2.3 Tuning the Proportional Band

To fine-tune a proportional band obtained using auto-tuning, or to manually tune the proportional band:

- Work from larger to smaller numbers (wider to narrower)
- If cycling appears, that means that the proportional band is too
- Proportional band tuning cannot cancel an offset.



• The proportional band (P) is adjusted as shown in the figure on the left.

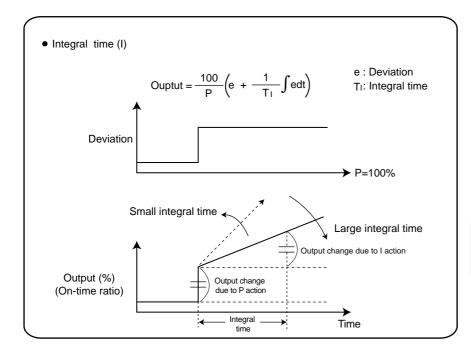
Parameter Range

Р

1°C/°F to the temperature corresponding to 100% of measured input range (scale) span

6.3 Integral (I) Action

6.3.1 Integral Time (I)



- "Integral action" ("I" action) is a function that will automatically diminish the offset (steady-state deviation) that is inherently unavoidable with proportional action alone. The parameter that specifies how the integral action will operate is the integral time (I). The integral action continuously increases or decreases the output in proportion to the time integral of the deviation (the product of the deviation and the time that the deviation continues).
- Integral action is normally used together with proportional action as proportional-plusintegral action (PI action).

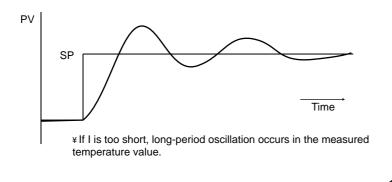
Parameter Range

	UT130: 1 to 999 sec or OFF
1	UT150/UT152/UT155:
	1 to 3600 sec or OFF

- The integral time (I) is defined as the time required to develop, when a stepwise change in deviation is imposed, an output change due to integral action that is exactly equal to the change due to proportional action. The longer the integral time set, the slower the change in output; the smaller the time, the faster the output changes.
- If integral action is not to be used, the integral parameter is set to OFF.

6.3.2 Tuning the Integral Time

- To manually adjust integral time
- The main goal is to reduce the offset
- Adjust from longer time to shorter time
- If you see an oscillation at a longer period than that seen when proportional band is too narrow, then you have made the integral time too short.



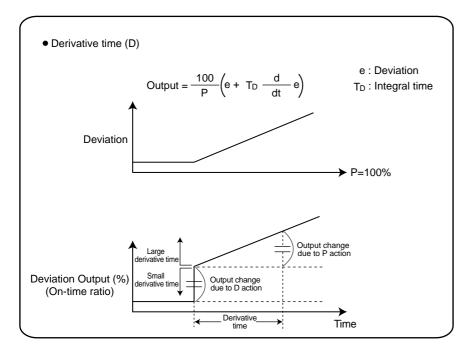
- When I action is OFF, change the operating parameter "MR" (Manual reset) to remove the offset.
- Shortening the integral time, like narrowing the proportional band, will cause the measured temperature to begin oscillating. However, oscillation due to integral action is characterized by a longer period than that of oscillation due to narrow proportional band.

Parameter Range

MR	UT130:	
	-19.9 to 99.9%	
	UT130 (heating/cooling type) and UT150/UT152/UT155:	
	and UT150/UT152/UT155:	
	-100 to 100%	

6.4 Derivative (D) Action

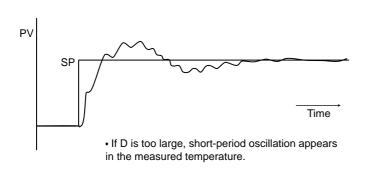
6.4.1 Derivative Time (D)



- If the control object has a large time constant or dead time the corrective action will be too slow with proportional action or proportional-plus-integral action alone, causing overshoot. However, even just sensing whether the deviation is on an increasing or a decreasing trend and adding some early corrective action can improve the controllability. Thus the derivative action ("D" action) is action that changes the output in proportion to the deviation derivative value (rate-of-change). The parameter that sets how the derivative action will operate is the derivative time (D).
- The derivative time (D) is defined as the time required with "PD" action to develop, when a constant-slope-change in deviation is imposed, an output change due to derivative action that is exactly equal to the change due to proportional action.

6.4.2 Tuning the Derivative Time

- To manually adjust the derivative time parameter
- Adjust from shorter time to longer time.
- If you see a short-period oscillation, the time is too long.



- The longer the derivative time is set, the stronger the corrective action is, and the more likely the output will become oscillatory. Oscillations due to derivative action are characterized by a short period.
- When the derivative time (D) is set to OFF, the derivative action does not function. D=OFF should always be used when controlling fast-responding inputs such as pressure and flow, or inputs characterized by rapid fluctuation, such as optical sensors.

Parameter Range

D UT130:
1 to 999 sec or OFF
UT150/UT152/UT155:
1 to 3600 sec or OFF

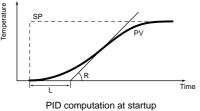
6.5 Dynamic Auto Tune Control and PID Control

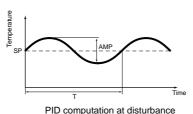
6.5.1 Dynamic Auto Tune Control

"Dynamic Auto Tune Control" is a sort of self-tuning

Dynamic Auto Tune Control is effective in the following cases:

(1) When the output travels up to 100% or down to 0% and remains there at power on; (2) When the output travels up to 100% or down to 0% and remains there after changing a setpoint; (3) When the process begins oscillating by disturbance and the like





• What is Dynamic Auto Tue Control? Dynamic auto tune control is one of the features offered by the temperature controller. When the controller is tuned on or the measured input (PV) starts "hunting", this mode of control monitors the behavior of the PV and/or OUT (control output value) to automatically determine the optimum PID constants. This means that the PID constants may be changed automatically. If this is not desirable for your system, operate the controller in the normal "PID control". If you want to automatically determine the PID constants at the initial startup of the controller, first define the target setpoint (SP) and then turn the controller off once and then back on again. Do not use Dynamic auto tune control for a system where there is interference or continual disturbances.

Parameter Range

ONF: ON/OFF control
PID: PID control
SLE: Dynamic auto tune cor

Precautions

To use Dynamic auto tune control,

- (1) be sure to turn on the final control element, such as a heater, before starting the control, and
- (2) make sure that the controlled loop is a closed loop.

If you do not follow these precautions, improper PID constants may be written into the controller. If this occurs, carry out the following:

- Set PID for the parameter "CTL".
- Set the factory-set defaults [P = (upper range(scale)-limit lower range (scale)-limit) x 5%; I = 240sec; and D = 60sec] for the PID constants.
- Set SLF for the parameter "CTL".

If the control still doesn t work properly, stop using the Dynamic auto tune control function. Change the parameter "CTL" setting to PID and execute auto-tuning to obtain the PID constants.

6.5.2 Manually Tuning PID Constants

• Procedure for manually tuning PID constants

Output =
$$\frac{\text{Temperature input span}}{P} \left(e + \frac{1}{T_{I}} \int edt + T_{D} \cdot \frac{d}{dt} PV \right)$$

e: Deviation

P : Proportional band PV: Measured input value

Ti: Integral time

Tp: Derivative time

(1) In principle, auto tuning must be used.

(2) Turn PID parameters in the order of P, I, D. Adjust a numeric slowly by observing the result, and keep notes of what the progress is.

(3) Gradually reduce P from a larger value. When the measured value begins to oscillate, stop tuning and increase the value somewhat.

(4) Also gradually reduce I from a larger value. When the measured value begins to oscillate (with long period), stop tuning and increase the value somewhat.

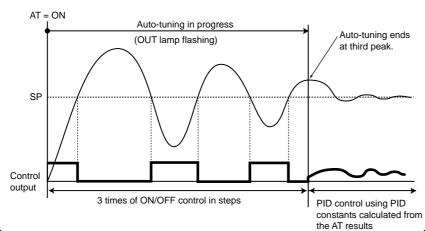
(5) Gradually increase D from a smaller value. When the measured value begins to oscillate (with short period), stop tuning and lower the value slightly.

• PID based output can be obtained by the equation on the left. Take this into account when tuning PID parameters. Manual PID tuning procedure is as described in (2) to (5) on the left.

6.5.3 PID Auto-Tuning

- Auto-tuning (AT)
- · Automatic PID constant setting function
- · Uses a limit cycle method

The auto-tuning temporarily executes ON/OFF control, calculates appropriate PID constants from response data obtained, and sets these constants.



- The temperature controller automatically measures the process characteristics and sets PID constants, which are control parameters, to optimum values for the setpoint.
- Auto-tuning can be executed using simple key operations.
- When auto-tuning starts, the temperature controller becomes an ON/OFF controller, with its output alternating between 100% and 0%.

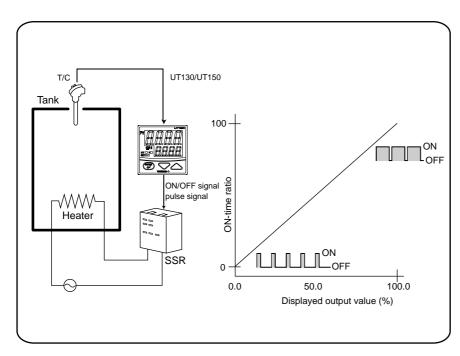
Do not use auto-tuning in the following

- Fast-response processes such as pressure and flow
- Processes in which control output ON/OFF switching is inappropriate
- Auto-tuning time is different according to the process.

The longest time is 24 hours.

6.6 Control Output

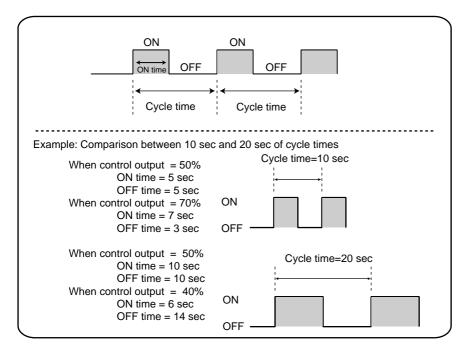
6.6.1 Time Proportional PID Output (Relay Output / Voltage Pulse Output)



- I his function is available for U I 130-RN or -VN. UT15X-RN or -VN.
- In time proportional PID, the PID computation result is output in the form of an ON/OFF signal pulse width.
- The fraction of the cycle time (shown below) during which output is ON (ON-time ratio) is proportional to the displayed output value (PID computation value).
- This function is primarily used in electrical heating control.

1	Contact rating: 250V AC, 3A (resistance load)
pulse	ON voltage: 12V DC OFF voltage: 0.1V DC or less (Load resistance: 600‰ or more)

6.6.2 Cycle Time

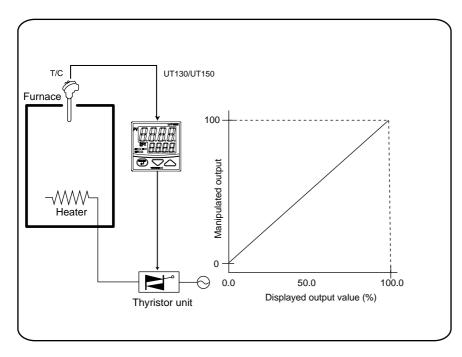


- This function is available in time proportional control.
- Cycle time is the basic cycle period for a signal full cycle of ON/OFF operation for a relay or voltage pulse output.
- Reducing cycle time results in faster cycling and finer control. In general, setting about one tenth of the time constant of control object is standard.
- For relay output, 20 seconds or more of cycle time is recommended for relay life.
- Cycle time can be set using the setup parameter "CT". Cooling-side control output cycle time can be set using the setup parameter "CTC".

Parameter Range

CT CTC	1 to 240 sec
-----------	--------------

6.6.3 Continuous PID Output (4 to 20mA DC)



- This function is available for UT150X-AN.
- In continuous PID output, the PID computation result is output as a continuous analog signal. The analog signal that serves as manipulated output (4 to 20mA DC) is proportional to displayed output value (PID computation value).
- This output type is used to drive final control elements such as thyristors, electro-pneumatic converter + pneumatic control valve combinations, and electrical positioner + motor-driven valve (or control motors) combinations.

4 to 20mA
DC output

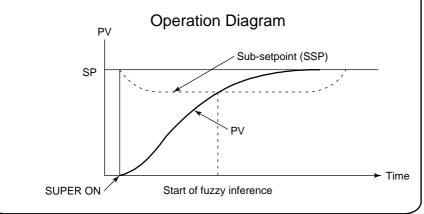
Load resistance:
600% or less
Output accuracy: -0.3%
(of maximum output)

• Output circuit: Isolated from measured input. Not isolated from heating and cooling sides nor from retransmission outputs.

6.7 Overshoot Suppressing Function "SUPER"

6.7.1 "SUPER" Operating Principles

- "SUPER" is effective in the following cases.
- Overshoot must be suppressed.
- Rise-up time needs to be shortened.
- · Load varies often.
- SP is changed frequently.
- The "SUPER" function is effective when used together with the Auto-Tune (AT) function.

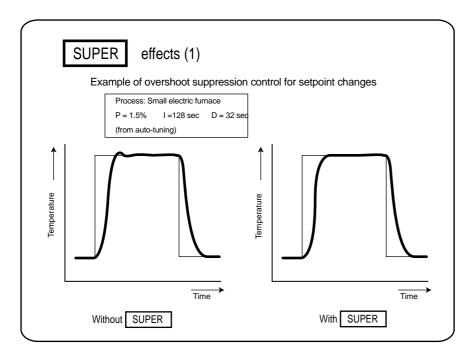


- The "SUPER" function monitors the deviation for evidence that there is a danger of overshoot, and on sensing such danger automatically changes the setpoint temporarily to a somewhat lower value (sub-setpoint "SSP").
- Once the danger of overshoot appears diminished, the function returns the effective setpoint gradually to the true setpoint.
- "Fuzzy inference" techniques are employed in the algorithms used to change the setpoint to the lower temporary value, and to return it gradually to the true setpoint.

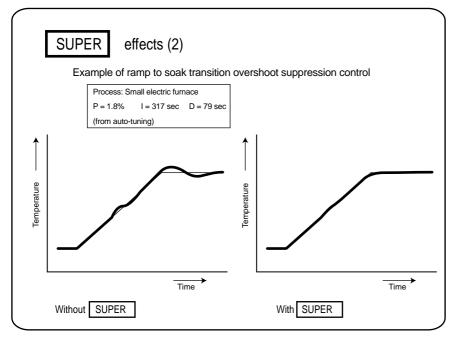
Parameter Range



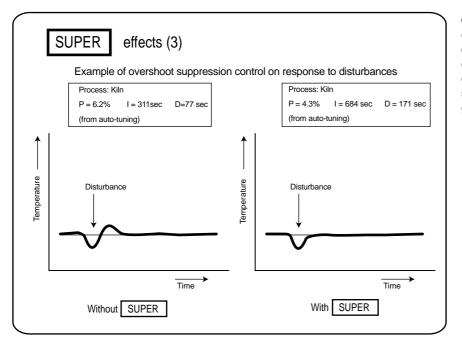
6.7.2 Effects of "SUPER"



- If the optimum PID values are being used, then use of the "SUPER" function yields stable control without overshoot even on setpoint changes.
- As a result, temperature up-ramps follow the programmed pattern more closely, giving more consistent product quality.
- "Overshoot" is not only a matter of temperature exceeding the setpoint, but also of prolonged instability and slow settling resulting from the undershoot that occurs in reaction to the overshoot.



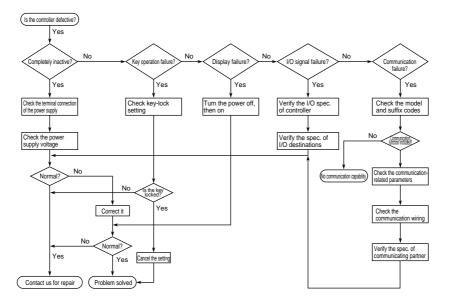
- Due to the gain changes that occur at the transition from ramp to soak, conventional controls are inevitably prone to overshoot. Yet, if the PID constants are set so that the output stabilizes more quickly in order to avoid overshoot, the temperature ramp will lag behind the prescribed pattern.
- By using the "SUPER" function, the temperature up ramp can be made to follow the pattern almost exactly, and significant savings can be achieved.



• The "SUPER" function is extremely effective for improving response to disturbances. The overshoot experienced with conventional PID control in correction for disturbances is significantly reduced, and settling time is greatly speeded up.

7. TROUBLESHOOTING

In the event of an abnormality, perform the following checks as outlined by the flowchart.



■ Error Display during Operation

(1) If the controller displays one of the following, carry out the appropriate remedy for the particular error.

Display	Error content	Remedy
		,
P.E. P. P.Fr		Check the settings of all the parameters and set
「. ட 「P.Er		them at their proper values.
1	Input burnout	Check the sensor wiring and correct it.
D . D B.o	,	Check the sensor wining and correct it.
	PV over-scale	
	(PV exceeds its effective range.)	Check the input type and range settings and
111111	PV under-scale	correct them.
	(PV falls below its effective range.)	
Flashing period	Communication failure	Press any key to stop the flashing.
on PV display	(for /RS option only)	

(2) The controller needs to be repaired if any of the indications in the table below appear. In these cases, do not try to repair the controller yourself. Order a new controller or contact us for repair.

Display	Error content	Display	Error content
Unknown (at power-on)	CPU failure	Flashing Err (at power-on)	RAM or ROM failure
All extinguished (at power-on)	Power source failure	Flashing Err	A/D converter failure,
Err (at power-on)	Calibration abnormal	(during operation)	RJC failure, or EEPROM failure

■When Power Failure Occurred during Operation

• Momentary power failures of less than 20ms (or less than 1ms when "/V24" is specified) have no effect on the controller operation (i.e., normal operation continues).

• For power failures longer than 20ms (or longer than 1ms when "/V24" is specified), however the status will be as follows.

(The controller action at power recovery is the same as at power-on.)

- Alarm action: Continues (but alarms with a waiting action enter the waiting state once)
- Setting parameters: Maintained
- Auto-tuning: Canceled

TI 05C01E02-01E 1st Edition : Oct. 31, 2001-00

8. INSTALLATION AND HARDWARE SPECIFICATIONS

8.1 Installation



CAUTION

To prevent electric shock, the source of power to the controller must be turned off when mounting the controller on to a panel.



NOTE

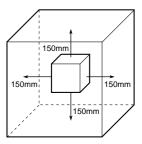
To install the controller, select a location where:

- 1. No-one may accidentally touch the terminals;
- 2. Mechanical vibrations are minimal;
- 3. Corrosive gas is minimal;
- 4. The temperature can be maintained at about 23°C with minimal fluctuation;
- 5. There is no direct heat radiation;

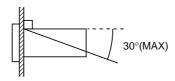
- 6. There are no resulting magnetic disturbances;
- 7. The terminal board (reference junction compensation element, etc.) is protected from wind;
- 8. There is no splashing of water; and
- 9. There are no flammable materials.

Never place the controller directly on flammable items.

If the controller has to be installed close to flammable items or equipment, be sure to enclose the controller in shielding panels positioned at least 150mm away from each side. These panels should be made of either 1.43mm thick metal-plated steel plates or 1.6mm thick uncoated steel plates.



● Mount the controller at an angle within 30° from horizontal with the screen facing upward. Do not mount it facing downward.





CAUTION

1) Before you start wiring, turn off the power source and use a tester to check that the controller and cables are not receiving any power in order to prevent electric shock.

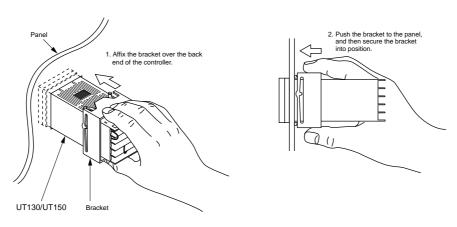
2) Wiring should be carried out by personnel with appropriate electrical knowledge and experience.



IMPORTANT

- Always fix a terminal cover bracket to the UT130 and UT150 controllers before wiring if an optional tional anti-electric-shock terminal cover (part number: L4000FB) is used.
- Two types of optional anti-electric-shock terminal covers (part numbers: T9115YE and T9115YD) are available for the UT152 and UT155 controllers, respectively.

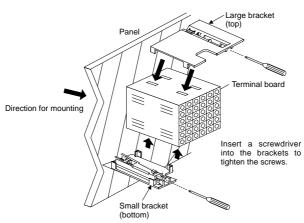
■ How to Mount UT130/UT150



[How to remove the bracket]

To move the bracket, push down the center of the upper and lower parts of the controller softly. The bracket is released from the latch.

■ How to Mount UT152/UT155



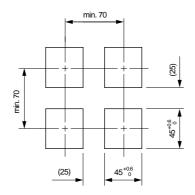
Insert the controller into the opening with the terminal board facing the front. Set and tighten the top and bottom brackets on the controller to fix it on the panel.

<Toc><Ind>

8.2 Panel Cutout Dimensions and External Dimensions

■ UT130 Panel cutout dimensions and external dimensions

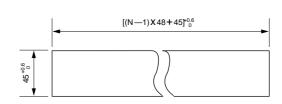
1. General Mounting

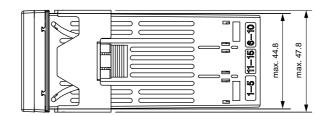


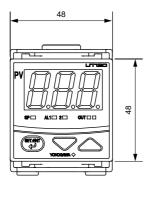
2. Side-by-side Close Mounting

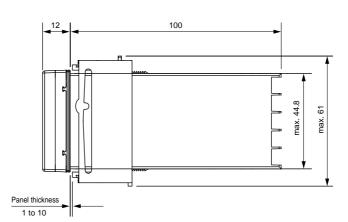
(Splash-proof construction is unavailable) *IP65 is unavailable.

Unit: mm









■ UT150 Panel cutout dimensions and external dimensions

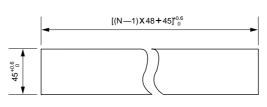
1. General Mounting

(25) 45*0.6 (S) (S) (S)

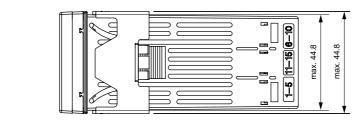
2. Side-by-side Close Mounting

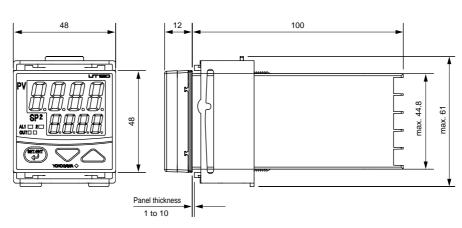
(Splash-proof construction is unavailable) *IP65 is unavailable.

Unit: mm

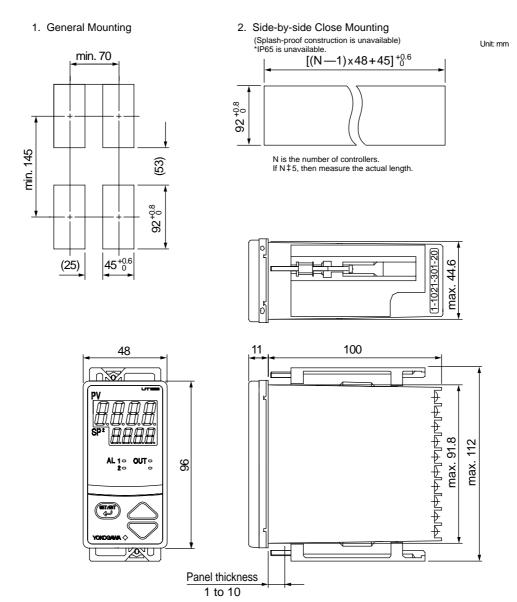


N is the number of controllers. If N $\stackrel{+}{\Rightarrow}$ 5, then measure the actual length.

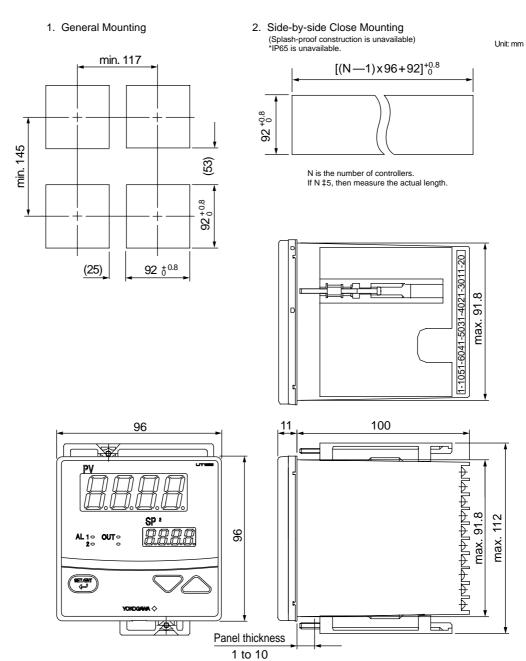




■ UT152Panel cutout dimensions and external dimensions



■ UT155 Panel cutout dimensions and external dimensions



8.3 Wiring



CAUTION

1) Before you start wiring, turn off the power source and use a tester to check that the controller and cables are not receiving any power in order to prevent electric shock.

2) Wiring should be carried out by personnel with appropriate electrical knowledge and experience.



NOTE

- 1) Use a single-phase power source. If the source has a lot of noise, use an isolation transformer for the primary side and a line filter (we recommend TDK's ZAC2205-00U product) for the secondary side. When this noise-prevention measure is taken, keep the primary and secondary power cables well apart. Since the controller has no fuse, be sure to install a circuit breaker switch (of 5A and 100V AC or 220V AC, and that conforms to IEC standards) and clearly indicate that the device is used to de-energize the controller.
- 2) For thermocouple input, use shielded compensating lead wires. For RTD input, use shielded wires which have low resistance and no resistance difference between the 3 wires. See the table given later for the specifications of the cables and terminals and the recommended products.
- 3) The control output relay cannot be replaced even though it has a limited service life (100,000 relay contacts for the resistance load). Thus, an auxiliary relay should be used so that the load can be turned on and off.
- 4) When using an inductive load (L) such as an auxiliary relay and solenoid valve, be sure to insert a CR filter (for AC) or diode (for DC) in parallel as a spark-rejecting surge suppressor to prevent malfunctions or damage to the relay.
- 5) When there is the possibility of being struck by external lightening surge, use the arrester to protect the instrument.



IMPORTANT

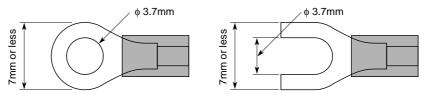
Always fix a terminal cover bracket to the UT130 controller before wiring if an optional anti-electric-shock terminal cover (part number: L4000FB) is used.

Cable Specifications and Recommended Products

Power supply and relay contact output	600V vinyl insulated wire/cable, JIS C3307, 0.9 to 2.0mm ²
Thermocouple input	Shielded compensating lead wire, JIS C1610
RTD input	Shielded wire (3-wire), UL2482 (Hitachi cable)
Other signals	Shielded wire

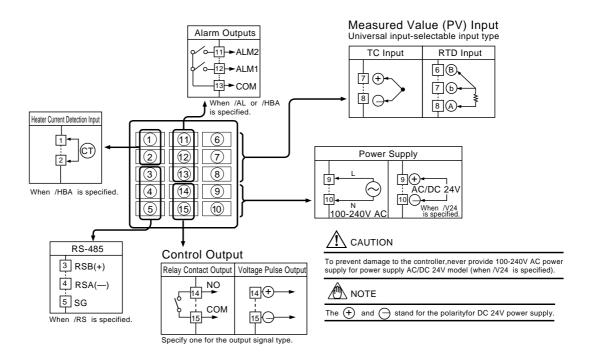
Recommended Terminals

Use M3.5 screw-compatible crimp-on terminals with an insulating sleeve, as shown below.

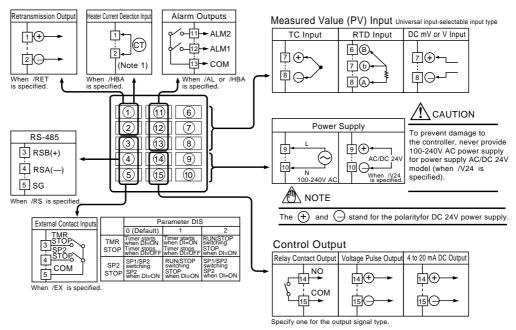


■ Standard Type

UT130 Terminal Arrangement (Standard Type)

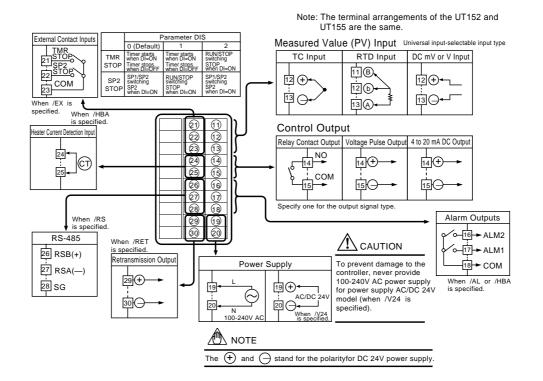


UT150 Terminal Arrangement (Standard Type)



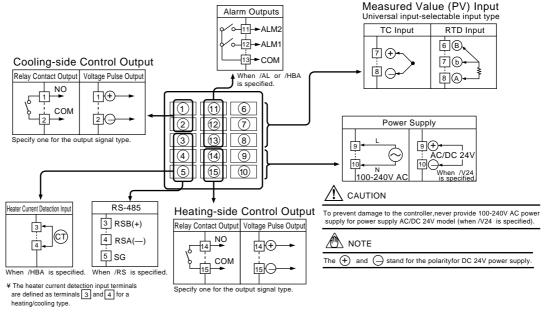
Note 1: The heater current detection input terminals (option code: /HBA) are defined as terminals 1 and 2 for a standard type and as terminals 3 and 4 for a heating/cooling type.

UT152/155 Terminal Arrangement (Standard Type)



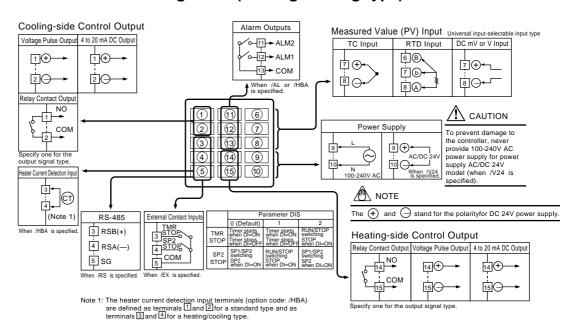
■ Heating/Cooling Type

UT130 Terminal Arrangement (Heating/Cooling Type)

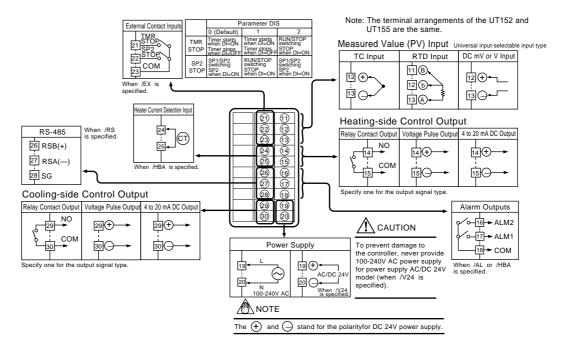


[¥] You are not allowed to specify both the /HBA and /RS options at the same time.

UT150 Terminal Arrangement (Heating/Cooling Type)



• UT152/155 Terminal Arrangement (Heating/Cooling Type)



8-12 <Toc> <Ind>

8.4 Hardware Specifications

Measured Value (PV) Input

- Input: 1 point
- Input type: Universal; can be selected by software
- Input accuracy (at 23 −2°C ambient temperature)
- Thermocouple: -2;C

 However, -4°C for thermocouple input —200 to —100°C
- \bullet –3°C for thermocouple input —100 to 0°C \bullet –5°C for types R and S (–9°C for 0 to 500°C)(For UT150/UT152/UT155 only) −9°C for type B (accuracy is not guaranteed for 0 to 400°C)(For UT150/UT152/UT155 only)
- RTD: −1°C −1digit
- Voltage(mV, V): -0.3% (For UT150/UT152/UT155 only)
- Sampling period for measured value input: 500ms
- Burn-out detection: Functions for thermocouple or RTD input (burn-out upscale only: cannot be switched off)
- Input resistance: 1M‰ or greater for thermocouple or DC mV input.

 Approx. 1M‰ for DC V input (For UT150/UT152/UT155 only)
- Maximum allowable signal source resistance : 250% for thermocouple or DC mV input 2k% for DC V input
- Maximum allowable wiring resistance for RTD input:
 10W/wire (The resistance values of three wires must be the same.)
- Allowable input voltage: -10V DC for thermocouple or DC mV input, -20V DC for DC V input(for UTISUUTISSUUTISS only)
 Noise rejection ratio: Normal mode noise: Min. 40dB
 (50/60Hz)
 Common mode noise: Min. 120dB
- (Min. 90dB for DC V input) (For UT150/UT152/UT155 only) Error of reference junction compensation: -1.5°C (at 15-35°C), -2.0¡C (at 0-50°C)
 The reference junction compensation cannot be switched off.
- Applicable standards:

Thermocouple and resistance temperature detector JIS/IEC/DIN (ITS90)

Control Output

- Output: 1 point (for standard type) or 2 points (for heating/cooling type)
- Output type: Choose one from (1) to (3) below:

(1) Relay contact output Contact capacity: 3A at 240V AC or 3A at 30V DC (with resistance load)

Note: The control output relay cannot be replaced by users

(2) Voltage pulse output

On voltage: 12-18V DC
Off voltage: 0.1V DC or less
(3) Current output (For UT150/UT152/UT155 only)

Output signal: 4 to 20mA

Maximum load resistance: 600%

Output accuracy: -0.3% of span (at 23-2°C ambient temperature)

Alarm Functions

Alarm Functions (Option Code /AL or /HBA)

 Alarm types: 22 types (waiting action can be set by software):
 PV high limit, PV low limit, Deviation high limit, Deviation low limit, Deenergized on deviation high limit, Deenergized on deviation low limit, Deviation high and low limits, High and low limits within deviation, De-energized on PV high limit, De-energized on PV low limit, Fault diagnosis output, FAIL output • Alarm output: 2 relay contacts
Relay contact capacity: 1A at 240V AC or 1A at 30V DC (with resistance load)

Note: The alarm output relays cannot be replaced by users. **Heater Disconnection Alarm (Option Code /HBA)**The heater disconnection alarm is available when time-proportional PID

control or on/off control is selected

- Heater current setting range: 1 to 80A
 Alarm output: 1 relay contact
 (The terminals are the same as those of the /AL option.)
 On time of burn-out detection: Min. 0.2 second
- Sensor: CTL-6-S-H or CTL-12-S36-8 (URD Co., Ltd.)
 To be purchased separately.

To be purchased separately.

Timer Function (Option Code /AL/EX or /HBA/EX)(For UT150/UT152/UT155 only)

The output contact status changes when the preset time has passed since external contact (TMR) turned on.

The contact action can be selected by software from:

(1) Make contact—the contact closes upon time-up.

(2) Break—the contact opens upon time-up.

- Input contact type: See the Contact Inputs below.

Retransmission Output (For UT150/UT152/UT155 only)

The retransmission output is provided only when the /RET option is specified, but is not available for the heating/cooling type

- Output signal: Measured value in 4-20mA DC
- Maximum load resistance: 600%
 Output accuracy: -0.3% of span (at 23-2°C ambient temperature)

Contact Inputs (For UT150/UT152/UT155 only)

The contact inputs are provided only when the /EX option is specified. • Functions: (1) SP1/SP2 switching
(2) Starting a timer (See the Alarm Functions.)

- (3) RUN/STOP switching Can be selected by parameter DIS.
- Input: 2 points (with the shared common terminal)
 Input type: Non-voltage contact or transistor contact input
- Contact capacity: At least 12V/10mA

Communication Function

communication function is provided only when the /RS option is specified. (For details the instruction manual of the communications functions IM 05C01E12-10E.) read the instruction manual of the c
Communication Protocol

Personal computer link: Used for

- Personal computer link: Used for communication with a personal computer, or UT link module of the FA-M3 controller (from Yokogawa Electric Corporation). Ladder communication: Used for communication with a ladder communication with a ladder communication that fa-M3, or a programmable controller of other manufacturers.
- MODBUS communication: Used for communication with equipment featuring the MODBUS protocol.

- Moubeus communication: Used for communication with equipment reaturing the Moubeus protocol.
 Communication Interface
 Applicable standards: Complies with EIA RS-485
 Number of controllers that can be connected: Up to 31
 Maximum communication distance: 1,200m
 Communication method: Two-wire half-duplex, start-stop synchronization, non-procedural
 Baut rate: 2400, 4800, or 9600 bps

Safety and EMC Standards

Safety: Confirms to IEC1010-1: 1990 and EN61010-1: 1992

Approved by CSA1010 for installation category CAT II (IEC1010-1), Certified for UL508

EMC standards: Complies with EN61326

The UT130 and UT150 series temperature controllers conform to the standards

specified under the following conditions.

• All wires except those for the power supply and relay contact output terminals are

- shielded.
 The controller does not fluctuate more than 20% even when noise is applied.

Power Supply and Isolation

Power Supply

Power supply	Voltage	Rated at 100-240VAC (-10%) AC/DC 24V when N24 is specified.	
	Frequency	50/60Hz	
Maximum power consumption		8VA max. (4W max.) 3W max. when N24 is specified.	
Memory		Non-volatile memory	
Withstanding Between primary terminals and secondary terminals voltage (See notes 1 and 3.)		1500V AC for 1 minute (See note 2.)	
Insulation resistance	Between primary terminals and secondary terminals (See notes 1 and 3.)	20M‰ or more at 500V DC	

Note 1: The primary terminals are the power supply terminals and relay output terminals

The secondary terminals are the analog input and output terminals, the voltage pulse output terminals, and the contact input terminals.

Note 2: The withstanding voltage is specified as 2300 V AC per minute to provide a margin of safety.

Note 3: AC/DC 24V terminals are secondary terminals.

The bold lines below indicate reinforced isolation, and the broken line indicates functional isolation.

	·
Power supply terminals (100-240V AC)	● Power supply terminals AC/DC 24V (When /V24 is specified)
Control output terminals (relay contacts)	■ Measured value input terminals ■ 2 input terminal for /EX ■ CT input terminals for /HBA ■ Internal circuit
Alarm output terminals (2 relay contacts)	 Control output terminals: 4-20 mA/Voltage pulse RS-485 terminals for /RS

Note: Neither the measured value input terminals, CT input terminals for the /HBA option, nor 2 input terminals for the /EX option are isolated from the internal circuit.

- Construction, Mounting, and Wiring
 Construction: Splash-proof front panel (compliant with IP65 [Models UT130 and UT150] and IP55 [Models UT152 and 155]). Splash-proof construction is not available if the controller is mounted closely side-by-side.
- · Casing: ABS resin and polycarbonate
- Case color: Black
 Mounting: Flush panel mounting
- Terminals: Screw terminals Environmental Conditions

Normal Operating Conditions

- Warm-up time: At least 30 minutes
 Ambient temperature:0-50°C (0-40°C when mounted side-by-side)
- Rate of change of temperature: 10°C/h or less
 Ambient humidity: 20-90% RH (no condensation allowed)
- Magnetic field: 400A/m or less
 Continuous vibrations of 5 to 14Hz: Amplitude of 1.2mm or less
- Continuous vibrations of 14 to 150Hz: 4.9m/s² (0.5G) or less
- Short-period vibrations: 14.7m/s² (1.5G) for 15 seconds or less
 Shock: 98m/s² (10G) for 11 milliseconds or less
- Mounting angle: Upward incline of up to 30 degrees; downward incline is not allowed.
 Altitude: 2000m or less above sea level

Maximum Effects from Operating Conditions

(1) Temperature effects

- Thermocouple, DC mV and DC V input: -2 V/°C or -0.02% of F.S./°C, whichever is larger
- Resistance temperature detector: -0.05°C/°C
 Analog output: -0.05% of F.S./°C
- Analog output: -0.05% of F.S. /V

 Analog output: -0.2 V/V or -0.002% of F.S./V, whichever is larger

 Analog output: -0.25% of F.S. /V

 Transportation and Storage Conditions

- Temperature: —25 to 70°C
- Humidity: 5 to 95% RH (no condensation allowed)
 Shock: Package drop height 90cm (when packed in the dedicated package)