REEN Model UP750 **Program Controller User's Manual for Single-loop Control** Installation

IM 05E01B02-01E



2nd Edition: Jul 1, 2001

Yokogawa M&C Corporation

This manual describes installation, wiring, and other tasks required to make the controller ready for operation.

Contents

- 1. Safety Precautions
- 2. Model and Suffix Codes
- 3. How to Install
- 4. How to Connect Wires
- 5. Hardware Specifications 6. Terminal Wiring Diagrams

Introduction

Thank you for purchasing the UP750 program controller.

The controller is shipped from the factory with 7 hardcopy user's manuals (A2 size) and 1 user's manual on CD-ROM. The 7 user's manuals in hardcopy format describe the operating procedures required for basic use (factory-set to single-loop control mode). It is recommended that you refer to these user's manuals to understand [1] installation, [2] initial settings, [3] program settings

and [4] operating procedures of the controller.

The CD-ROM contains an User's Manual (Reference) with descriptions of various functions and setting ranges that can be set as necessary. The manual also contains information on operations used to carry out control other than single-loop control. Moreover, the use of an optional parameter setting tool (Model: LL100-E10) allows you to easily perform settings and adjustments with

■ How to Use the Manuals

Purpose	Manual Title	Description	Media
Setup	Installation	Describes the tasks (installation, wiring, and others) required to make the controller ready for operations.	A2-size paper back and front
Basic operation	Initial Settings	Describes examples of setting PV input types and control output types. Making settings described herein and program creation in Programming User's Manual allows you to carry out basic control.	A2-size paper back and front
Program creation	Programming	Describes examples of creating basic programs. The use of the program pattern setup charts included in the Program Parameters User's Manual is recommended.	A2-size paper back and front
General understand- ing of programming operations	Program Parameters	Contains a parameter map that serves as a guide to creating programs. Also includes a brief explanation of the functions of program parameters.	A2-size paper, back and front
Operating procedures and troubleshooting	Operations	Describes key operation sequences. For operation control through external contact inputs, see the back of Installation User's Manual.	A2-size paper back and front
Brief operation	Parameter Map	Contains the parameter map used as a guideline for setting parameters.	A2-size paper, back and front
Function description and setpoint recording	Parameters	Briefly describes the functions of parameters. In addition, each parameter table has a User Setting column, where you can record your setpoints when setting them in the controller.	A2-size paper, back and front
Detailed description of functions	User's Manual (Reference)	Explains more advanced applications than those found in the 7 hardcopy user's manuals (A2 size).	CD-ROM

1. Safety Precautions

symbol is indicated on the controller to ensure safe use.



CAUTION

This symbol on the controller indicates that the operator must refer to an explanation in the user's manual in order to avoid the risk of injury or death of personnel or damage to the instrument. The manual describes how the operator should exercise special care to avoid electric shock or other dangers that may result in injury or loss of life.

The following symbols are used in the hardcopy user's manuals and in the user's manual supplied on the CD-ROM.



Indicates that operating the hardware or software in a particular manner may damage it or result in a system failure.



Draws attention to information that is essential for understanding the operation and/or features of the controller.

2. Model and Suffix Codes

check that the model and suffix codes match your order

Before using the C	before using the controller, check that the moder and sumx codes match your order.		
Model	Suffix Code		Description
UP750	Program controller (provided with Custom Computing Function (Note1))		
Туре	-0 Single-loop type -5 Dual-loop type		
Optional functions 0		0	None With communication, auxiliary analog input (Note?)

Note1: Using an optional custom computation building tool (Model LL200-E10) that runs on a personal computer, you can build a variety of computations (e.g., four arithmetic operations, logical operations, ten-segment linearizer con factor computations, and pressure correction factor computations) to be applied to the controller's I/O signals. Note2:Not used in single-loop control.

Check that the following items are provided:

• User's Manual (Reference) (CD-ROM Version):

- Program controller (of ordered model):
- Brackets (mounting hardware): Unit label:
- User's Manuals for Single-loop Control: 7 (A2 size)

3. How to Install



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- To install the controller, select a location where:
- (1) no one may accidentally touch the terminals (2) mechanical vibrations are minimal,
- (3) corrosive gas is minimal,
- (4) temperature can be maintained at about 23°C and the fluctuation is minimal,
- (5) no direct radiant heat is present,
- (6) no magnetic disturbances are caused. (7) no wind blows against the terminal board (reference junction compensation

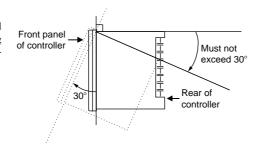
- (9) no flammable materials are around,

Never place the controller directly on flammable items or equipment.

If the controller has to be installed close to flammable items or equipment, be sure to provide shielding panels all around the controller, at least 150mm away from every side; the panels should be made of either 1.43mm-thick metal-plated steel plates or 1.6mm-thick uncoated steel plates.

Installation Position

Install the controller at an angle within 30° from horizontal with the front panel facing upward. Do not install it facing downward. The position of right and left sides should be hori-

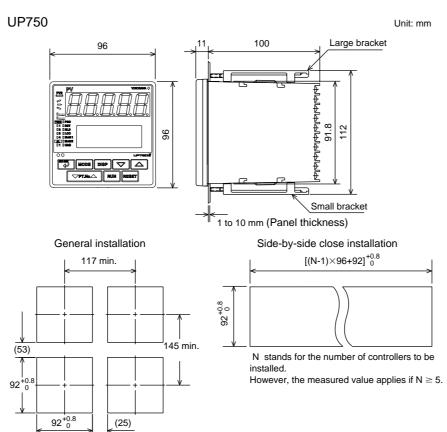


150mm

. 150mm

150mm

■ External Dimensions and Panel Cutout Dimensions



■ How to Install



Turn off the power to the controller before installing it on the panel because there is a possibility of electric shock.

After opening the mounting hole on the

panel, follow the procedures below to in-

Insert the controller into the opening

from the front of the panel so that the

terminal board on the rear is at the far

Set the brackets in place on the top and

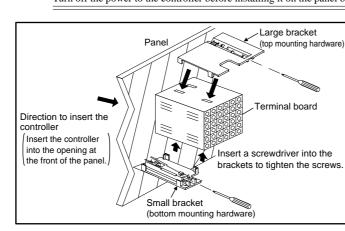
bottom of the controller as shown in the

figure on the left, then tighten the

screws of the brackets. Take care not to

stall the controller:

overtighten them.



4. How to Connect Wires

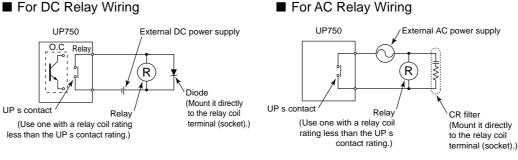
CAUTION

- 1) Before carrying out wiring, turn off the power to the controller and check that the cables to be connected are not alive with a tester or the like because there is a possibility of electric shock.
- 2) Wiring must be carried out by personnel who have basic electrical knowledge and practical experience.

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- 1) Provide power from a single-phase instrument power supply. If there is a lot of noise in the power line, insert an insulating transformer into the primary side of the line and use a line filter (recommended part: ZAC2205-00U from TDK) on the secondary side.
- As a countermeasures against noise, do not place the primary and secondary power cables close to each other. 2) For thermocouple input, use shielded compensating lead wires for wiring. For RTD input, use shielded wires that have low conductor resistance and cause no significant differences in resistance between the three wires.
- The cables to be used for wiring, terminal specifications, and recommended parts are as shown below. 3) Control output relays may be replaced. However, because they have a life of 100,000 times that of the resis-
- tance load, use auxiliary relays to turn on/off a load. 4) The use of inductance (L) loads such as auxiliary relays, motors and solenoid valves causes malfunction or relay failure; always insert a CR filter for use with alternating current or a diode for use with direct current, as a spark-removal surge suppression circuit, into the line in parallel with the load.
- 5) When there is possibility of being struck by external lightening surge, use the arrester to protect the instrument.

■ For DC Relay Wiring



Cable Specifications and Recommended Cables

Purpose	Name and Manufacturer
Power supply, grounding, relay contact outputs	600 V PVC insulated wires, JIS C 3307, 0.9 to 2.0 mm ²
Thermocouple	Shielded compensating lead wires, JIS C 1610, □X-□-□□-□ (See Yokogawa Electric s GS 6B1U1-E.)
RTD	Shielded wires (three conductors), UL2482 (Hitachi Cable)
Other signals	Shielded wires

Recommended Terminal Lugs

Applicable wire size	Tightening torque	
0.3 to 1.65 mm ²	0.8 N·m or less	
3	.7mmφ	3.7mmф
mm or less		

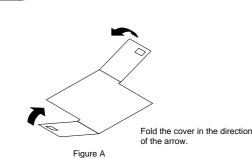
Terminal Covers (Optional parts)

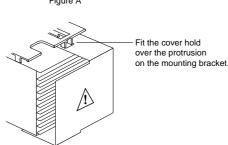
	For UP750	T9115YD	1
1. E	Before attaching the	e terminal cover, be	end the side with
t	he groove inward a	s shown in Fig. A.	Be careful not t

bend it backwards. This not only marks it harder to attach the cover but will also weaken its hold.

Target Model Part Number Sales Unit

2. Fit the holes on the top and bottom of the terminal cover the projections on the brackets (Fig. B) and lock in place. The figure right shows the attachment of a terminal cover to UP controller.





5. Hardware Specifications

PV Input Signals

- Number of inputs: 1 (terminals @-@-@)
- · Input type: Universal input system. The input type can be selected with the software.
- Sampling period: Can be selected from 100, 200 and 500 ms. · Burnout detection: Functions at TC, RTD, standard signal (0.4 to 2 V or 1 to 5 V)
- Upscale, downscale, and off can be specified. For standard signal, burnout is deter ined to have occurred if it is 0.1 V or less.
- Input bias current: 0.05 μA (for TC or RTD b-terminal)
- · Measurement current (RTD): About 0.13 mA - Input resistance: 1 $M\Omega$ or more for thermocouple or mV input
- About 1 $M\Omega$ for DC voltage input - Allowable signal source resistance: 250 Ω or less for thermocouple or mV input
- Effects of signal source resistance: $0.1 \mu V/\Omega$ or less $2 \text{ k}\Omega$ or less for DC voltage input
- Effects of signal source resistance: About 0.01%/100 Ω · Allowable wiring resistance: for RTD input Maximum 150 Ω/wire: Conductor resistance between three
- wires should be equal However, 10 Ω/wire for a maximum range of -150.0 to 150.0°C.
- Wire resistance effect: $\pm 0.1^{\circ} C \, / 10 \; \Omega$
- Allowable input voltage: ±10 V DC for thermocouple, mV, or RTD input ±20 V DC for DC voltage input
- Noise rejection ratio: 40 dB (50/60 Hz) or more in normal mode 120 dB (50/60 Hz) or more in common mode • Reference junction compensation error: ±1.0°C (15 to 35°C)
- ±1.5°C (0 to 15°C, 35 to 50°C) Applicable standards: JIS, IEC, DIN (ITS-90) for thermocouples and RTD

Auxiliary Analog Input Signals

- Available only for controllers with auxiliary analog input terminals These signals are not used in single-loop control, however,
- Number of inputs: 1 (terminals @-@) Input type: Settable in a range of 0-2, 0-10, 0.4-2.0, or 1-5 V DC
- Sampling period: 100, 200 and 500 ms The sampling period of an auxiliary analog input signal is associated with the PV input's sampling period.
- Input resistance: About 1 MΩ • Input accuracy: ±0.3% ±1 digit of input span for 0 to 2 V DC
- $\pm 0.2\% \pm 1$ digit of input span for 0 to 10 V DC $\pm 0.375\% \pm 1$ digit of input span for 0.4 to 2.0 V DC $\pm 0.3\% \pm 1$ digit of input span for 1 to 5 V DC Under standard operating conditions (23±2°C, 55±10% RH, power frequency of 50/60 Hz)

Loop Power Supply

ower is supplied to a two-w (15 V DC: terminals @-⑤) A resistor (10 to 250 Ω) connected between the controller and transmitter converts a current signal into a voltage signal, which is then read via the PV input terminal. Supply voltage: 14.5 to 18.0 V DC, max. 21 mA (provided with a protection circuit against a field short-circuit)

Retransmission Output

Figure B

- Either PV, program setpoint, or control output is output. Either the retransmission output or the loop power supply can be used with terminals @- . .
- Number of outputs: 1 or 2 (terminals @-⑤, terminals ⑥-⑥)
- Output signal: 4-20, 0-20, 20-4, or 20-0 mA DC (where
- outputting signal levels of less than 0 mA is not feasible)
- Load resistance: 600 Ω or less - Output accuracy: $\pm 0.1\%$ of span ($\pm 5\%$ of span for 1 mA or less.) under standard operating conditions (23 \pm 2°C, 55 $\pm 10\%$ RH, power frequency of 50/60 Hz)

Control Output

- Universal output system, The output type can be selected with the software.

(Single-loop type: terminals @-@; heating-side output: terminals @-@, cooling-side output: terminals @-⑤)

Number of outputs	or 2 (two for heating/cooling control), switched between a voltage pulse output and current output.		
Output signal	4-20, 0-20, 20-4, or 20-0 mA DC		
Load resistance	600 Ω or less		
Output accuracy	\pm 0.1% of span (\pm 5% of span for 1 mA or less) Under standard operating conditions (23 \pm 2 $^{\circ}$ 55 \pm 10% RH, power frequency of 50/60 Hz		

Voltage pulse output (Single-loop type: terminals @-@; heating-side output:

terminals @-@, cooling-side output: not selected)

	ber of tputs	1 switched between a voltage pulse output and current output.
Outpu	ıt signal	On-voltage = 12 V or more (load resistance: 600 Ω or more) Off-voltage = 0.1 V DC or less
Res	olution	10 ms or 0.1% of output, whichever is larger

· Relay contact output

(Single-loop type: terminals ①-②-③, heating-side output: terminals ①-②-③, cooling-side output: terminals ④-⑦)

	- · · · · · · · · · · · · · · · · · · ·
Number of outputs	1 or 2 (two for heating/cooling control)
Output signal	Three terminals (NC, NO, and common)/Two terminals
Contact rating	Terminals (1) - (2) - (3): 250 V AC or 30 V DC, 3 A (resistance load) Terminals (4) - (7): 240 V AC or 30 V DC, 1A (resistance load)
Resolution	10 ms or 0.1% of output, whichever is larger

Contact Inputs

Purpose: Program pattern no. selection, and run/reset switching • Number of inputs: 7 points

On/off determination: For non-voltage contact input, contact

· Minimum status detection hold time: PV input's sampling

resistance of $1 \text{ k}\Omega$ or less is determined as "on" and contact

For transistor open collector input, input voltage of 2 V or

less is determined as "on" and leakage current must not

5-digit, 7-segment, red LEDs, character height of 20 mm

• Safety: Compliant with IEC1010-1: 1990 and EN61010-1: 1992

CSA1010 installation category (overvoltage category):

The instrument continues to operate at a measuring

accuracy of within ±20% of the range during tests.

Construction, Installation, and Wiring

For side-by-side close installation the controller loses its

96 (W) \times 96 (H) \times 100 (depth from panel face) mm

Installation: Panel-mounting type. With top and bottom

Wiring: M3.5 screw terminals (for signal wiring and power

• Power supply: Rated voltage of 100 to 240 V AC (±10%), 50/60 Hz

Between primary terminals* and secondary terminals** At least 1500 V AC for 1 minute (Note)

Between primary terminals* and grounding terminal:

Between grounding terminal and secondary terminals**

* Primary terminals indicate power terminals and relay

** Secondary terminals indicate analog I/O signal, voltage

Note: The withstanding voltage is specified as 2300 V AC

At least 1500 V AC for 1 minute (Note)

At least 1500 V AC for 1 minute

At least 500 V AC for 1 minute

pulse output, and contact input terminals

per minute to provide a margin of safety

power terminals and grounding terminal

Not isolated from the internal circuit.

output terminals and the internal circuit

Analog output terminals (for control output and retrans

• Insulation resistance: $20 \text{ M}\Omega$ or more at 500 V DC between

- Grounding: Class 3 grounding (grounding resistance of 100 Ω

PV input terminals: Isolated from other input/output terminals.

- $15~V~D\bar{C}$ loop power supply terminals: Not isolated from analog

current output nor voltage pulse control output. Isolated

Not isolated between analog outputs nor from 15 V DC

loop power supply and voltage pulse control output.

Isolated from other input/output terminals and internal

Voltage pulse control output terminals: Not isolated from analog

other input/output terminals and internal circuit.

· Contact input terminals: Not isolated between contact input

other input/output terminals and internal circuit.

· Relay contact output terminals: Not isolated between relay

· Transistor contact output terminals: Not isolated between

· RS-485 communication terminals: Not isolated from contact

Power terminals: Isolated from other input/output terminals and

· Grounding terminals: Isolated from other input/output terminals

and internal circuit.

and internal circuit.

and internal circuit.

internal circuit.

terminals and internal circuit.

· Relay contact control output terminals: Isolated between contact

outputs and 15 V DC loop power supply. Isolated from

output terminals and from other input/output terminals and

terminals and from communication terminals. Isolated from

contact outputs. Isolated from other input/output terminals

transistor contact outputs. Isolated from other input/output

input terminals. Isolated from other input/output terminals

from other input/output terminals and internal circuit.

Auxiliary analog input terminals: Isolated from other input/

Between secondary terminals*

output terminals

Signal Isolations

mounting hardware (1 each)

Installation position: Up to 30° upward facing

(not designed for facing downward)

Power Supply Specifications

• Power consumption: Max. 20 VA (8.0 W max.)

• Internal fuse rating: 250 V AC, 1.6A time-lug fuse · Data backup: Lithium battery with life expectancy of 10 years

 $92^{+0.8}_{0.0}(W) \times 92^{+0.8}_{0.0}(H) \text{ mm}$

ground wiring as well)

Construction: Only the front panel is dust-proof and drip-pro

dust-proof and drip-proof protection. Material: ABS resin and polycarbonate

Input contact rating: 12 V DC, 10 mA or more

resistance of 20 k Ω or more as "off."

Purpose: Event output, FAIL output, and others

• Transistor contact rating: 24 V DC, 50 mA

Safety and EMC Standards

• EMC standards: Complies with EN61326.

Display Specifications

Status indicating lamps: LEDs

Approved by CSA1010

CATII (IEC1010-1) Approved by UL508

(protection class IP55)

· Case color: Black · Weight: About 1 kg or less

· Panel cutout dimensions:

Withstanding voltage

Number of outputs: 7 points
Relay contact rating: 240 V AC, 1 A, or 30 V DC, 1 A

• Setpoint display: 32×128 dot LCD with back lighting

exceed 100 µA when "off."

period $\times 3$

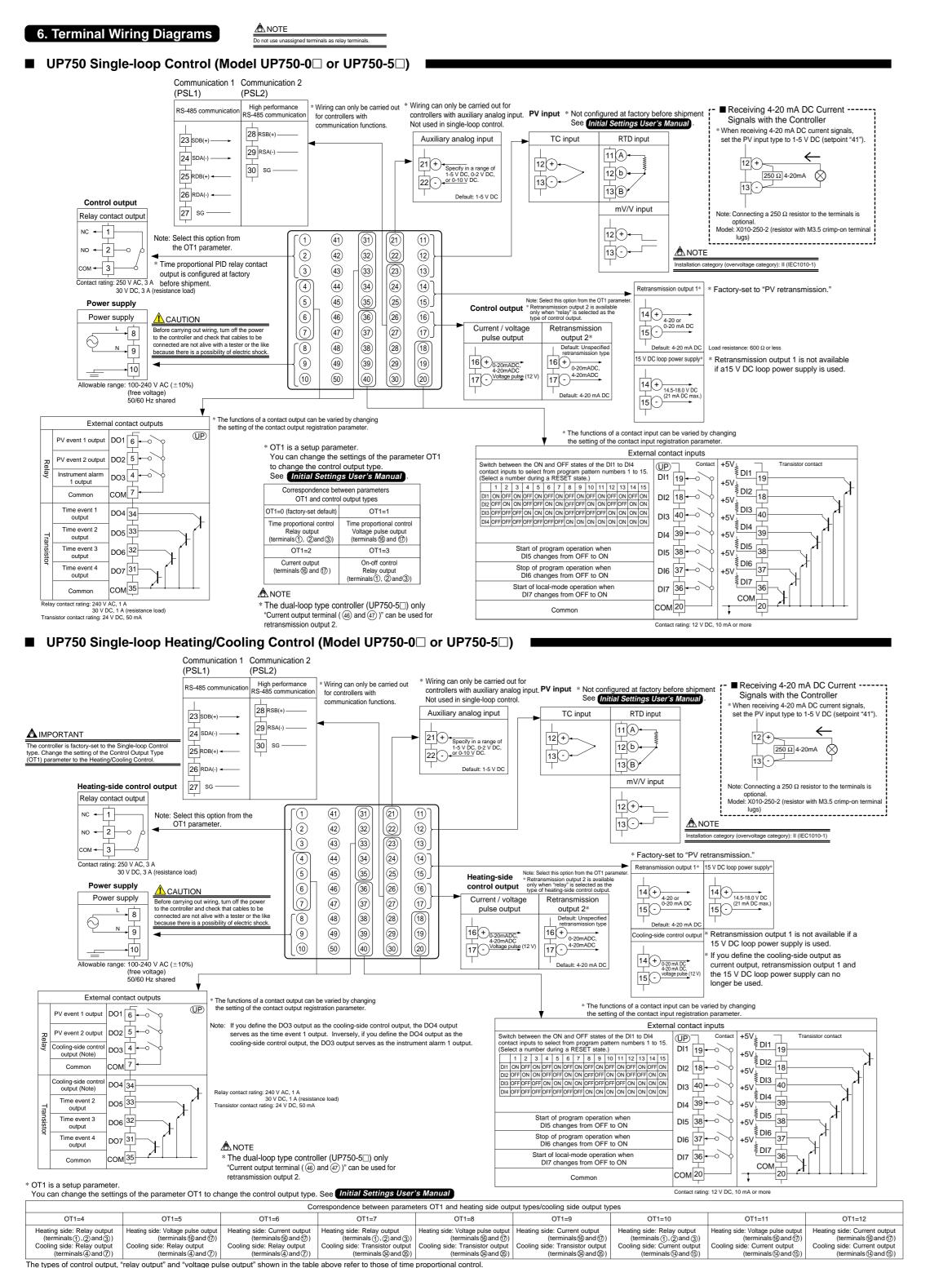
Contact Outputs

- Ambient temperature: 0 to 50°C (40°C or less for side-by-side · Input type: Non-voltage contact or transistor open collector input
 - close installation) Temperature change rate: 10°C/h or less

Environmental Conditions

Normal operating condi

- Ambient humidity: 20 to 90% RH (no condensation allowed)
- Magnetic field: 400 A/m or less
- Continuous vibration at 5 to 14 Hz: Full amplitude of 1.2 mm or Continuous vibration at 14 to 150 Hz: 4.9 m/s² or less
- Short-period vibration: 14.7 m/s², 15 seconds or less Shock: 147 m/s² or less, 11 ms
- Installation height: Height above sea level of 2000 m or less
- Warm-up time: 30 minutes or more after power on · Transportation and storage conditions
- Temperature: -25 to 70°C Temperature change rate: 20°C/h or less
- Humidity: 5 to 95% RH (no condensation allowed) · Effects of changes in operating conditions
- Effects from changes in ambient temperature
- On voltage or thermocouple input, $\pm 1~\mu V/^{\circ}C$ or $\pm 0.01\%$ of F.S./°C, whichever is larger
- On auxiliary analog input, ±0.02% of F.S./°C
- On RTD input, ±0.05°C /°C (ambient temp
- On analog output, ±0.05% of F.S./°C or less - Effects from power supply fluctuation (within rated voltage
- range)
- On analog input, $\pm 1~\mu\text{V}/10~\text{V}$ or $\pm 0.01\%$ of F.S./10 V, whichever is larger
- On analog output, $\pm 0.05\%$ of F.S./ $10\,V$ or less



To change to a relay output for on-off control, select "Relay Terminals" and change the setpoint of the proportional band to "0."

Model UP750 REEN **Program Controller User's Manual for Single-loop Control** Initial Settings

IM 05E01B02-02E



Programming User's Manual

2nd Edition: Jul 1, 2001

Setup Procedure

Power-on

Set PV input.

Initialize

Set setup

parameters.

Set operating

Set program patterns.

Controller operation

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0.0iC

(Factory-set to unspecified.)

See 4. Setting Control Output Type.

See 5. Initializing Parameters

See 2. Setting PV Input Type (Setting First at Power-on), or 3. Changing PV Input Type.

(Factory-set to Time Proportional Relay Output.)

Be sure to follow this

tep whenever a change of settir is made to the PV input type.

2. Setting PV Input Type (Setting First at Power-on)

the operating procedure below for more details.

Set a range

How to return to a menu

-(Example of Temperature Input)

input range

← PV input range → —

Minimum value of Maximum value of PV input range (RL1) PV input range (RH1)

Parameters to be set for temperature input

PV input type (IN1): Set according to a sensor
 Maximum value of PV input range (RH1): Set the maximum value of the range to be controlled.
 Minimum value of PV input range (RL1): Set the

parameter menu.

minimum value of the range to be controlled.

800.0iC

When initializing parameters is excuted, the controller initializes the operating parameter and setup parameters. Therefore, check that the appropriate value are set for the parameters after initializing parameters. If changed to initial values, set them to the appropriate values again.

· The controller displays an operating display when the power is turned on. The submenu "IN" appears at this

point if the type of PV input has not been defined yet. In this case, first press the 🙀 key once to display the

parameter "IN1" for the PV input type, and use the 🛕 key to display the input range code to use, then press

the key to resister it. Then, set the maximum value (RH1) and minimum value (RL1) of the PV input

range (for voltage input, set the maximum value (SH1) and minimum value (SL1) of the PV input scale). See

input range

PV input range

PV input scale

PV input scale (SL1) PV input scale (SH1)

Press the press

Example of Voltage Input

50.0m³/h

Maximum value of

PV input type (IN1): Set according to an input signal
 Maximum value of PV input range (RH1): Set the maximum value of an input signal
 Minimum value of PV input range (RL1): Set the minimum value of an input signal
 Position of PV input decimal point (SDP1): Set the position of the decimal point for PV input display

. Maximum value of PV input scale (SH1): Set the maximum value of the scale to be controlled.

(Set a reading for the maximum value of the input signal.)

6. Minimum value of PV input scale (SL1): Set the minimum value of the scale to be controlled.

(Set a reading for the minimum value of the input signal.)

First check these defaults listed in **Parameters User's Manual**, and change their values if necessary.

0.0m³/h

Minimum value of

rameters to be set for voltage input

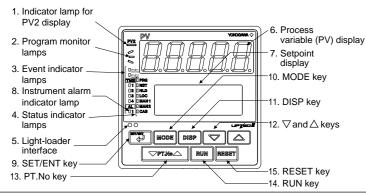
The controller is configured to the default of each parameter at the factory before shipment.

This manual describes examples of setting PV input types, control output types. Carrying out settings described herein allows you to perform basic control. Refer to examples of various settings to understand how to set parameters required. Refer to **Parameter Map User's Manual** for an easy to understand explanation of setting various parameters. If you cannot remember how to carry out an operation during setting, press the DSP key no more than four times. This brings you

to the display (operating display) that appears at power-on. After carrying out the setting describes here, create programs in

- Contents
- 1. Names and Functions of Front Panel Parts 2. Setting PV Input Type (Setting First at Power-on)
- 3. Changing PV Input Type
- 4. Setting Control Output Type
- 5. Initializing Parameters

1. Names and Functions of Front Panel Parts

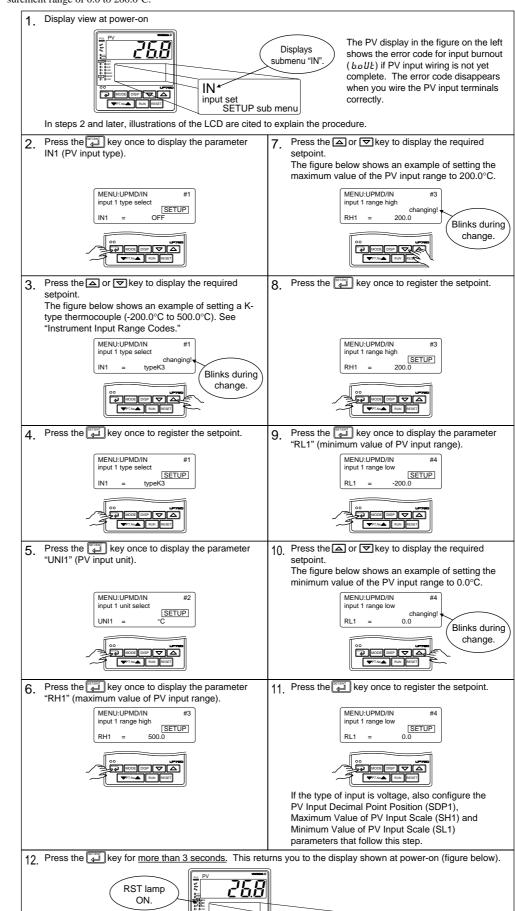


	13. PT.No k	15. RESET Key ———————————————————————————————————	
	Name of Part	Function	
1.	Indicator lamp for PV2 display	Is lit when Loop2 PV is displayed in PV display. Not used in single-loop control.	
2.	Program monitor lamps	 	
3.	Event indicator lamps	Show the statuses of PV events, time events and instrument alarms in orange. PVE1 and PVE2 lamps: Come on when PV event 1 and PV event 2 turn on. TME1 to TME4 lamps: Come on when time event 1 to time event 4 turn on. AL1 lamp: Comes on when instrument alarm 1 turns on.	
4.	Status indicator lamps	Is lit (in green) to indicate the status of operation or control. PRG:Is lit when in program mode. RST:Is lit when in reset mode. HLD:Is lit when in hold mode. LOC:Is lit when in local mode. MAN1:Is lit when in manual mode. MAN2:Not used in single-loop control. CAS:Not used in single-loop control.	
5.	Light-loader interface	Interface for an adapter cable used when setting and storing parameters from a PC. This requires an optional parameter setting tool.	
6.	Process variable (PV) display	Displays PV. Displays an error code (in red) if an error occurs.	
7.	Setpoint display (LCD)	Displays the name and value of a program setpoint (SP), output (OUT), deviation trend, or a parameter. Displays an error code if an error occurs.	
8.	Instrument alarm indicator lamp	The AL1 lamp comes on in orange if instrument alarm 1 occurs.	
9.	SET/ENT key	Used to switch or register a parameter. Pressing the key for more than 3 seconds allows you to switch between the operating display and the main menu for operating parameter setting display alternately.	
10.	MODE key MODE	Presents a display for switching between the hold, advance, local, AUTO and MAN modes.	
11.	DISP key DISP	Used to switch between displays. Pressing this key while any operating display is shown lets you switch to another prearranged operating display. Pressing this key while any display other than an operating display is shown lets you go one display back. (One to four presses (maximum) of this key lets you return to the current operating display, though the number of presses depends on the operating status.)	
12.	∇and △ keys	Used to change numerical values. On setting displays for various parameters, you can change target setpoints, parameters, and output values (in manual operation). Pressing the ∇ key decreases a numerical value, while pressing the \triangle key causes it to increase. You can hold down a key to gradually increase the speed of change. These keys also switch between menu displays when a main menu or submenu of parameter setting display is shown.	
13.	PT.No key	Use this key when the controller is at a reset to select a program pattern number on an operating display.	
14.	RUN key RUN	Pressing this key for more than 2 seconds while an operating display is shown starts the controller.	
15.	RESET key RESET	Pressing this key for more than 2 seconds while an operating display is shown stops the controller.	

■ Setting of Main Parameters at the Factory before Shipment

Item	Factory-set defaults for single-loop type/dual-loop type controllers	
Control output	Time proportional PID relay output (variable)	
Control action	Reverse action (variable)	
PID parameter	P = 5.0%, I = 240 seconds, D = 60 seconds.	

The following operating procedure describes an example of setting a K-type thermocouple (-200.0 to 500.0°C) and a mea-



■ Instrument Input Range Codes

Select the unit from the UNIT parameter.

Input	Туре	Instrument Input Range Code	Instrument Input Range	Measurement Accuracy	
Unspecified		OFF	Set the data item PV Input Type "IN1" to the OFF option to leave the PV input		
			type undefined. -270.0 to 1370.0°C	T	
		type K1	-450.0 to 2500.0°F		
			-270.0 to 1000.0°C		
	K	type K2	-450.0 to 2300.0°F	±0.1% of instrument range ±1 digit at 0°C or more	
			-200.0 to 500.0°C	±0.2% ±1 digit for temperatures below 0°C,	
		type K3	-200.0 to 1000.0°F	where the accuracy is: ±2% of instrument range ±1	
	J	type J	-200.0 to 1200.0°C	digit for temperatures below -200.0°C for a type-K	
	3	type J	-300.0 to 2300.0°F	thermocouple, or $\pm 1\%$ of instrument range ± 1 digit for	
		type T1	-270.0 to 400.0°C	temperatures below -200.0°C for a type-T thermocouple	
	Т	974	-450.0 to 750.0°F		
		type T2	0.0 to 400.0°C		
			-200.0 to 750.0°F 0.0 to 1800.0°C	±0.15% of instrument range ±1 digit at 400°C or more	
	В	type B	32 to 3300°F	±5% of instrument range ±1 digit at less than 400°C	
			0.0 to 1700.0°C	= 0 % of instrument range = 1 digit at less than 400 0	
	S	type S	32 to 3100°F		
	<u></u>	t D	0.0 to 1700.0°C	±0.15% of instrument range ±1 digit	
	R	type R	32 to 3100°F		
Thermocouple			-200.0 to 1300.0°C	±0.1% of instrument range ±1 digit	
	N	type N	-300.0 to 2400.0°F	$\pm 0.25\%$ of instrument range ± 1 digit for temperatures	
				below 0°C	
	E	type E	-270.0 to 1000.0°C		
	_	21 -	-450.0 to 1800.0°F		
	L(DIN)	type L	-200.0 to 900.0°C -300.0 to 1600.0°F	±0.1% of instrument range ±1 digit at 0°C or more ±0.2% ±1 digit for temperatures below 0°C, where the	
	U(DIN)		-200.0 to 400.0°C	accuracy is:±1.5% of instrument range ±1 digit for	
		type U1	-300.0 to 750.0°F	temperatures below -200.0°C for a type-E thermocouple	
			0.0 to 400.0°C		
			-200.0 to 1000.0°F		
	w	type W	0.0 to 2300.0°C	±0.2% of instrument range ±1 digit	
	VV	type w	32 to 4200°F	±0.2% of instrument range ±1 digit	
	Platinel 2	Plati 2	0.0 to 1390.0°C	±0.1% of instrument range ±1 digit	
			32.0 to 2500.0°F	0 0	
	PR20-40	PR2040	0.0 to 1900.0°C	±0.5% of instrument range ±1 digit at 800°C or more	
	WOZDag		32 to 3400°F 0.0 to 2000.0°C	No accuracy is guaranteed at less than 800°C	
	W97Re3- W75Re25	W97Re3	32 to 3600°F	±0.2% of instrument range ±1 digit	
	WYSINGES		-200.0 to 500.0°C		
		JPt1	-300.0 to 1000.0°F	$\pm 0.1\%$ of instrument range ± 1 digit (Note1) (Note2)	
	JPt100	ID40	-150.00 to 150.00°C	10.00% of instrument and a digit (Note 4)	
		JPt2	-200.0 to 300.0°F	±0.2% of instrument range ±1 digit (Note1)	
		Pt1	-200.0 to 850.0°C		
RTD		1 (1	-300.0 to 1560.0°F	$\pm 0.1\%$ of instrument range ± 1 digit (Note1) (Note2)	
	Pt100	Pt2	-200.0 to 500.0°C		
			-300.0 to 1000.0°F		
		Pt3	-150.00 to 150.00°C -200.0 to 300.0°F	±0.2% of instrument range ±1 digit (Note1)	
Standard	0.4 to 2 V	0.4 to 2 V	0.400 to 2.000 V		
signal	1 to 5 V	1 to 5 V	1.000 to 5.000 V	1	
<u> </u>	0 to 2 V	0 to 2 V	0.000 to 2.000 V	1	
	0 to 10 V	0 to 10 V	0.00 to 10.00 V	±0.1% of instrument range ±1 digit	
OC voltage	0.0 to 1.2 V	0.0 to 1.2 V	0.000 to 1.200 V	Display range is scalable in a range of -19999 to 30000. Display span is 30000 or less.	
o voltage	(Note3)			Display spair is source of less.	
	-10 to 20 mV	mV1	-10.00 to 20.00 mV		
	0 to 100 mV	mV2	0.0 to 100.0 mV	I .	

Note1: The accuracy is $\pm 0.3^{\circ}$ C of instrument range ± 1 digit for a temperature range from 0°C to 100°C. Note2: The accuracy is $\pm 0.5^{\circ}$ C of instrument range ± 1 digit for a temperature range from -100°C to 200°C.

Note3: Not used in single-loop control. * To receive a 4-20 mA DC signal, select a standard signal of 1 to 5 V DC and connect it to a 250Ω resistor. This resistor is optional. Model: X010-250-2 (resistor with M3.5 crimp-on terminal lugs)



 $The \ controller \ may \ automatically \ initialize \ the \ registered \ operating \ parameter \ setpoints \ if \ any \ change \ is \ made \ to \ the$ data item PV Input Type (IN1), Maximum Value of PV Input Range (RH1), Minimum Value of PV Input Range (RL1), PV Input Decimal Point Position (SDP1), Maximum Value of PV Input Scale (SH1) or Minimum Value of PV Input Scale (SL1). After a change has been made to any of these data items, be sure to verify the registered operating parameter setpoints to ensure that they are correct. If any data item has been changed to its default, set it to a required value.

Ranges Selectable for PV Input

Thermocouple	typeK1, K2, K3, J, T1, T2, B, S, R, N, E, L, U1, U2, W, Plati2, PR2040
RTD	JPt1, JPt2, Pt1, Pt2, Pt3, Pt4
DC voltage(mV,V)	0.4 to 2 V, 1 to 5 V, 0 to 2 V, 0 to 10 V, mV1, mV2

١.	
	<u> </u>
	E Suit D Suit
	WODE DISP TO THE PROPERTY OF T
	In steps 2 and later, illustrat
2.	Press the key once to IN1 (PV input type).
	MENU:UPMD/IN input 1 type select
	IN1 = O
	MODE DISP
3.	Press the △ or ▼ key to e setpoint.
	The figure below shows an type thermocouple (-200.0° "Instrument Input Range Co
	MENU:UPMD/IN input 1 type select
	IN1 = typel
	MODE DISP V
4.	Press the key once to
	MENU:UPMD/IN input 1 type select IN1 = type
	[00
	MOCE DISP
5.	Press the لغي key once to "UNI1" (PV input unit).
	MENU:UPMD/IN input 1 unit select
	UNI1 =
	MODE DISP V
6.	Press the key once to "RH1" (maximum value of F
	MENU:UPMD/IN input 1 range high
	RH1 = 500
	MODE DISP
12.	Press the key for more
	RST lam ON.

enotes a step that must always be followed.

Denotes a step that should be followed as necessary.

0.0°C

IM 05E01B02-02E (1)

3. Changing PV Input Type

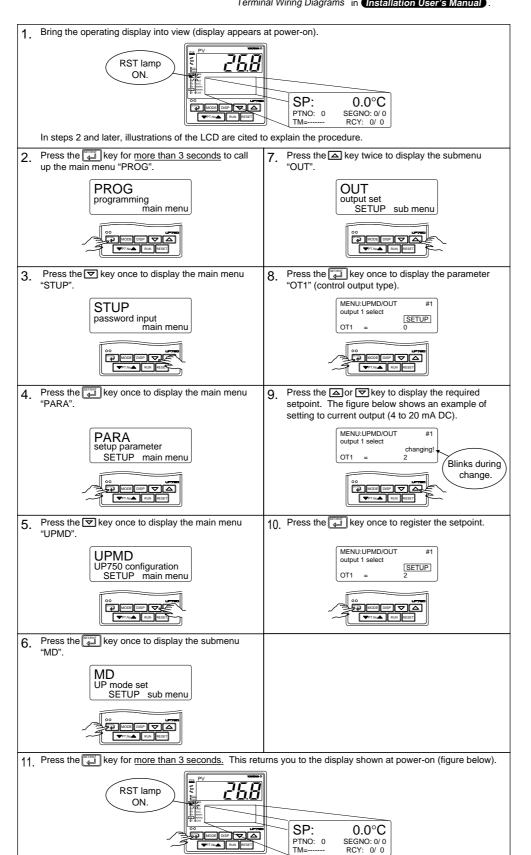
The following operating procedure describes an example of changing the setting of K-type thermocouple (-200.0 to 500.0°C) to RTD Pt100 (-200.0 to 500.0°C) and a measurement range of 0.0 to 200.0°C. .. 10-12-13

1.	Bring the operating display into view (display appears	at po	ower-on)
	RST lamp		
	ON.		
	MODE OSP VA		SP: 0.0°C
	WYTNO RESET	\	PTNO: 0 SEGNO: 0/ 0 TM= RCY: 0/ 0
	In steps 2 and later, illustrations of the LCD are cited t		· · · · · · · · · · · · · · · · · · ·
2.	Press the key for more than 3 seconds to call up the main menu "PROG".	10.	Press the key once to register the setpoint.
	PROG		MENU:UPMD/IN #1 input 1 type select
	programming main menu		IN1 = Pt2
	OO DEF V		
	TOTAL RUN REST		TT MAN RUN RESET
3.	Press the key once to display the main menu "STUP".	11.	Press the key once to display the parameter "UNI1".
	STUP		MENU:UPMD/IN #2
	password input main menu		input 1 unit select SETUP UNI1 = °C
	MODE DISP V		OO DEP VAA
4.	Press the key once to display the main menu	12.	Press the key once to display the parameter
۲.	"PARA".	12.	"RH1" (maximum value of PV input range).
	PARA setup parameter		MENU:UPMD/IN #3 input 1 range high
	SETUP main menu		RH1 = 500.0
	₩73% RAN BESET		TYTANA RIN PESET
5.	Press the key once to display the main menu "UPMD".	13.	setpoint. The figure below shows an example of
			setting the maximum value of the PV input range to 200.0 $^{\circ}\text{C}.$
	UPMD		MENU:UPMD/IN #3 input 1 range high
	UP750 configuration SETUP main menu		changing! RH1 = 200.0 Blinks during
			change.
	WOT NAM RUN RESET		MODE DES TAKE
6.	Press the key once to display the submenu "MD".	14.	Press the key once to register the setpoint.
	MD		MENU:UPMD/IN #3
	UP mode set SETUP sub menu		input 1 range high SETUP
1	OLIOI SUDINCIIU		RH1 = 200.0
	OL LOT SUD HIGHU		
	SETOF SUB INEIU		
7.		15.	RH1 = 200.0 □□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□
7.	Press the Akey once to display the submenu "IN".	15.	Press the key once to display the parameter "RL1" (minimum value of PV input range).
7.	Press the A key once to display the submenu "IN".	15.	Press the key once to display the parameter "RL1" (minimum value of PV input range). MENU: UPMD/IN #4 input 1 range low SETUP
7.	Press the A key once to display the submenu "IN". IN input set SETUP sub menu	15.	Press the key once to display the parameter "RL1" (minimum value of PV input range). MENU: UPMD/IN #4 input 1 range low SETUP RL1 = -200.0
7.	Press the A key once to display the submenu "IN".	15.	Press the key once to display the parameter "RL1" (minimum value of PV input range). MENU: UPMD/IN #4 input 1 range low SETUP
	Press the A key once to display the submenu "IN". IN input set SETUP sub menu		Press the key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN #4 input 1 range low SETUP RL1 = -200.0
7.	Press the A key once to display the submenu "IN". IN input set SETUP sub menu		Press the key once to display the parameter "RL1" (minimum value of PV input range). MENU: UPMD/IN #4 input range low SETUP RL1 = -200.0
	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type).		Press the Key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN #4 input 1 range low SETUP RL1 = -200.0 Press the or key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C.
	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select SETUP		Press the Key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN
	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select		Press the Key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN
	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select IN1 = typeK3		Press the Key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN
8.	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select IN1 = typeK3	16.	Press the key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN input 1 range low SETUP RL1 = -200.0 Press the or very key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU:UPMD/IN #4 input 1 range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input 1 range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input 1 range low changing! Change.
	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select SETUP IN1 = typeK3 Press the or very to display the required setpoint. The figure below shows an example of	16.	Press the Key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN
8.	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select IN1 = typeK3 Press the or very to display the required	16.	Press the key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN input 1 range low SETUP RL1 = -200.0 Press the or very key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU:UPMD/IN #4 input 1 range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input 1 range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input 1 range low changing! Change.
8.	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select SETUP IN1 = typeK3 Press the or key to display the required setpoint. The figure below shows an example of setting the PV input type to a Pt100 resistance temperature detector (-200.0°C to 500.0°C). MENU:UPMD/IN #1 input 1 type select	16.	Press the key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN #4 input 1 range low SETUP RL1 = -200.0 Press the or key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU:UPMD/IN #4 input 1 range low changing change.
8.	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select SETUP input 1 type to a Pt100 resistance temperature detector (-200.0°C to 500.0°C).	16.	Press the Key once to display the parameter "RL1" (minimum value of PV input range). Press the Or key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU: UPMD/IN #4 changing! RL1 = 0.0 MENU: UPMD/IN #4 Input range low changing! RL1 = 0.0 MENU: UPMD/IN #4 MENU: UPMD/IN #4 MENU: UPMD/IN #4
8.	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select SETUP input 1 type to a Pt100 resistance temperature detector (-200.0°C to 500.0°C). MENU:UPMD/IN #1 input 1 type to a Pt100 resistance temperature detector (-200.0°C to 500.0°C).	16.	Press the Key once to display the parameter "RL1" (minimum value of PV input range). Press the SETUP RL1 = -200.0 Press the or key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU: UPMD/IN #4 input 1 range low changing change. Press the key once to register the setpoint.
8.	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select SETUP IN1 = typeK3 Press the or key to display the required setpoint. The figure below shows an example of setting the PV input type to a Pt100 resistance temperature detector (-200.0°C to 500.0°C). MENU:UPMD/IN #1 input 1 type select changing! Blinks during change.	16.	Press the key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN #4 input 1 range low SETUP RL1 = -200.0 Press the or key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU:UPMD/IN #4 input 1 range low changing RL1 = 0.0 MENU:UPMD/IN #4 input 1 range low change.
8.	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select SETUP IN1 = typek3 Press the or key to display the required setpoint. The figure below shows an example of setting the PV input type to a Pt100 resistance temperature detector (-200.0°C to 500.0°C). MENU:UPMD/IN #1 input 1 type select changing! Blinks during change.	16.	Press the Key once to display the parameter "RL1" (minimum value of PV input range). Press the SETUP RL1 = -200.0 Press the or key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU: UPMD/IN #4 input 1 range low changing! RL1 = 0.0 Press the key once to register the setpoint. MENU: UPMD/IN #4 input 1 range low changing! RL1 = 0.0 Press the setpoint. MENU: UPMD/IN #4 input 1 range low setup look setup l
8.	Press the key once to display the submenu "IN". IN input set SETUP sub menu Press the key once to display the parameter "IN1" (PV input type). MENU:UPMD/IN #1 input 1 type select SETUP IN1 = typek3 Press the or key to display the required setpoint. The figure below shows an example of setting the PV input type to a Pt100 resistance temperature detector (-200.0°C to 500.0°C). MENU:UPMD/IN #1 input 1 type select changing! Blinks during change.	16.	Press the Key once to display the parameter "RL1" (minimum value of PV input range). MENU:UPMD/IN
9.	Press the key once to display the submenu "IN". N	16.	Press the Key once to display the parameter "RL1" (minimum value of PV input range). Press the Or key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range to 0.0°C. MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low range lo
9.	Press the key once to display the submenu "IN". IN	16.	Press the Key once to display the parameter "RL1" (minimum value of PV input range). Press the Or key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range to 0.0°C. MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low range low changing! RL1 = 0.0 MENU:UPMD/IN #4 input range low range lo
9.	Press the key once to display the submenu "IN". IN	16.	Press the Key once to display the parameter "RL1" (minimum value of PV input range). Press the Or key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU: UPMD/IN #4 changing RL1 = 0.0 Blinks during change. Press the Ney once to register the setpoint. MENU: UPMD/IN #4 input 1 range low changing change. Press the Ney once to register the setpoint.
9.	Press the key once to display the submenu "IN". IN	16.	Press the Key once to display the parameter "RL1" (minimum value of PV input range). Press the Or key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C. MENU: UPMD/IN #4 changing RL1 = 0.0 Blinks during change. Press the Ney once to register the setpoint. MENU: UPMD/IN #4 input 1 range low changing change. Press the Ney once to register the setpoint.

4. Setting Control Output Type

The following operating procedure describes an ex- Control output terminal Values in parentheses are setpoints ample of changing time proportional PID relay out-

put (0: factory-set default) to current output (2). For details on the output terminals for heating/cooling control, see 6. Terminal Wiring Diagrams in Installation User's Manual.

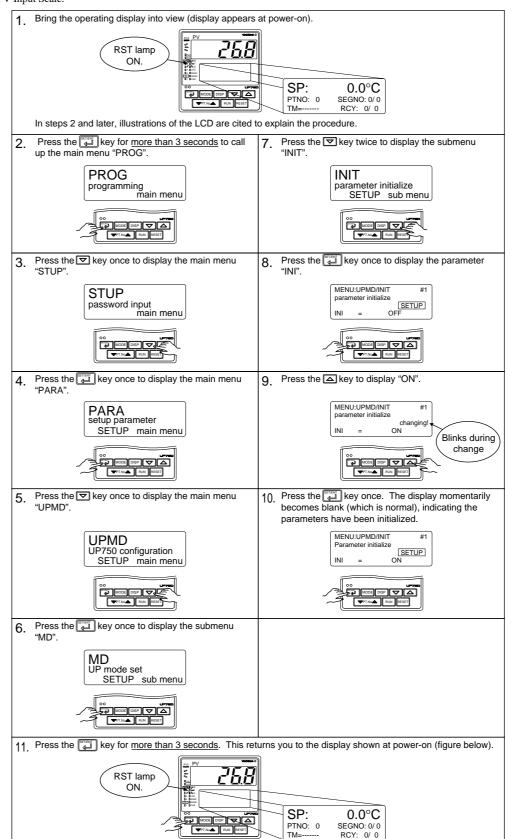


List of Control Output Types

Parameter Symbol	Name of Parameter	Setpoint	Control Output Types
		0	Time proportional PID relay contact output (terminals ① - ② - ③)
		1	Time proportional PID voltage pulse output (terminals 6 - 7)
		2	Current output (terminals 6 - 7)
		3	On/off control relay contact output (terminals ① - ② - ③)
	Control output type	4	Heating-side relay output (terminals ① - ② - ③), cooling-side relay output (terminals ④ - ⑦)
		5	Heating-side pulse output (terminals (6) - (7)), cooling-side relay output (terminals (4) - (7))
⊢OT1		6	Heating-side current output (terminals 6 - 7), cooling-side relay output (terminals 4 - 7)
•		7	Heating-side relay output (terminals ① - ② - ③), cooling-side transistor output (terminals ④ - ⑤)
		8	Heating-side pulse output (terminals 6 - 7), cooling-side transistor output (terminals 4 - 3)
		9	Heating-side current output (terminals ® - ®), cooling-side transistor output (terminals ® - ®)
		10	Heating-side relay output (terminals ① - ② - ③), cooling-side current output (terminals ⑭ - ⑤)
		11	Heating-side pulse output (terminals 6 - 7), cooling-side current output (terminals 4 - 5)
		12	Heating-side current output (terminals 60 - 67), cooling-side current output (terminals 49 - 45)

5. Initializing Parameters

Be sure to follow the steps below after a change of setting has been made to the data item PV Input Type, PV Input Range or PV Input Scale.



IM 05E01B02-02E (2)

Model UP750 REEN **Program Controller User's Manual for Single-loop Control Programming**

IM 05E01B02-03E



2nd Edition: Jul 1, 2001

Yokogawa M&C Corporation

This manual explains how to create programs by citing specific examples. Create user programs by referring to the given programming examples. Use the parameter map included in "2. Program Parameter Map," in Program Parameters **User's Manual**, in order to further familiarize yourself with the required operations.

Be sure to carry out the settings instructed in *Initial Settings User's Manual* before beginning any of the tasks discussed in this manual.

Contents

- 1. Overview of Program Patterns
- 2. Example of Program Pattern Setup Charts
- 3. Creating Program Patterns
- 4. Changing Program Patterns

1. Overview of Program Patterns

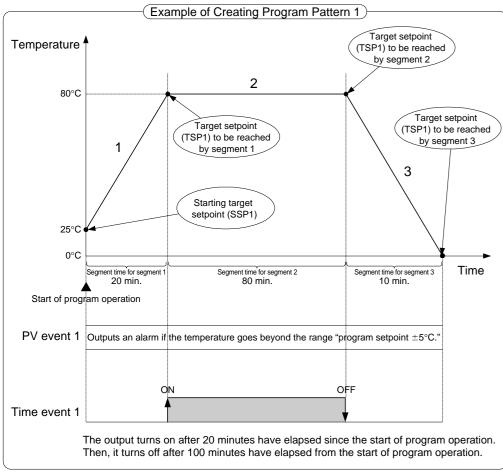
■ Programming Overview

The programming example given here demonstrates how to do the tasks outlined below.

- 1. Program the controller to start program operation at 25°C and raise the temperature up to 80°C in 20 minutes.
- 2. When the temperature reaches 80°C, keep it at this level for 80 minutes.
- 3. Finally, lower the temperature to 0°C in 10 minutes.

Event output

- Set a deviation of 5°C on both the positive and negative sides of a program setpoint to allow the controller to output an event signal if the temperature goes beyond the deviation range.
- \bullet Let the controller output an event signal when the temperature stabilizes to 80°C.



2. Example of Program Pattern Setup Charts

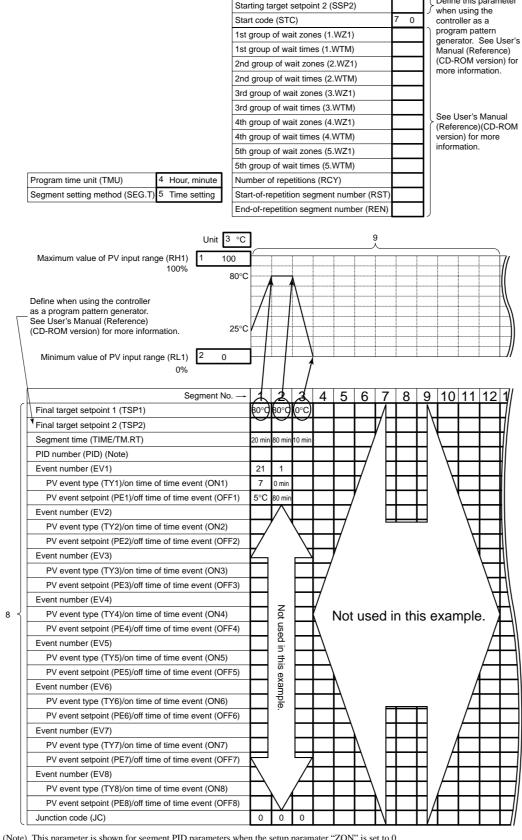
Complete the following setup chart before setting programs in the controller. Filling in the chart makes it easier for you to input program data into the controller. See "1. Program Pattern Setup Charts", in Program Parameters User's Manual In the following chart, fill in the fields with bold-face borders.

1. Maximum value of PV input range: Setpoint of the "Maximum Value of PV Input Range (RH1)" setup parameter 2. Minimum value of PV input range: Setpoint of the "Minimum Value of PV Input Range (RL1)" setup parameter

Starting target setpoint 1 (SSP1)

- 3. PV input unit: Setpoint of the "PV Input Unit (UNI1)" setup parameter
- 4. Program time unit: Setpoint of the "Program Time Unit (TMU)" setup parameter
- 5. Segment setting method: Setpoint of the "Segment Setting Method (SEG.T)" setup parameter
- 6. Starting target setpoint: Setpoint of the "Starting Target Setpoint (SSP1)" program parameter
- 7. Start code: Setpoint of the "Start Code (STC)" program parameter
- 8. Final target sepoint, Segment time, Events (PV event and Time event) and Junction code: setpoint of each program
- 9. Draw the program pattern.

Example of Chart Entries



(Note) This parameter is shown for segment PID parameters when the setup parameter "ZON" is set to 0.

3. Creating Program Patterns

The following operating procedure describes an example of creating the program discussed in "1. Overview of Program



Define this parameter

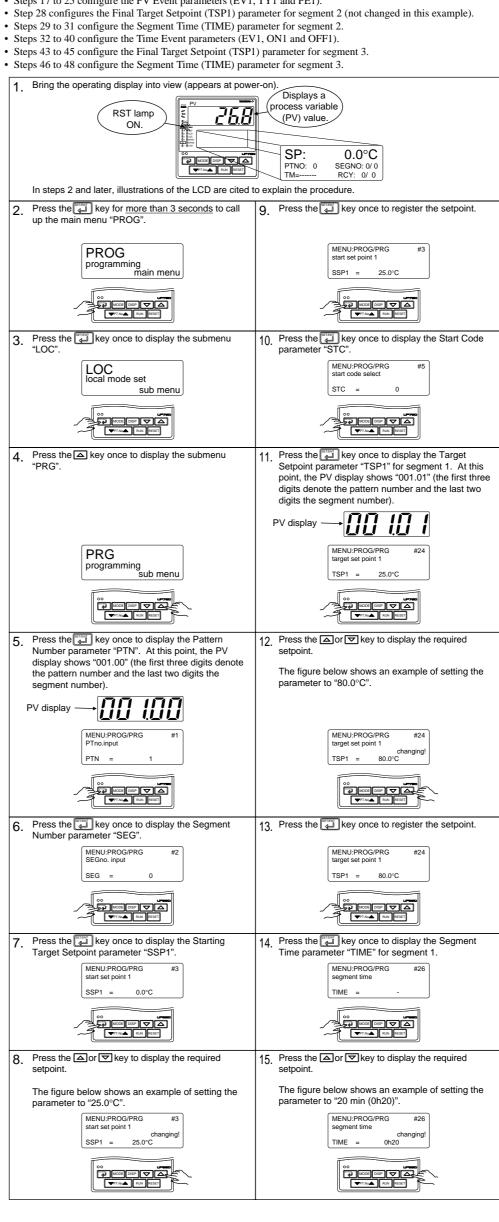
MOTE

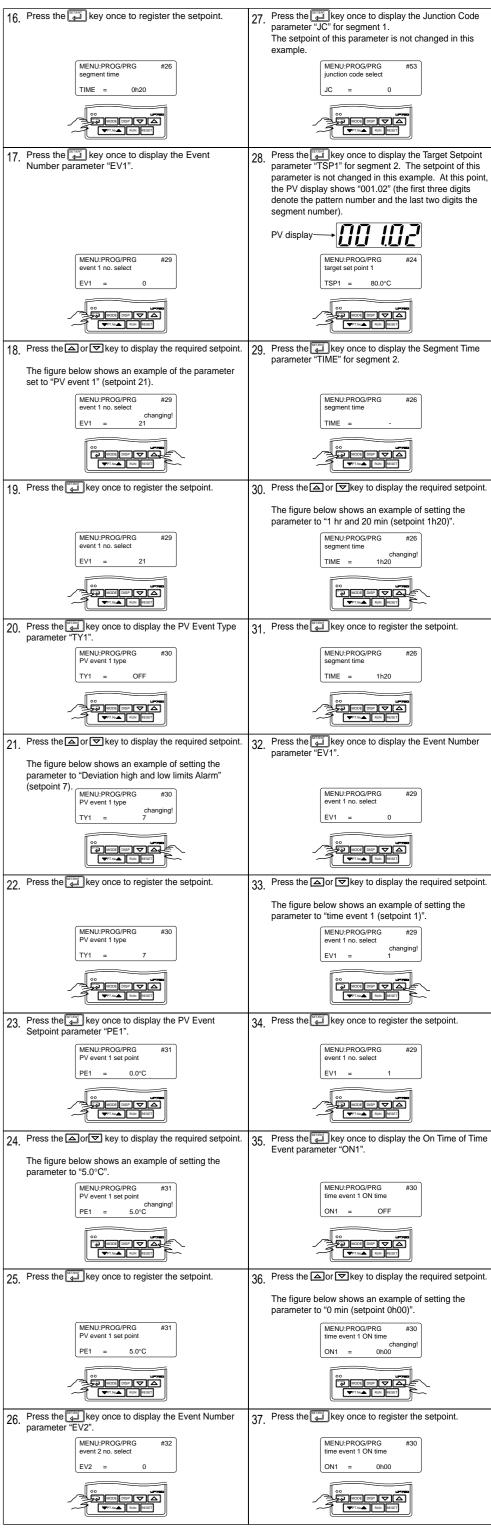
Before creating the program, reverify the Maximum Value of PV Input Range (RH1), Minimum Value of PV Input Range (RL1), Program Time Unit (TMU), and Segment Setting Method (SEG.T) parameters. If the setting of the setup parameter "SEG.T" is changed, the program patterns created and stored so far will be all cleared (initialized) !! Be careful

The programming example given in this manual includes the following steps.

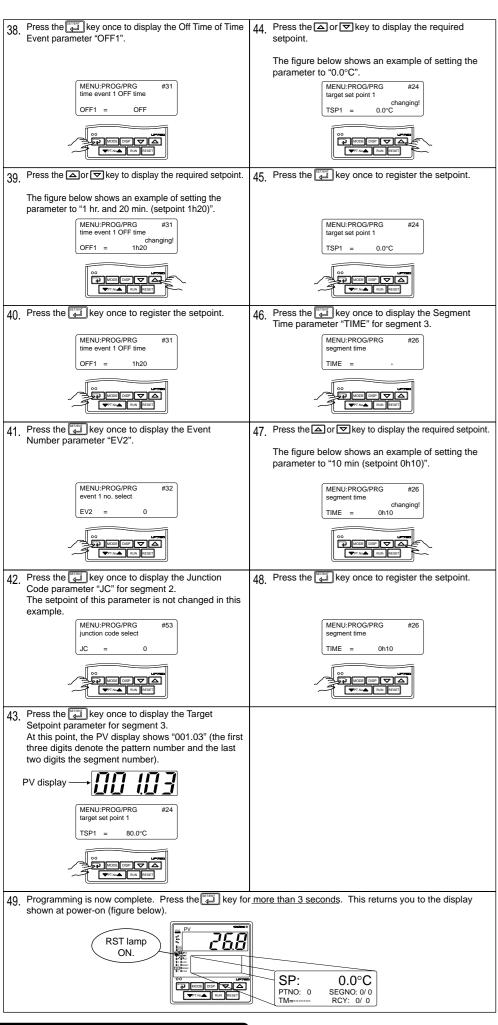
- Step 5 selects the program pattern number (PTN).
- $\bullet \ \ Steps\ 7\ to\ 9\ configure\ the\ parameter\ Starting\ Target\ Setpoint\ (SSP1)\ (so\ that\ the\ program\ starts\ from\ 25^{\circ}C).$
- Steps 11 to 13 configure the Final Target Setpoint (TSP1) parameter for segment 1.
- Steps 14 to 16 configure the Segment Time (TIME) parameter for segment 1. • Steps 17 to 25 configure the PV Event parameters (EV1, TY1 and PE1).

- Steps 32 to 40 configure the Time Event parameters (EV1, ON1 and OFF1).



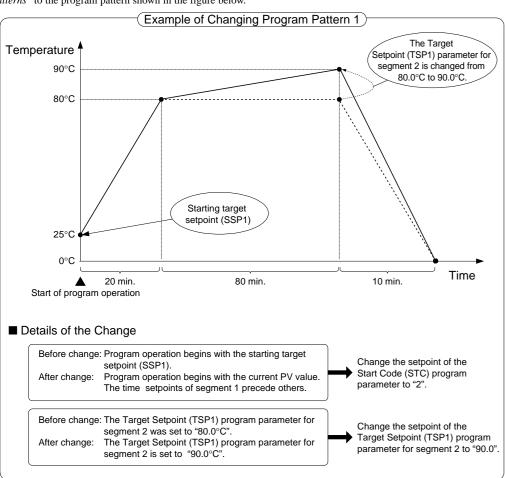


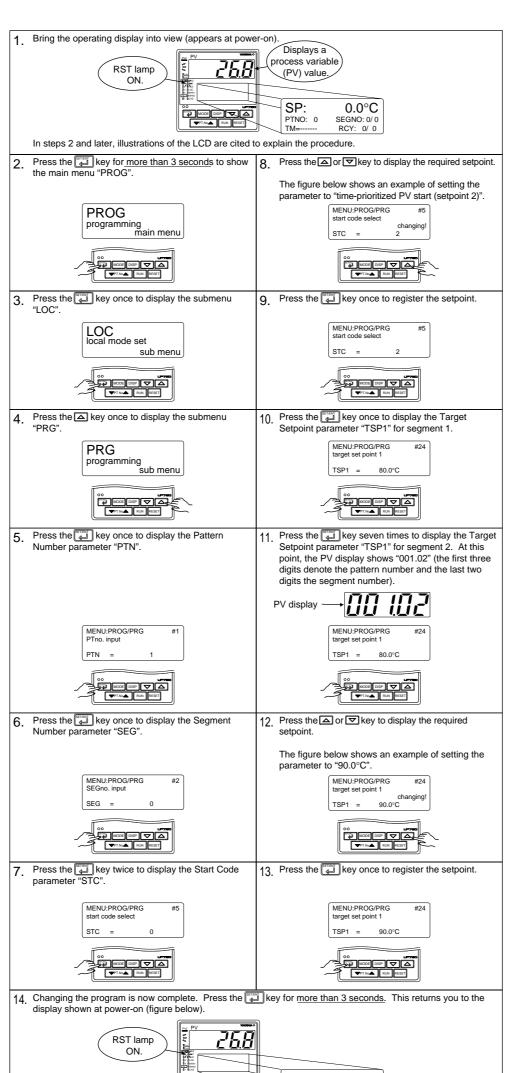
IM 05E01B02-03E (1)



4. Changing Program Patterns

The following operating procedure describes an example of changing the program pattern created in "3. Creating Program Patterns" to the program pattern shown in the figure below.





display shown at power on (ligure below).						
	RST lamp ON.	SP: 0.0°C PTNO: 0 SEGNO: 0/0 TM= RCY: 0/0				
Error Indicati	on at Program Pattern Cre	eation and Editing				
Error code	Error information	Cause of error				

Error code	Error information	Cause of error
0	No error	Normal end
01	Pattern creadtion or editing is disable during program operation.	Adding, deleting, or copying of the program pattern, segment, or event was excuted during program or local operation.
02	Pattern number error Only when using communication (The error code is stored in register B0005.)	The specified pattern number does not exist. Pattern numbers : 1 to 300
03	Segment number error Only when using communication (The error code is stored in register B0105.)	The specified segment number does not exist. Segment numbers: 1 to 99
11	Pattern information read error Only when using communication (The error code is stored in register B0005.)	Pattern read was attempted during pattern read. Pattern read was excuted when the parameters in "PRG" and "EDIT" program parameter submenus are displayed on t LCD.
12	Pattern information write error Only when using communication (The error code is stored in register B0005.)	Pattern wirte was attempted during pattern wirte. Pattern write was excuted when t parameters in "PRG" and "EDIT" program parameter submenus are displayed on t LCD.
21	Segment read error Only when using communication (The error code is stored in register B0105.)	Segment read was attempted during pattern read. Segment read was excuted whe the parameters in the "PRG" and "EDIT" program parameter submenus are display on the LCD.
22	Segment write error Only when using communication (The error code is stored in register B0105.)	The total number of segments exceeded 3000.
23	Segment insert error	During program operation, the total number of segments exceeded 300 or number a pattern exceeded 99, and therefore a new segment cannot be register or added. The specified segment is missing.
24	Segment delete error	Any segment cannot be deleted during program operation. The specifed segment missing.
25	Exceeded segment count error	The number of segments exceeded 3000.
31	Pattern copy error Only when using communication (The error code is stored in register B0065.)	No pattern is present at the source or patterns already exist at the destination.
32	Pattern source specification error	No pattern is present at the source or program operation is being excuted when the source of pattern copy is specified.
33	Pattern destination specification error	Patterns already exist at the destination.
41	Pattern delete errror	At pattern delete operation, specified pattern does not exist or program operation is being excuted.
51	Event write error Only when using communication (The error code is stored in register B0105.)	The number of events exceeded 4000. Or the number of remaining events is less than 8. (Wirte is disabled when remaining settable events are less tha 8)

Operation Modes

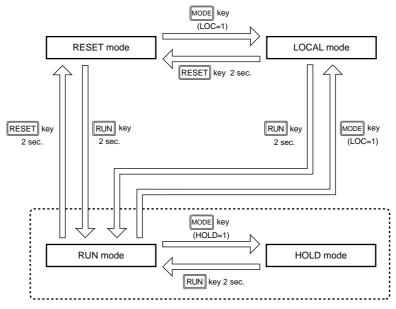
The UP750 has the following four types of operation modes:

- RUN (program operation start) mode
- HOLD (program operation hold) mode
- LOCAL (local operation) mode
- RESET (program operation stop) mode

The operation modes switching function and the control state for each mode are described below.

■ Operation Modes Switching Function

Operation modes RUN, HOLD, LOCAL, and RESET can be switched as described below.



RUN (program operation start) mode

The controller executes the control operation using the program pattern.

Pressing the RUN key on the controller's front panel starts a control operation using the selected program pattern, which can also be started by means of an external contact input or communication. The PRG indicator lamp on the front panel

HOLD (program operation hold) mode

The controller temporarily interrupts the program operation

Pressing the MODE key on the front panel temporarily interrupts the program operation, which can also be interrupted by means of an external contact input or communication. The HLD indicator lamp on the front panel is lit in Hold mode.

RESET (program operation stop) mode

The controller stops the program operation.

Pressing the RESET key on the front panel stops the program operation, which can also be stopped by means of an external contact input or communication. The RST indicator lamp on the front panel is lit in RESET mode, and all event functions are turned off.

LOCAL (local operation) mode

The controller executes the local control operation

Selecting the LOCAL operation using the MODE key on the front panel starts the local control operation, which can also be started by means of an external contact input or communication. The LOC indicator lamp on the front panel is lit in

■ Control Status

The control status of each operation mode for UP750 is described below.

Operation Mode and Control Status

Operation mode	Target setpoint	Control output	Applicabe key operation
RESET	0%	Preset output.	Program patern selection.Program operation starting.Local operation starting
LOCAL	Setpoint for local-mode operation (LSP)	AUTO: Result of control computation. MAN: Manipulated output.	LSP modification Output value modification (in MAN mode) RESET of operation Program operation starting
RUN	Target setpoint for each segment	AUTO: Result of control computation. MAN: Manipulated output.	Output value modification (in MAN mode) RESET of operation LOCAL operation starting HOLD mode
HOLD	Setpoint when the mode is changed to HOLD, or setpoint in HOLD mode modified by key operation in the case of soak segment.	AUTO: Result of control computation. MAN: Manipulated output.	Output value modification (in MAN mode). Segment remaining time modification (in the case of soak segments). RESET of operation LOCAL operation starting Program operation starting

Auto-tuning Function

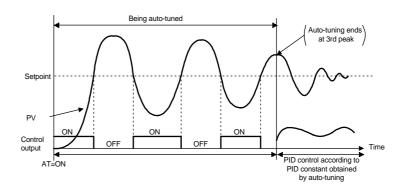
The auto-tuning function is used to have the controller measure process characteristics and automatically set the most appropriate PID constant. This function cannot be used for on/off control. As the function is started, control outputs are temporarily varied in steps and the responses are used for computing the proper PID constant - this is called a limited-cycle method.

The auto-tuning function should not be applied to the following processes:

- · Control processes with quick response such as flow control or pressure control
- Processes where even temporary output on/off results in inconvenience
- Processes where a large output change at control element results in inconvenience • Processes where variations in PV may exceed an allowable range, adversely affecting product quality.

Operating parameter AT

Description	Setpoint	TIP
Disable auto-tuning	OFF	Factory-set default
Perform auto-tuning on the specified PID group	1 to 8	When PID setpoint is switched using segment-PID, setpoints 1 to 8 are not effective.
Perform auto-tuning to all PID groups	9	Only availale for zone-PID



Auto-tuning function

■ Auto-tuning in Segment-PID Control

When auto-tuning is performed for segment-PID, the most proper PID constant can be obtained for the current target setpoint. The obtained PID constant is saved to the set PID constant parameter. When PID number 2 is set for segment 1 and AT=1 is executed, for example, obtained PID constant is saved as PID number 2.

• The auto-tuning parameter (AT) setpoints, its corresponding tuning point, and the tuned PID group number for "segment-PID" control (zone-PID selection parameter ZON is set at "0") are:

AT setpoint	Tuning point (SP at which auto-tuning is performed)	Tuned PID group number
1		
2		
3		
4	Currrent target setpoint (SP) at the starting of auto-tuning	PID number assigned for the
5		segment being used.
6		
7		
8		

Auto-tuning in Zone-PID Control

When auto-tuning is performed for zone-PID with the parameter AT set between 1 and 8, the optimum PID constants are obtained by using the current target setpoint value at the start of auto-tuning as a tuning point. The obtained PID values are saved as PID parameters for the PID number of the specified auto-tuning number. For example, if AT=2 is executed in zone 1, which is controlled with 1.PID parameters, the obtained PID constants will be saved as 2.PID parameters.

On the other hand, when auto-tuning is performed with parameter AT=9, the optimum PID constants for all the group numbers in use are obtained automatically, using the median value of each set reference point as tuning point. For example, the following points will be the tuning points.

• Median value of "the minimum value of PV input range" and "reference point 1"

• Median value of "reference point 1" and "reference point 2"

• Median value of "reference point 2" and "the maximum value of PV input range"

Since auto-tuning is performed progressively by processing to successive reference points, reference points 2 to 6 should be set so that the temperature during auto-tuning does not rise above the maximum limit for the controlled process. If there are any unused reference points, set them at the same value as the maximum value of the PV input range.

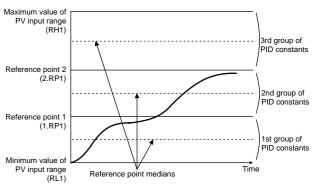
In heating/cooling control, when a certain zone is set for on/off control (proportional band parameter, n.P or n.Pc, is set at "0") however, auto-tuning skips that zone and proceeds to the next zone.

When controlling equipment such as heating furnaces, the PV input range must be set at a proper value (for example, setting room-temperature as the minimum value) when:

• The gap between reference point 1 and the minimum value of PV input range is large.

• The gap between the top reference point and the maximum value of the PV input range is large.

The figure below is the example of setting two reference points



Auto-tuning in Zone-PID Control (when AT=9)

• The auto-tuning parameter (AT) setpoints, corresponding tuning points and tuned PID group numbers for "zone-PID" control (zone-PID selection parameter ZON is set at "1") are:

AT setpoint Tuning point (SP at which auto-tuning is performed)

A i Setpoint	runing point (SF at which auto-tuning is performed)	Tuned FID group number
1	Currrent target setpoint (SP) at the starting of auto-tuning	1
2	Currrent target setpoint (SP) at the starting of auto-tuning	2
3	Currrent target setpoint (SP) at the starting of auto-tuning	3
4	Currrent target setpoint (SP) at the starting of auto-tuning	4
5	Currrent target setpoint (SP) at the starting of auto-tuning	5
6	Currrent target setpoint (SP) at the starting of auto-tuning	6
7	Currrent target setpoint (SP) at the starting of auto-tuning	7
8	Currrent target setpoint (SP) at the starting of auto-tuning	8
9 (AUTO)	Median of each zone	1 to 8

IM 05E01B02-03E (2)

IM 05E01B02-04E

Model UP750 REEN **Program Controller User's Manual for Single-loop Control Program Parameters**

YOKOGAWA •

2nd Edition: Jul 1, 2001

Yokogawa M&C Corporation

This manual briefly explains the functions of program parameters. In addition, it contains a program pattern setup chart. Completely fill in the chart before you set a program in the UP750 program controller.

Contents

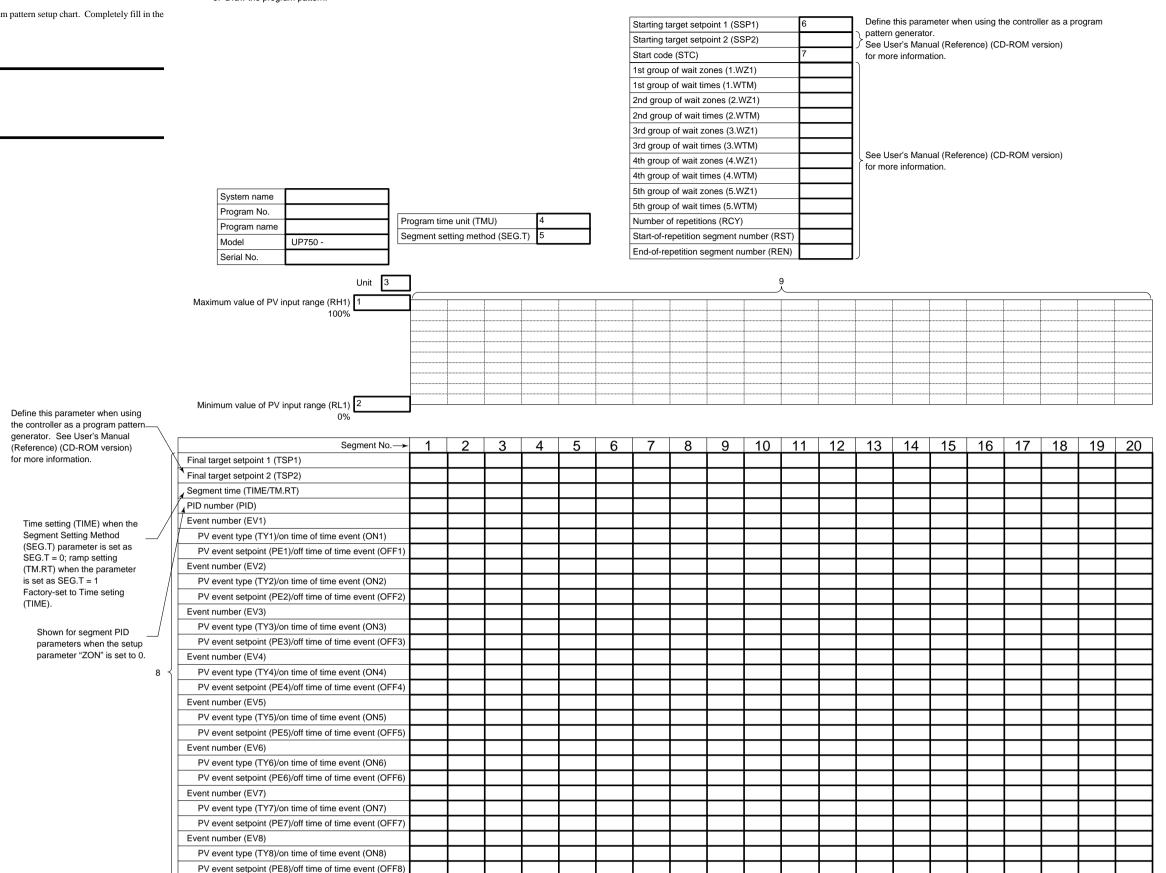
- 1. Program Pattern Setup Charts
- 2. Program Parameter Map
- 3. Lists of Program Parameters 4. Explanation of Program Functions

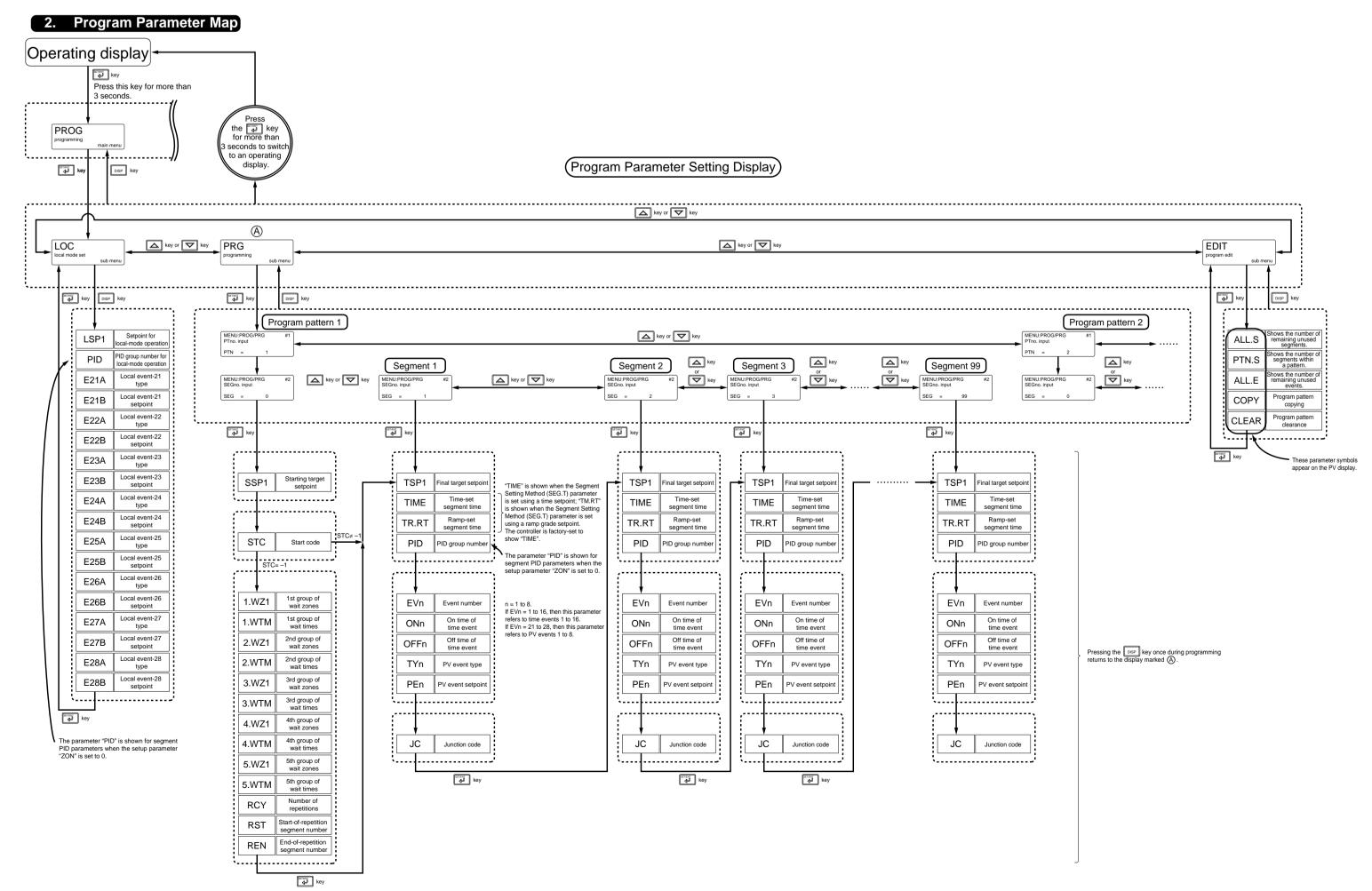
1. Program Pattern Setup Charts

For details on how to use the program pattern setup chart, see "1. Overview of Program Patterns," and "2. Example of Program Pattern Setup Charts," in Programming User's Manual You can register as many as 300 program patterns with the UP750 controller. Create as many copies of the chart as necessary. First fill in the fields with bold-face borders in the order from number 1 to number 9. Then, input the data into the controller.

- 1. Maximum value of PV input range: Setpoint of the "Maximum Value of PV Input Range (RH1)" setup parameter
- 2. Minimum value of PV input range: Setpoint of the "Minimum Value of PV Input Range (RL1)" setup parameter 3. PV input unit: Setpoint of the "PV Input Unit (UNI1)" setup parameter
- 4. Program time unit: Setpoint of the "Program Time Unit (TMU)" setup parameter
- 5. Segment setting method: Setpoint of the "Segment Setting Method (SEG.T)" setup parameter
- 6. Starting target setpoint: Setpoint of the "Starting Target Setpoint (SSP1)" program parameter
- 7. Start code: Setpoint of the "Start Code (STC)" program parameter 8. Final target setpoint, Segment time, Events (PV event and Time event), and Junction code: Setpoint of each program parameter
- 9. Draw the program pattern.

Junction code (JC)





Parameters of program pattern 1

3. Lists of Program Parameters

Local Setpoint Parameters

Located in: Main menu = PROG · Submenu = LOC

Parameters relating to PV or program setpoints should all be set in real numbers. For example, use temperature values to define program setpoints and PV event setpoints for temperature input.

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
LSP1	Setpoint for local-mode operation	0.0 to 100.0% of PV input range	0.0% of PV input range		
PID	PID group number for local-mode operation	Shown for segment PID parameters when the setup parameter ZON is set to 0. This parameter is factory-set so as not to appear. 1: Uses the 1st group of PID parameters. 2: Uses the 2nd group of PID parameters. 3: Uses the 3rd group of PID parameters. 4: Uses the 4th group of PID parameters. 5 to 8: Likewise, selecting these numbers uses the 5th to 8th groups of PID parameters.	1		
E21A	Local event-21 type	OFF, 1 to10, 28 to 31 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action) 3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation high limit (de-energized, no stand-by action) 7: Deviation high/low limits (energized, no stand-by action) 8: Deviation within high/low limits (energized, no stand-by action) 9: PV high limit (de-energized, no stand-by action) 10: PV low limit (de-energized, no stand-by action) 8: See **Parameter **Map User's **Manual** for details on other alarm types.	OFF		
E21B	Local event-21 setpoint	PV/SP alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Output value alarm: -5.0 to 105.0%	PV/SP high limit alarm: 100.0% of PV input range. Deviation alarm: 0.0% of PV input range span. Other PV/SP low limit alarms: 0.0% of PV input range. Output high limit alarm: 100.0% Output low limit alarm: 0.0%		
E22A	Local event-22 type	Same as the E21A parameter.	Capation initial damage of the		Ref.5.2(9)
E22B	Local event-22 setpoint	Same as the E21B parameter.			1
E23A	Local event-23 type	Same as the E21A parameter.			
E23B	Local event-23 setpoint	Same as the E21B parameter.			
E24A	Local event-24 type	Same as the E21A parameter.			
E24B	Local event-24 setpoint	Same as the E21B parameter.			
E25A	Local event-25 type	Same as the E21A parameter.			
E25B	Local event-25 setpoint	Same as the E21B parameter.			1
E26A	Local event-26 type	Same as the E21A parameter.			
E26B	Local event-26 setpoint	Same as the E21B parameter.]
E27A	Local event-27 type	Same as the E21A parameter.			1
E27B	Local event-27 setpoint	Same as the E21B parameter.			1
E28A	Local event-28 type	Same as the E21A parameter.			1
E28B	Local event-28 setpoint	Same as the E21B parameter.			1

Program Parameters (Parameters for Setting the Conditions of Program Operation

Use the program pattern setup chart discussed in "1. Program Pattern Setup Charts" of this manual, to record your setpoints of program

Located in: Main menu = PROG ; Submenu = PRG

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
PTN	Pattern number	Program pattern 1 2: Program pattern 2 Program pattern 3 4 to 300: Likewise, specifying these numbers sets their corresponding program pattern numbers.			
SEG	Segment number	O: Shows parameters for setting the starting target setpoint, start code, etc. 1 to 99: Specify the corresponding segment numbers. Specify 0 when creating a program for the first time.	0		
SSP1	Starting target setpoint	0.0 to 100.0% of PV input range	0.0% of PV input range		
STC	Start code	-1: Shows parameters for setting the wait and repeat actions. 0: Program operation begins with the starting target setpoint . 1: Ramp-prioritized PV start (program operation begins with the PV value by giving priority to the ramp of segment 1) 2: Time-prioritized PV start (program operation begins with the PV value by giving priority to the time of segment 1) TIP: The option -1 is not a setpoint.	0		Ref.5.2.(1)

Program Parameters (Parameters for Setting the Wait and Repeat Actions) The parameters listed below are shown when the Start Code (STC) parameter is set to "-1".

Located in: Main menu = PROG; Submenu = PRG

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
1.WZ1	1st group of wait zones	OFF: No function 0.0 to 10.0% of PV input range span	OFF		
1.WTM	1st group of wait times	OFF: No function 0.01 to 99.59 (hour, minute or minute, second) Use the TMU setup parameter to set the time unit.	OFF		
2.WZ1	2nd group of wait zones	Same as the 1st group of wait zones.			
2.WTM	2nd group of wait times	Same as the 1st group of wait times.			
3.WZ1	3rd group of wait zones	Same as the 1st group of wait zones.			Ref.5.2(4)
3.WTM	3rd group of wait times	Same as the 1st group of wait times.			
4.WZ1	4th group of wait zones	Same as the 1st group of wait zones.			
4.WTM	4th group of wait times	Same as the 1st group of wait times.]
5.WZ1	5th group of wait zones	Same as the 1st group of wait zones.]
5.WTM	5th group of wait times	Same as the 1st group of wait times.]
RCY	Number of repetitions	0 to 999: The controller repeats the segment specified by the RST and REN parameters as many times as defined by this parameter. CONT: The controller indefinitely repeats the segment specified by the RST and REN parameters.	0		Pof 5 2/2)
RST	Start-of-repetition segment number	1≤RST≤REN≤99	1		Ref.5.2(6)
REN	End-of-repetition segment number		1		

* The User Setting column in the table below is provided for the customer to record setpoints

The Target Item in CD-ROM column in the table below provided references from User's Manual (Reference) (CD-ROM version) which describes items in more detail and items that are not contained in this manual.

Program Parameters (Parameters for Setting the Final Target Setpoints and Segment

Located in: Main menu = PROG; Submenu = PRG

Parameter Symbol	Name of Parameter	Setting Range and Description	User Setting	Target Item in CD-ROM	
TSP1	Final target setpoint	The final target setpoint of each segment.			
TIME	Time-set segment time	Time setpoint: - (unregistered) 0.00 to 99.59 ("hour, minute" or "minute, second") Without a time setpoint, it is not possible to create programs.			
TM.RT	Ramp-set segment time	For ramp segments (ramp setpoint): - (unregistered), 0.0 to 100.0% of PV input range span per hour or minute For soak segments (time setpoint): 0.00 to 99.59 ("hour, minute" or "minute, second") Without a time setpoint or a ramp grade setpoint, it is not possible to create programs.			
PID	Segment PID group number	This parameter is shown for segment PID parameters when the setup parameter "ZON" is set to 0. This parameter is factory-set so as not to appear. 1 to 8	1		Ref.5.1(2)

Program Parameters (Parameters for Setting the Event Action)

You can set a maximum of eight units each for the parameters listed below for each individual segment. Located in: Main menu = PROG; Submenu = PRG

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
2: Time event 2 (terminal n 3: Time event 3 (terminal n 4: Time event 4 (terminal n 5 to 16: Time events 5 to 16 sion user s manual for details 21: PV event 1 (terminal n 22: PV event 2 (terminal n 23 to 28: PV events 3 to 8		1: Time event 1 (terminal numbers (3)-(5)) 2: Time event 2 (terminal numbers (3)-(5)) 3: Time event 3 (terminal numbers (3)-(6)) 4: Time event 4 (terminal numbers (3)-(6)) 5 to 16: Time events 5 to 16 (see the CD-ROM version user s manual for details on the terminal number) 21: PV event 1 (terminal numbers (6)-(7)) 22: PV event 2 (terminal numbers (6)-(7)) 23 to 28: PV events 3 to 8 (see the CD-ROM version user s manual for details on the terminal	0		Ref.3.4(5)
ONn	On time of time event	OFF: Unused. 0.00 to 99.59 (hour, minute or minute, second)	OFF		Ref.3.4(6)
OFFn	Off time of time event	OFF: Unused. 0.00 to 99.59 (hour, minute or minute, second)	OFF		Kei.3.4(6)
TYn	PV event type	OFF, 1 to 10, 28 to 31 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action) 3: Deviation high limit (energized, no stand-by action) 4: Deviation how limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action) 7: Deviation high/low limits (energized, no stand-by action) 8: Deviation within high/low limits (energized, no stand-by action) 9: PV high limit (de-energized, no stand-by action) 10: PV low limit (de-energized, no stand-by action) See List of PV Event Types and Instrument Alarm Types in Parameter Map User's Manual for details on other alarm types.			Ref.3.4(5)
PEn	PV event setpoint	PV/SP alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input range span Output value alarm: -5.0 to 105.0%	PV/SP high-limit alarm: 100.0% of PV input range. Deviation alarm: 0.0% of PV input range span. Other PV/SP low limit alarms: 0.0% of PV input range. Output high limit alarm: 100.0% Output low limit alarm: 0.0%		

Program Parameters (Junction Code Parameter) Located in: Main menu = PROG; Submenu = PRG

Name of Parameter Setting Range and Description Initial Value Target Item Paramete User Setting The junction code (JC) basically used to specify the condition for moving from one segment to the next and the intra-segme operating condition.

0: Switching for continuation 1: Hold-on switching (the controller holds the end-of-segment Ref.5.2(3) setpoint when the segment is completed, to perform control).

2: Local-mode end (the controller switches to a local setpoint Ref.5.2(4) when the segment is completed).

11 to 15: Wait during switching between segments (see the CD-ROM version user's manual).

21 to 25: Wait within a segment interval (see the CD-ROM Ref.5.3(6) rersion user's manual). INSERT: Allows a segment to be added to the end of a specifie segment.

DELETE: Allows a specified segment to be deleted. 101 to 199:Linked to the pattern 1 to 99.
For example, when setting "102" in JC of the final segment, the operation for pattern 2 is started after the end of pattern < Notes at pattern-link >
- Parameter STC is available.

Program Parameters (Parameters for Editing Programs) Located in: Main menu = PROG; Submenu = EDIT

PV event and time event are reset.
 Parameter SST is not available.

Symbol on PV display	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
ĀĻĻ5 (ĀLL.S)	Number of remaining unused segments.	Read-only			Ref.5.3(1)
PTN.S)	Number of segments within a pattern.				Ref.5.3(2)
ALL.E)	Number of remaining unused events.				Ref.5.3(3)
COPY)	Program pattern copying	Specify the numbers of the source-of-copying program pattern and target-of-copying program pattern. (1 to 300)			Ref.5.3(4)
CLEAR)	Program pattern clearance	Specify the number of the program pattern to be cleared. (1 to 300)			Ref.5.3(5)

4. Explanation of Program Functions

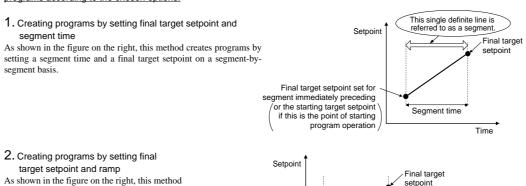
Programming

You can create programs using either method 1 or 2 described below. The controller is factory-set to "method 1". To create programs using method 2, change the setpoint of the SEG.T (Segment Setting Method) setup parameter to "1". Before you begin programming, determine whether your programs are created using the time unit of "hour and minute" or "minute and second." The controller is factory-set to the "hour and minute" time unit. To create programs using the "minute and second" time unit, change the setpoint of the TMU (Program Time Unit) setup parameter to "mm:ss".

Controller Settings

	Setpoint of SEG.T (Segment Setting Method) Setup Parameter
Time setting (method 1)	0 (factory-set default)
Ramp setting (method 2)	1

Choose the desired method and unit from the two programming methods and time unit options discussed above. Then, create programs according to the chosen options.



Controller Settings

creates programs by setting a final target setpoint

and a ramp grade on a segment-by-segment ba-

sis. Define the ramp grade as the amount of

change in the setpoint per hour or per minute.

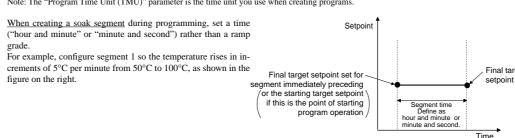
	Setpoint of TMU (Program Time Unit) Setup Parameter
When changing the setpoint linearly over an hour	hh:mm (factory-set default)
When changing the setpoint linearly over a minute	mm:ss

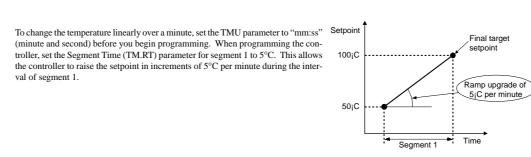
Final target setpoint set for

egment immediately preceding or the starting target setpoint

if this is the point of starting

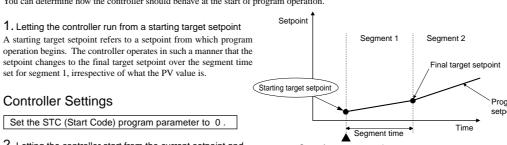
Note: The "Program Time Unit (TMU)" parameter is the time unit you use when creating programs





■ Controller Behavior at the Start of Program Operation

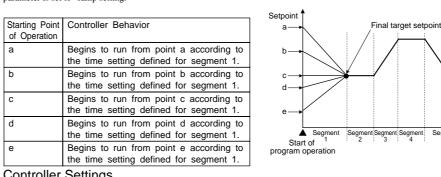
You can determine how the controller should behave at the start of program operation.



Start of program operation

2. Letting the controller start from the current setpoint and

run according to time settings defined for segment 1 This method is not available if the SEG.T (Segment Setting Method) parameter is set to "ramp setting



Controller Settings

Set the STC (Start Code) program parameter to 2.

3. Letting the controller start from the current setpoint and run according to ramp settings defined for segment 1 of the created program

Starting Point of Operation	Controller Behavior	Setpoint a
а	Begins to run from point C1 (ignores the time setting defined for segment 1).	b B1
b	Begins to run from point C1 (ignores the time setting defined for segment 1).	Program setpoint
С	Begins to run from point C1 (ignores the time setting defined for segment 1).	d — D1
d	Begins to run from point D1 according to the preset ramp setting (the time setting defined for segment 1 is reduced).	e E1
е	Begins to run from point E1 according to the preset ramp setting.	Start of 1 2 3 4 5 Time Start of 1 2 3 4 5 Time program operation

Controller Settings

Set the STC (Start Code) program parameter to 1.

■ PID Switching (Zone PID)

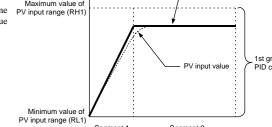
 $The \ UP750 \ offers \ two \ methods \ of \ PID \ switching. \ One \ of \ the \ methods \ is \ to \ automatically \ switch \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ between \ groups \ of \ PID \ constants \ according \ according \ between \ groups \ of \ PID \ constants \ according \$ to the temperature zone. The other method is to automatically switch between groups of PID constants on a segment-by-segment basis. This paragraph explains the method of switching between groups of PID constants according to the temperature zone. You can set a maximum of seven temperature zones. When shipped from the factory, the UP750 is configured so that it operates in zone 1 only and uses only one group

When One Group of PID Constants

Is Used (factory-set default) As shown in the figure on the right, the controller uses one PV input range (RH1

group of PID constants over the range from the minimum value to the maximum value of the PV input range.

Controller Settings Configure the 1st group of PID constants (1.P, 1.I and 1.D operating parameters).



3rd group of

2nd group of

Selection of PID Constants when the Control Range Is Split into Three

As shown in the figure on the right, three zones are set for the controller to automatically switch from one group of PID constants to another. Two zones can also be set for the controller to Reference point 1 switch between two groups of PID constant

[1] The controller uses the 1st group of PID constants if the PV input value is within the zone set off by the minimum value of the PV input range and reference point 1.

PV input range (RL [2] The controller uses the 2nd group of PID constants if the PV input value is within the zone set off by reference point 1 and reference point 2.

maximum value of the PV input range.

[3] The controller uses the 3rd group of PID constants if the PV input value is within the zone set off by reference point 2 and the

Controller Settings

Define the ramp grade as the

amount of change in the setpoint per hour or per minute.

· Splitting the control range into two zones

- To split the control range into two zones, define reference point 1 (i.e., the 1.RP1 setup parameter). Define the 1st and 2nd groups of PID constants (i.e., the 1.P, 1.I and 1.D operating parameters for the 1st group and the 2.P, 2.I and 2.D
- operating parameters for the 2nd group). Splitting the control range into three zones
- · To split the control range into three zones, define reference points 1 and 2 (i.e., the 1.RP1 and 2.RP1 setup parameters)
- Define the 1st, 2nd and 3rd groups of PID constants (i.e., the 1.P, 1.I and 1.D operating parameters for the 1st group, the 2.P, 2.I and 2.D operating parameters for the 2nd group and the 3.P, 3.I and 3.D operating parameters for the 3rd group).

Minimum value of

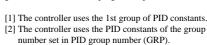
Selecting PID Constants According to the Deviation

constants only by a deviation from a program setpoint. PV input range (RI The other method is to use a reference point, as discussed earlier, as well as a deviation from a program setpoint, to switch between groups of PID constants

PID constants can be selected according to the deviation in two ways. One method is to select a group of PID

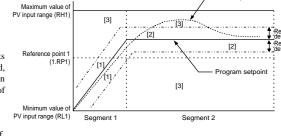
Method 1:

As shown in the figure on the right, the controller selects the PID constants of the group number set in PID group number (GRP) if the PV input value goes beyond the given deviation from the program setpoint



Method 2:

As shown in the figure on the right, the controller selects an appropriate group of PID constants for each zone and. if the PV input value goes beyond the given deviation from the program setpoint, selects the PID constants of the group number set in PID group number (GRP).



[1] The controller uses the 1st group of PID constants if the PV input value is both within the zone set off

by the minimum value of the PV input range and reference point 1 and within the given reference deviation bandwidth

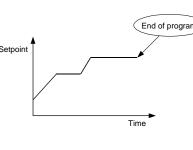
[2] The controller uses the 2nd group of PID constants if the PV input value is both within the zone set off by reference points 1 and the maximum value of the PV input range, and within the given reference deviation bandwidth.

[3] The controller uses the PID constants of the group number set in PID group number (GRP).

■ Retaining the End-of-Program State (Holdmode End)

This function keeps the controller in the same state as when program operation was completed. When in hold operation, the controller retains its states of control output and event output. To cancel hold operation, use either key operation or external contact input. When the hold operation is cancelled, the control output is set to 0% or OFF, and the event output is set to OFF.

To retain the end-of-program state, set the Junction Code program parameter of the segment in question to "1"



■ Suspending the Progress of a Program (Wait Function)

zone and a wait time, until any deviation is cancelled. A wait zone is a deviation bandwidth from which the degree of PV input tracking is $judged. \ A \ wait \ time \ is \ the \ length \ of \ time \ that \ elapses \ until \ the \ PV \ input \ enters \ the \ wait \ zone. \ The \ program \ progresses \ if \ the \ PV \ input \ fails \ to$ re-enter the wait zone within the wait time.

When the program is in wait state, the time setpoints of Segment Time and Time Event parameters temporarily cease to be passed. At this point, the output based on the Time Event parameter is retained

See User's Manual (Reference) (CD-ROM version) for more information

Model UP750 REEN **Program Controller User's Manual for Single-loop Control** Operations

IM 05E01B02-05E



2nd Edition: Jul 1, 2001

This manual describes key entries for operating the controller. For operations using external contact inputs, see "6. Terminal Wiring Diagrams" in Installation User's Manual . If you cannot remember how to carry out an operation during setting, press the DISP key no more than four times. This brings you to the display (operating display) that appears at power-on.

Contents

- Monitoring-purpose Operating Displays Available during Operation
- 2. Performing/Canceling Auto-tuning
- 3. Setting PID Manually
- 4. Selecting Program Pattern Number (PT.No)
- 5. Switching between RUN and RESET Modes
- 6. Switching between AUTO and MAN 7. Manipulating Control Output during Manual Operation
- 8. Enabling/Disabling Hold Mode of Program Operation 9. Changing Program Setpoints when in Hold Mode
- 10. Executing "Advance" Function
- 11. Switching to Local-mode (LOCAL) Operation
- 12. Changing Setpoints during Local-mode Operation 13. Troubleshooting

For description of Operation Mode, see the back of **Programming User's Manual**

1. Monitoring-purpose Operating Displays Available during Operation

The monitoring-purpose operating displays available during operation include those for single-loop control and those for single-loop heating/cooling control

The Process Variable (PV) display always displays the value of PV input.

■ Operating Displays for Single-loop Control

SP Display

On the Setpoint display (LCD), the controller displays the current setpoint (SP), the program pattern number (PTNO) selected, the segment number (SEGNO) for which operation is in progress, the number of segments included in the selected program pattern, the remaining time of the segment for which operation is in progress, the current number of repetitions (RCY), and the total sum of repetitions.

Target SP Display

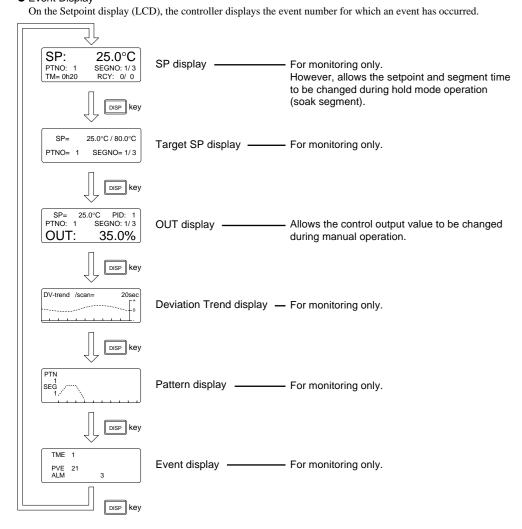
On the Setpoint display (LCD), the controller displays the current setpoint (SP) and final target setpoint (TSP), the program pattern number (PTNO) selected, the segment number (SEGNO) for which operation is in progress, the number of segments included in the selected program pattern, the program pattern name (only displayed when setting the program pattern name using an optional parameter setting tool (model: LL100-E10)).

On the Setpoint display (LCD), the controller displays the current target setpoint (SP), the PID number (PID) being used, the program pattern number (PTNO), the segment number (SEGNO) for which operation is in progress, and the number of segments included in the selected program pattern, and the control output value (OUT).

Deviation Trend Display

On the Setpoint display (LCD), the controller displays the deviation trend. Pattern Display

On the Setpoint display (LCD), the controller displays the selected program pattern. Event Display



■ Operating Displays for Single-loop Heating/cooling Control

SP Display

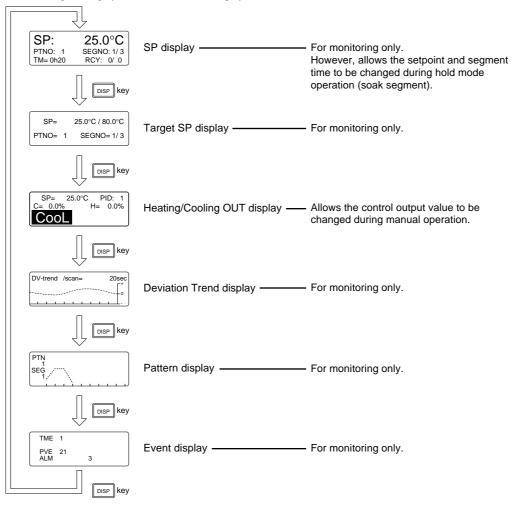
On the Setpoint display (LCD), the controller displays the current target setpoint (SP), the program pattern number (PTNO) selected, the segment number (SEGNO) for which operation is in progress, the number of segments included in the selected program pattern, the remaining time of the segment (TM) for which operation is in progress, the current number of repetitions (RCY), and the total sum of repetitions.

Target SP Display

On the Setpoint display (LCD), the controller displays the current target setpoint (SP) and final target setpoint (TSP), the program pattern number (PTNO) selected, the segment number (SEGNO) for which operation is in progress, the number of segments included in the selected program pattern, the program pattern name (only displayed when setting the program pattern name using an optional parameter setting tool (model: LL100-E10)).

- - On the Setpoint display (LCD), the controller displays the current target setpoint (SP), the PID number (PID) being used, and the heating-side (HEAT) and cooling-side (COOL) control output values.
 - Deviation Trend Display

 - On the Setpoint display (LCD), the controller displays the deviation trend.
 - On the Setpoint display (LCD), the controller displays the selected program pattern. Event Display
 - On the Setpoint display (LCD), the controller displays the event number for which an event has occurred.



2. Performing/Canceling Auto-tuning

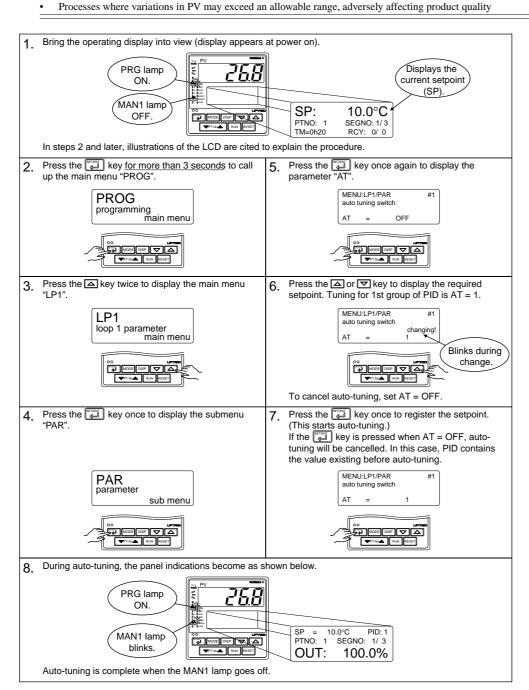
Perform auto-tuning when you have finished creating program patterns. Make sure the controller is in program (RUN) mode and in automatic (AUTO) mode before carrying out auto-tuning. See "5. Switching between RUN and RESET Modes" to change to RUN or "6. Switching between AUTO and MAN" to change to AUTO.

PID constants are obtained by using the current program setpoint value at the start of auto-tuning. See the back of **Programming User's Manual** for more information.

₩ NOTE

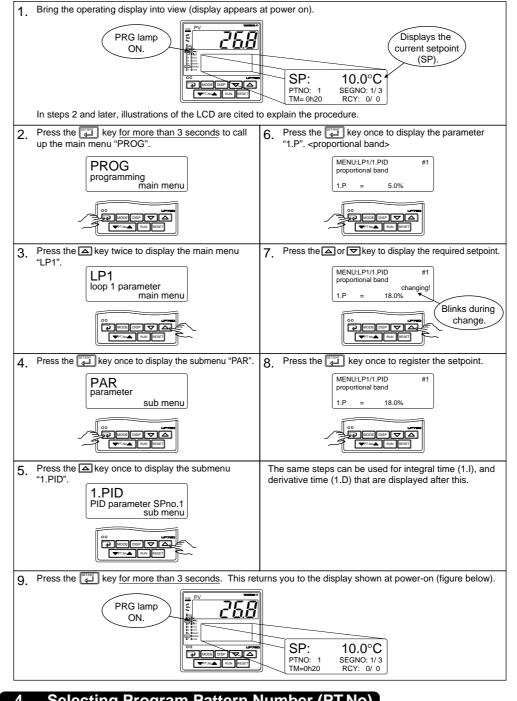
When on-off control is being used, auto-tuning cannot be carried out. Moreover, do not perform auto-tuning when controlling any of the following processes.

- Control processes with quick response such as flow control or pressure control
- Processes where even temporary output on/off results in inconvenience
- Processes where a large output change at control element results in inconvenience



3. Setting PID Manually

If you know the values to be set or if suitable PID constants cannot be obtained by auto-tuning, follow the procedure below

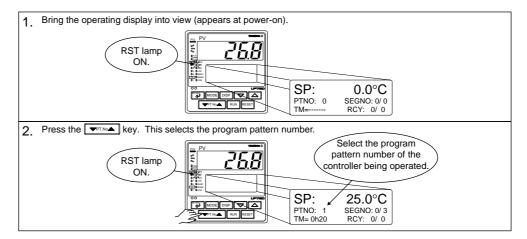


4. Selecting Program Pattern Number (PT.No)

The following operating procedure selects program pattern 1. A program pattern number can only be selected when the controller is in a RESET mode.

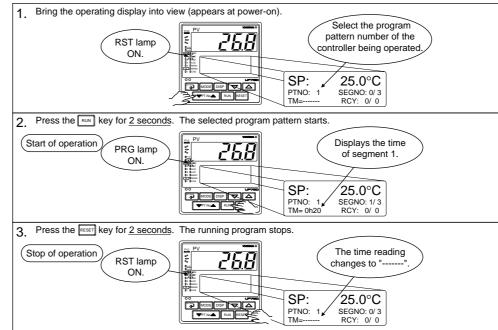


If contact input, which is used to select between program pattern numbers, is on, any program pattern number cannot be selected by key operation.



5. Switching between RUN and RESET Modes

The following operating procedure switches the RUN mode and the RESET mode



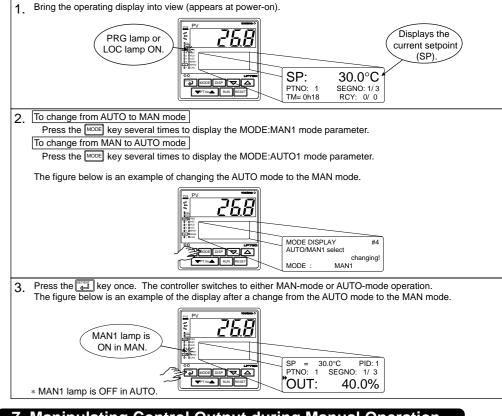
When in the RESET mode, the controller provides the following PV input

Value of process variable Control output | Preset output value (factory-set to 0%) Event output OFF, if there is any event.

6. Switching between AUTO and MAN



If AUTO and MAN have been switched using contact input, when the contact input is ON, switching between AUTO and MAN cannot be achieved by keystroke.

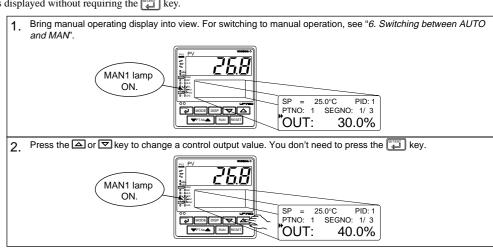


7. Manipulating Control Output during Manual Operation



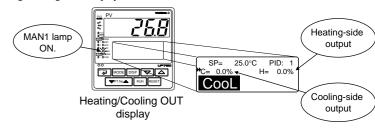
Control output cannot be changed if the controller is in the RESET mode. In this case, the preset output value (operating parameter PO) will be output.

A control output value is linked with a display value changed using the 🔻 or 🖾 key. Note that the control output changes as displayed without requiring the key.



■ Manipulating the Control Output during Heating/Cooling Control

Showing the Heating/Cooling OUT display.

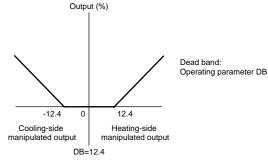


 Controller behavior and control output manipulation when the dead band is positive The following is an example when the DB parameter is set at 12.4%.

heating-side output (H =) decreases.

Consequently, both the heating-side and cooling-side outputs change to 0.0%. If you keep the ▼ key held down longer, you enter the state of manipulating the cooling-side output, and its value begins to increase.

Inversely, if you hold down the \(\begin{align*} \begin{align*} \text{key} & \text{with the cooling-side output under manipulation (i.e., heating-side output H = g-side output (C =) decreases. Consequently, both the heating-side and cooling-side you keep the 🖾 key held down longer, you enter the state of manipulating the heating-side output, and its value begins to

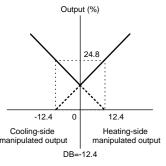


Change in manipulated output when the dead band is positive

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Controller behavior and control output manipulation when the dead band is negative The following is an example when the DB parameter is set at -12.4%.

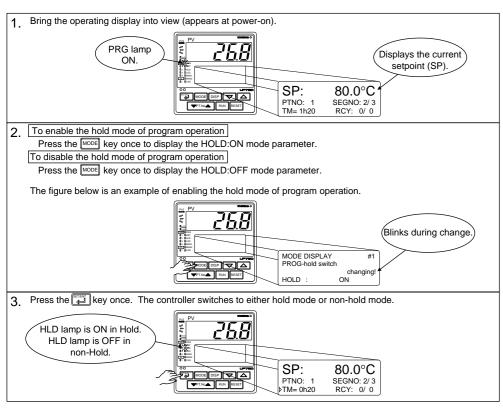
heating-side output (H =) decreases. If the output H falls below 24.8%, the cooling-side output C begins to increase from 0.0%. If you keep the key held down longer and the output C rises above 24.8%, the output H goes to 0.0% and you enter the state of manipulating the cooling-side output.



Change in manipulated output when the dead band is negative

8. Enabling/Disabling Hold Mode of Program Operation ng/disabling the hold mode of program operation should be done when the controller is in operation

The following operating procedure is an example of setting program operation in the hold mode.



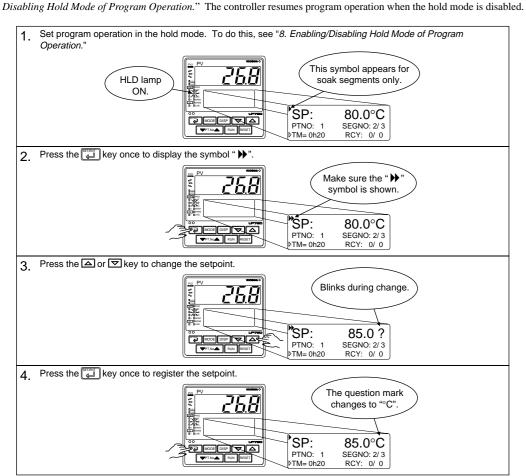
* Other operating procedures for disabling the hold mode:

[1] Press the RUN key for two seconds during hold-mode operation. In this case, the controller resumes program operation. [2] Execute the "advance" function during hold-mode operation. In this case, the segment is advanced.

9. Changing Program Setpoints when in Hold Mode

The following operating procedure changes program setpoints when program operation (in soak segment) is put in the hold

When you have finished changing the setpoints, disable the hold mode of program operation as instructed in "8. Enabling/



How to Change the Target Setpoint in the Segment being in Operation

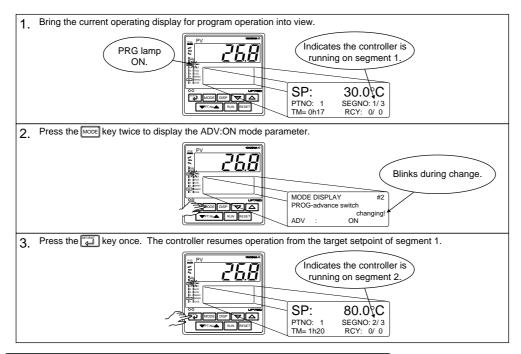
1. Set the program operation in the hold mode.

- 2. Change the target setpoint of the corresponding segment of operation program on the program parameter
- 3. When the hold mode of program operation is disabled, the controller resumes the control toward the changed target setpoint.

Note: To perform the above, specify "programming by setting segment times" for segment setting method (SEG.T setup parameter), and do not change the hold SP and hold time on the operating display in HOLD mode.

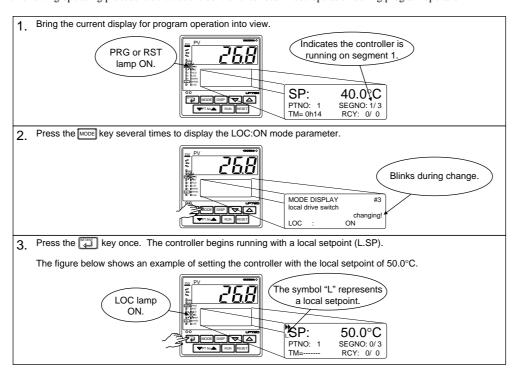
10. Executing "Advance" Function

The following operating procedure advances the controller from segment 1 to segment 2. If you execute the "advance" function during hold-mode operation, the hold mode is disabled.



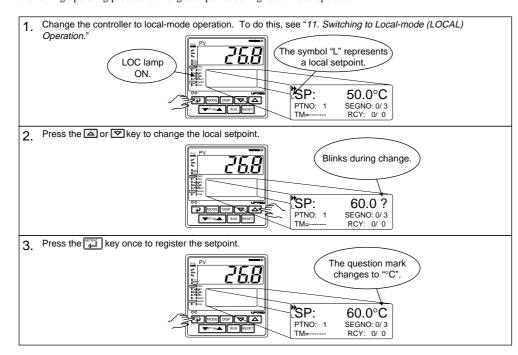
11. Switching to Local-mode (LOCAL) Operation

The controller can be switched to local-mode operation when it is in program operation or in a RESET mode. The following operating procedure switches the controller to local-mode operation during program operation.



12.Changing Setpoints during Local-mode Operation

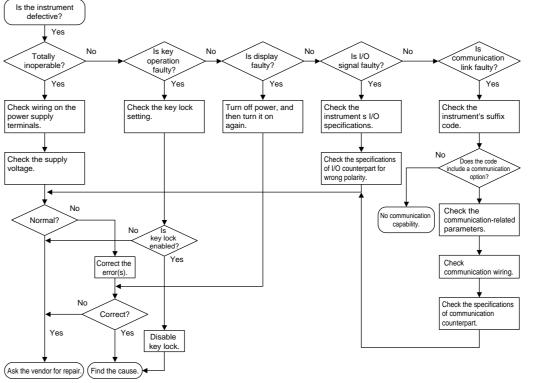
The following operating procedure changes setpoints during local-mode operation



13. Troubleshooting

■ Troubleshooting Flow

If the operation display does not appear after turning on the controller's power, follow the measures in the procedure below. If a problem appears complicated, contact our sales representative.



IMPORTANT

Take note of the parameter settings when asking the vendor for repair

■ Errors at Power On

The following table shows errors that may be detected by the fault diagnosis function when the power is turned on.

Display position	Error indication (on PV display unit)	Description of error	PV	Control output	Alarm output	Retransmission output	Communication	Remedy	
	E000	Faulty RAM	Ness		055	00/			
B1/	E001	Faulty ROM	None	or OFF		OFF 0% or less		F10	
PV indicating	E002	System data error	Undefined			Undefined		Faulty Contact us	
LED		Faulty calibration value	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)	Normal action (out of accuracy)		for repair.	
LCD	Error code (Note) (See description below.)	Parameter error	Normal action	0% or less or OFF	Normal action	Normal action	Normal operation	Check and set the initialized parameter.	

An error code is displayed in the event of an error, according to its type.

An error code is a two-digit figure in which a combination of 6 bits of on and off is converted into a decimal number. The following shows the relationship between each bit and parameter to be checked for abnormality

Bit No.	6	5	4	3	2	1	0
Parameter to be checked	Operation mode/output	Operating parameters	Setup parameters	Range data	UP mode	Custom computing data	Calibration data

be as follows:

For example, if	an error	occurs w	ith the op	erating p	arameter	and calib	ration da	ta, the en	ror code will l
Bit No.	-	6	5	4	3	2	1	0	
Error Code	-	2 ²	2 ¹	2 ⁰	2 ³	2 ²	21	2 ⁰	
			2			, –		1	
				0.15	nint displa	2 1	← Erro	or code 2	1 is displayed

■ Possible Errors during Operation

The following shows possible errors occurring during operations.

Display position (Note)	Error indication (on PV display unit)	Description of error	PV	Control output	Alarm output	Retransmis- sion output		Remedy
	Displays "RJC" and PV alternately	RJC error	Measured with RJC=OFF	Normal action				Faulty
	E300	ADC error	105%	In AUTO:				Contact us for repair.
3	B.OUT	PV burnout error	Dependent on the BSL parameter Up-scale: 105% Down-scale: -5%	Preset value output In MAN: Normal action		Normal action		Check wires and sensor.
	OVER or -OVER	Excessive PV Out of -5 to 105%	-5% or 105%	Normal action	Normal action		Normal action	Check process.
	E200	Auto-tuning failure (Time-out)		Action with PID existing before auto-tuning				Check process. Press any key to erase error indication.
		Feedback resistor burnout	Normal action	Stopped		Stopped		Check the feedback resistor.
2	Blinking dot in the most left on LCD	Faulty communication line		Normal action		Normal action		Check wires and communication parameters, and make resetting. Recovery at normal receipt
1	Decimal point at right end lights.	Runaway (due to defective power or noise)	Undefined	0% or less or OFF	OFF	0% or less	Stopped	Faulty if power off/on does not reset start the unit. Contact us for repair.
-	All indications off	Power off	None					Check for abnormal power.

1: PV indicating LED display

3: Display showing the PV of the loop in which the error has been caused.

■ Remedies if Power Failure Occurs during Operations

The operation status and remedies after a power failure differ with the length of power failure time:

• Instantaneous power failure of 20 ms or less

A power failure is not detected. Normal operation continues.

 Power failure of about 2 seconds or less The following show effects caused in "settings" and "operation status."

Alarm action	Continues. Alarm with standby function will enter standby status.
Setting parameter	Set contents of each parameter are retained.
Auto-tuning	Cancelled.
Control action	Action before power failure continues.

• Power failure of more than about 2 seconds

The following show effects caused in "settings" and "operation status."

Alarm action	Continues. Alarm with standby function will enter standby status.						
Setting parameter	Set contents	of each parameter are retained.					
Auto-tuning	Cancelled.						
Control action	Differs with s	Differs with setting of setup parameter "R.MD" (restart mode).					
	R.MD settin	g Control action after recovery from power failure					
	CONT	Continues action before power failure. (Factory-set default)					
	MAN	Outputs preset output value (PO) as control output and continues action set before power failure in MAN mode. For heating/cooling control, starts action from heating-side output value and cooling-side output value of 50% of control computation output.					
	RESET	Outputs preset output value (PO) as control output and continues action set before power failure in AUTO mode. For heating/cooling control, starts action from heating-side output value and cooling-side output value of 50% of control computation output.					

■ Troubleshooting When the Controller Fails to Operate Correctly

If your control tasks are not successful, check the preset parameters and controller wiring before concluding the controller to be defective. The following show some examples of troubleshooting you should refer to in order to avoid the possibility of

• The controller does not show the correct measured input (PV).

• The UP750 controllers have a universal input.

The type of PV input can be set/changed using the parameter "IN1". At this point, the controller must be wired correctly according to the selected type of PV input. Check the wiring first if the controller fails to show the correct PV value. To do this, refer to Initial Settings User's Manual

With the parameters "RH1", "RL1", "SDP1", "SH1" and "SL1", it is possible to scale the input signal and change its number of decimal places. Also check that these parameters are configured correctly.

The controller does not provide any control output or the control output does not change at all.

• The UP750 controllers have a universal output.

The type of control output can be set/changed using the parameter "OT1".

At this point, the controller must be wired correctly according to the selected type of control output. Check the wiring first if the controller provides no control output. To do this, refer to "6. Terminal Wiring Diagrams," in Installation User's Manual

With the parameters "OH" and "OL", it is possible to set/change the high and low limits of control output. The control output may not change at all, however, because of restrictions on these parameters. Also check the restrictions on these

• The control output can only be changed when the controller is in the MAN mode.

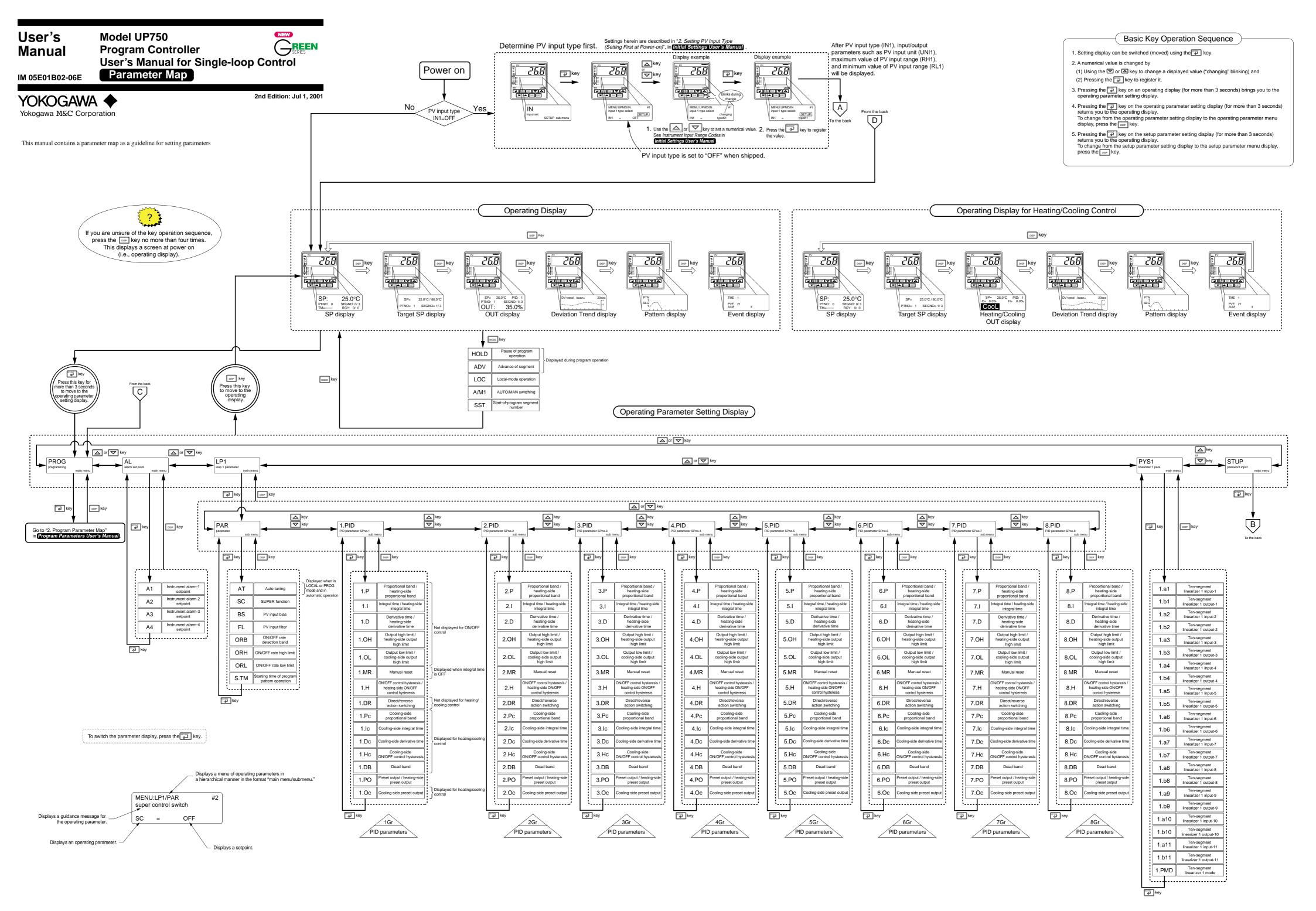
If the MAN lamp is off (i.e., the controller is in the AUTO mode), you cannot change the control output using key

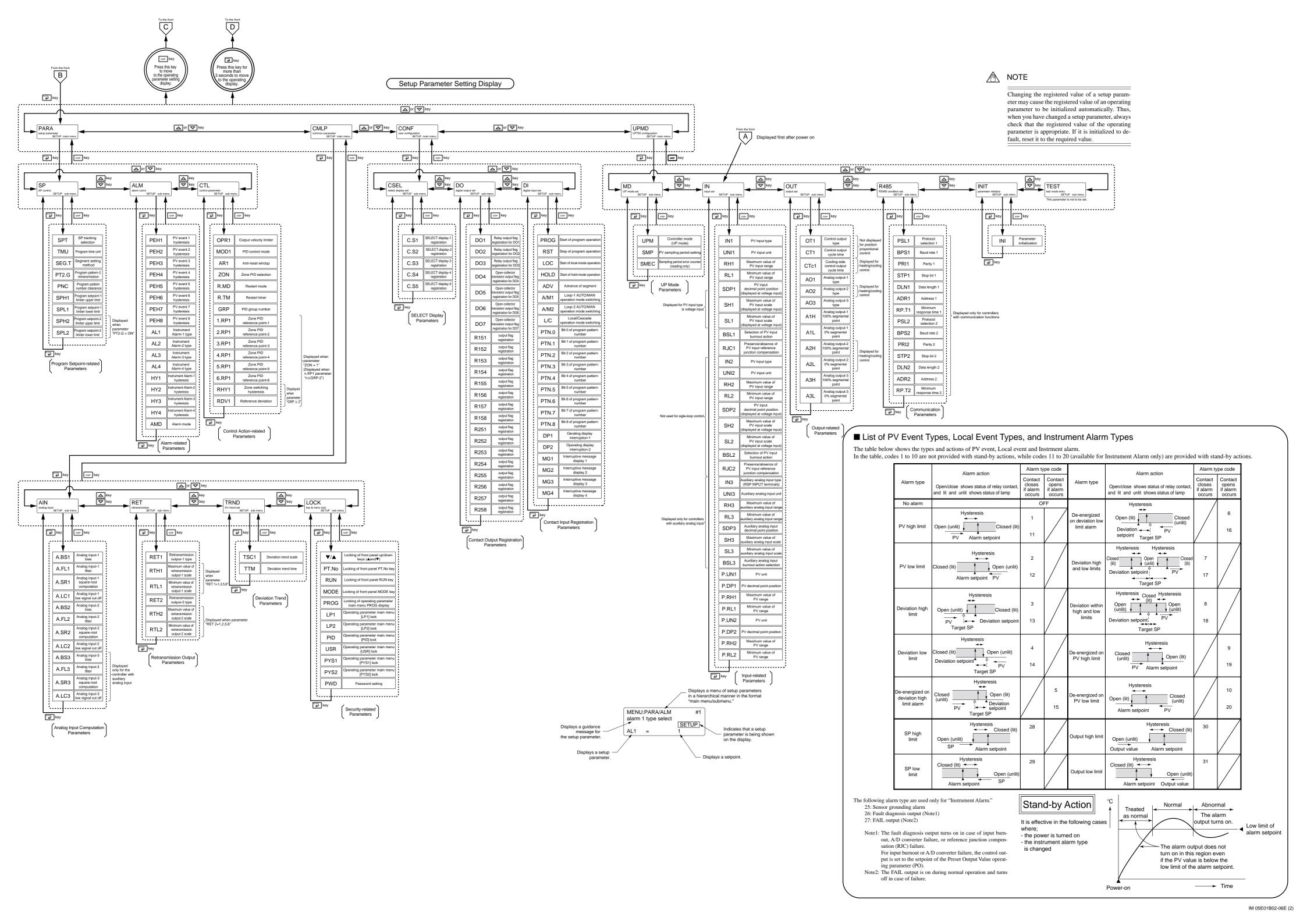
• The control output does not change soon after the target setpoint (SP) has been

• If this happens, check the setpoint of the parameter "MOD1". In cases where fixed-point control is selected as the PID control mode (MOD1 = 1), tracking based on the I-term works to prevent the control output from changing suddenly even if the target setpoint (SP) is varied.

The control output therefore may appear to be working incorrectly at first; however it gradually adapts itself to the new

IM 05E01B02-05E (2)





Model UP750 REEN **Program Controller User's Manual for Single-loop Control Parameters**

IM 05E01B02-07E



2nd Edition: Jul 1, 2001

This manual describes the functions of parameters briefly. In addition, each parameter table has a "User Setting" column, where you can record your setpoints when setting them in the controller.

> * Parameters relating to PV or program setpoints should all be set in real numbers. For example, use temperature values to define program setpoints and PV event setpoints for temperature input.

■ Operation Mode Parameters

Located in: MODE key (MODE key on the instrument's front panel)

	, (
Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
HOLD	Pause of program operation	Set as "HOLD = ON" to enable the hold mode of program operation.			
ADV	Advance of segment	nt Set as "ADV = ON" to advance from the current segment to the next segment.			
LOC	Local-mode operation	Set as "LOC = ON" to switch from program operation or RESET mode	to local-mod	le operation.	Ref.5.2(9)
A/M1	AUTO/MAN switching	To switch between AUTO and MAN: To switch to AUTO mode, display "MODE: AUTO1", then press the To switch to MAN mode, display "MODE: MAN1", then press the			_
SST	Start-of-program segment number	1 to 99 Program operation begins with the segment whose number is specified by this parameter.	1		_

■ Operating Parameters ■

• Instrument Alarm Setting Parameters

Located in: Main menu = AL

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
A1	Instrument alarm-1 setpoint	Allows alarm action to be set irrespective of the program.	PV high limit/SP high limit alarm: 100.0% of PV input range		
A2	Instrument alarm-2 setpoint	PV alarm / SP alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV	Deviation alarm: 0.0% of PV input range span Other PV/SP low limit		Def 2 4(4)
А3	Instrument alarm-3 setpoint	input range span Output alarm: -5.0 to 105.0%	alarm: 0.0% of PV input range Output high limit		Ref.3.4(1)
A4	Instrument alarm-4 setpoint		alarm: 100.0% Output low limit alarm: 0.0%		

Operation-related Parameters

Located in: Main menu = LP1; Submenu = PAR

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial	Value	User Setting	Target Item in CD-ROM
AT	Auto-tuning	OFF: No auto-tuning 1: Auto-tuning for 1st group of PID 2: Auto-tuning for 2nd group of PID 3: Auto-tuning for 3rd group of PID 4: Auto-tuning for 4th group of PID 5 to 8: Perform auto-tuning on a group basis in the same way as 1 to 4 9: Performs auto-tuning to all groups 1 to 8.	OFF			_
SC	"SUPER" function	OFF: Disable 1: Overshoot suppressing function Suppresses overshoots generated by abrupt changes in the target s by disturbances. 2: Hunting suppressing function (Stable mode) Suitable to stabilize the state of control when the load varies greatly the target setpoint is changed. Enables to answer the wider characteristic changes compared with Response mode. 3: Hunting suppressing function (Response mode) Enables quick follow-up and short converging time of PV for the cha target setpoint. Note: Use "SUPER" function (SC) 2 or 3 in PID control or PI control. "SUPER" function 2 or 3 is not available in the following control: 1) ON/OFF control 2) P control (control for proportional band only) 3) PD control (control for proportional band and derivative item only) 4) Heating/cooling control Do not use hunting suppressing function when control process with res such as flow or pressure control.	, or	OFF		Ref.2.1(5) Ref.2.1(6)
BS	PV input bias	-100.0% to 100.0% of PV input range span Used to correct the PV input value.	0.0% of input ra span			Ref.1.1(1)
FL	PV input filter	OFF, 1 to 120 sec Used when the PV input value fluctuates.	OFF			
ORB	ON/OFF rate detection band	0.0 to 100.0% of PV input range span	1.0% of input ra span	nge		
ORH	ON/OFF rate high limit	ORL + 1 digit to 105.0%	100.0 %	6		Ref.3.4(4)
ORL	ON/OFF rate low limit	-5.0% to ORH - 1 digit	0.0%			
S.TM	Starting time of program pattern operation	0.00 to 99.59 ("hour, minute" or "minute, second") The controller begins control when the specified time has passed after power-on.	0.00			Ref.5.2(2)

PID-related Parameters

Located in: Main menu = LP1; Submenu = 1.PID

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
1.P	Proportional band/Heating- side proportional band (in heating/cooling control)	0.1 to 999.9% of PV input range In heating/cooling control: 0.0 to 999.9% (heating-side on/off control applies when 0.0)	5.0%		
1.l	Integral time Heating-side integral time (in heating/cooling control)	OFF, 1 to 6000 sec.	240 sec.		
1.D	Derivative time Heating-side derivative time (in heating/cooling control)	OFF, 1 to 6000 sec.	60 sec.		
1.OH	Output high limit Heating-side output high limit (in heating/cooling control)	-5.0 to 105.0% Heating-side limiter in heating/cooling control: 0.0 to 105.0% (1.OL < 1.OH)	100% Heating/cooling control: 100.0%		
1.OL	Output low limit Cooling-side output high limit (in heating/cooling control)	-5.0 to 105.0% Cooling-side limiter in heating/cooling control: 0.0 to 105.0% (1.0L < 1.0H) SD (shutdown): Set in manual operation in 4-20 mA control output. Output is 0 mA.	0.0% Heating/cooling control: 100.0%		Ref.2.1(3)
1.MR	Manual reset	-5.0 to 105.0% (enabled when integral time 1.1 is OFF) The manual reset value equals the output value when PV = SP is true. For example, if the manual reset value is 50%, the output value is 50% when PV = SP becomes true.	50.0%		

* The User Setting column in the table below is provided for the customer to record setpoints.

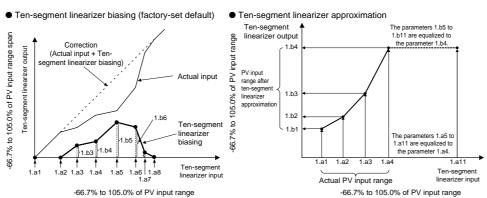
The column Target Item in CD-ROM in the table below provides references from User's Manual (Reference) (CD-ROM Version) which describes items in more detail and items that are not contained in this manual.

1.H	ON/OFF control hysteresis Heating-side ON/OFF control hysteresis (in heating/cooling control)	In ON/OFF control: 0.0 to 100.0% of PV input range span In heating/cooling control: 0.0 to 100.0% Hysteresis can be set in the program setpoint when the controller is performing ON/OFF control.	ON/OFF control: 0.5% of PV input range span Heating/cooling control: 0.5%	
		Output ON/OFF action (Program setpoint) On Off PV value		_
1.DR	Direct/reverse action switching	REVERSE: reverse action, DIRECT: direct action Control output 100% Reverse action OW Deviation (PV-SP)	REVERSE	Ref.2.1(1)
1.Pc	Cooling-side proportional band	0.0 to 999.9% of PV input range (Cooling-side ON/OFF control applies when 0.0)	5.0%	-
1.lc	Cooling-side integral time	OFF, 1 to 6000 sec.	240 sec.	_
1.Dc	Cooling-side derivative time	OFF, 1 to 6000 sec.	60 sec.	_
1.Hc	Cooling-side ON/OFF control hysteresis	0.0 to 100.0%	0.5%	_
1.DB	Dead band	In heating/cooling control: -100.0 to 50.0% • When performing heating/cooling control: When setting any positive value, there is region where none of the heating- and cooling-side output is presented; when setting any negative value, there is a region where both of the heatin- and cooling-side outputs are presented. When setting a value of zero, either the heating- and cooling-side output is provided.	3.0%	_
1.PO	Preset output/Heating- side preset output (in heating/cooling control)	-5.0 to 105.0% In heating/cooling control: Heating side 0.0 to 105.0% In RESET mode, fixed control output can be generated.	0.0%	Ref.2.1(8)
1.Oc	Cooling-side preset output	0.0 to 105.0% In RESET mode, cooling-side fixed control output can be generated.	0.0%	1.61.2.1(0)

If you are using two or more groups of PID parameters, use the following table									
Parameter	n=2	n=3	n=4	n=5	n=6	n=7	n=8		
n.P									
n.l									
n.D									
n.OH									
n.OL									
n.MR									
n.H									
n.DR									
n.Pc									
n.lc									
n.Dc									
n.Hc									
n.DB									
n.PO									

● Ten-segment Linearizer 1 Parameters Located in: Main menu = PYS1

-66.7% to 105.0% of PV input range



Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Iten in CD-ROM
1.a1	Ten-segment linearizer 1 input-1	-66.7% to 105.0% of PV input range	0.0% of PV input range		
1.b1	Ten-segment linearizer 1 output-1	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		
1.a2	Ten-segment linearizer 1 input-2	-66.7% to 105.0% of PV input range	0.0% of PV input range		
1.b2	Ten-segment linearizer 1 output-2	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		
1.a3	Ten-segment linearizer 1 input-3	-66.7% to 105.0% of PV input range	0.0% of PV input range		
1.b3	Ten-segment linearizer 1 output-3	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		
1.a4	Ten-segment linearizer 1 input-4	-66.7% to 105.0% of PV input range	0.0% of PV input range]
1.b4	Ten-segment linearizer 1 output-4	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Ref.1.1(2
1.a5	Ten-segment linearizer 1 input-5	-66.7% to 105.0% of PV input range	0.0% of PV input range]
1.b5	Ten-segment linearizer 1 output-5	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		
1.a6	Ten-segment linearizer 1 input-6	-66.7% to 105.0% of PV input range	0.0% of PV input range		
1.b6	Ten-segment linearizer 1 output-6	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		
1.a7	Ten-segment linearizer 1 input-7	-66.7% to 105.0% of PV input range	0.0% of PV input range		1
1.b7	Ten-segment linearizer 1 output-7	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		

1.a8	Ten-segment linearizer 1 input-8	-66.7% to 105.0% of PV input range	0.0% of PV input range	
1.b8	Ten-segment linearizer 1 output-8	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation	
1.a9	Ten-segment linearizer 1 input-9	-66.7% to 105.0% of PV input range	0.0% of PV input range	
1.b9	Ten-segment linearizer 1 output-9	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation	
1.a10	Ten-segment linearizer 1 input-10	-66.7% to 105.0% of PV input range	0.0% of PV input range	Ref.1.1(2)
1.b10	Ten-segment linearizer 1 output-10	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation	
1.a11	Ten-segment linearizer 1 input-11	-66.7% to 105.0% of PV input range	0.0% of PV input range	
1.b11	Ten-segment linearizer 1 output-11	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation	
1.PMD	Ten-segment linearizer 1 mode	Ten-segment linearizer biasing Ten-segment linearizer approximation	0	

■ Setup Parameters

Program Setpoint-related Parameters Located in: Main menu = PARA; Submenu = SP

					1
Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Iten in CD-ROM
SPT	SP tracking selection	OFF, ON Tracking is performed when the mode changes from program to Local (The local setpoint keeps track of the program setpoint.)	OFF		Ref.5.2(3
TMU	Program time unit	Sets the time unit of a program. hh:mm: hour, minute mm:ss: minute, second	hh:mm		
SEG.T	Segment setting method	Defines the method of programming. Note that changing the setpoint of this parameter deletes the program in question. 0: Programming by setting segment times 1: Programming by setting segment ramps	0		Ref.5.1(1
PT2.G	Program pattern-2 retransmission	The controller can serve as a program pattern generator. Thus, another program pattern can be created in addition to the control-purpose program pattern. Note that the segment time setpoints of the created program pattern are the same as those of the control-purpose program pattern. OFF: Not used. ON: Used.	OFF		Ref.2.2(2
PNC	Program pattern number clearance	The controller resets (clears) the program pattern number on the operating display to 0 at the end of program operation. OFF: Not cleared. ON: Cleared. (Set the program No. before reset program operation)	OFF		
SPH1	Program setpoint-1 limiter upper limit	Place limits on the program setpoints when the controller is in program operation.	100.0% of PV input range		
SPL1	Program setpoint-1 limiter lower limit	0.0% to 100.0% of PV input range. Note that SPL1 < SPH1	0.0% of PV input range		
SPH2	Program setpoint-2 limiter upper limit	Place limits on the program setpoints when the controller is in program operation.	100.0% of PV input range		
SPL2	Program setpoint-2 limiter lower limit	0.0% to 100.0% of PV input range. Note that SPL2 < SPH2	0.0% of PV input range		

Alarm-related Parameters

Located in: Main menu = PARA; Submenu = ALM

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
PEH1	PV event 1 hysteresis	0.0 to 100.0% of PV input range span Allows margins to be set for an PV event setpoint.	0.5% of PV input range		
PEH2	PV event 2 hysteresis	With the hysteresis settings, it is possible to prevent relays from chattering.	span		
PEH3	PV event 3 hysteresis	Hysteresis for PV high limit alarm Output Point of ON/OFF action (PV event setpoint)			
PEH4	PV event 4 hysteresis	On			Ref.3.4(3)
PEH5	PV event 5 hysteresis	Off			Ref.3.4(5)
PEH6	PV event 6 hysteresis	PV value			
PEH7	PV event 7 hysteresis				
PEH8	PV event 8 hysteresis				
AL1	Instrument alarm-1 type	OFF, 1 to 20, 25 to 31 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action)	1		
AL2	Instrument alarm-2 type	Deviation high limit (energized, no stand-by action) Deviation low limit (energized, no stand-by action) Deviation high limit (de-energized, no stand-by action)	2		
AL3	Instrument alarm-3 type	6: Deviation low limit (de-energized, no stand-by action) For other alarm types, see "■ List of PV Event Types and Instrument Alarm Types" in Parameter Map User's Manual.	1		Ref.3.4(1)
AL4	Instrument alarm-4 type		2		
HY1	Instrument alarm-1 hysteresis	0.0 to 100.0% of PV input range span Output alarm: 0.0 to 100.0%	0.5% of PV input range span		
HY2	Instrument alarm-2 hysteresis	Allows margins to be set for an alarm setpoint. With the hysteresis settings, it is possible to prevent relays from chattering. Hysteresis for PV high limit alarm Output Point of ON/OFF action	Output alarm: 0.5%		D (0.4(0)
HY3	Instrument alarm-3 hysteresis	Output Point of ONOFF action (Alarm setpoint)			Ref.3.4(3)
HY4	Instrument alarm-4 hysteresis	Off Hysteresis PV value			
AMD	Alarm mode	Allows the instrument alarm function to be enabled or disabled according to the operating condition. 0: Always active 1: Not active when in RESET mode 2: Not active when in RESET mode or manual operation	0		Ref.3.4(2)

Control Action-related Parameters Located in: Main menu = PARA; Submenu = CTL

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
OPR1	Output velocity limiter	OFF 0.1 to 100.0%/sec Can limit control output velocity	OFF		_
MOD1	PID control mode	Standard PID control (with output bump at SP change) Fixed-point control (without output bump at SP change) Choose "Fixed-point Control" when controlling pressure or flow rate.	0		Ref.2.1(2)
AR1	Anti-reset windup (Excess integration prevention)	AUTO, 50.0 to 200.0% The larger Setting, the sooner PID computation (integral computation) stops. Used when the control output travels up to 100% or down to 0% and stays at this point.	AUTO		Ref.2.1(4)
ZON	Zone PID selection	Segment PID Zone PID segment PID," allows PID constants to be selected for each segment. Segment PID," automatically selects PID constants according to the temperature range set in the given Reference Point parameter.	1		Ref.5.1(2)
R.MD	Restart mode	CONT: Continues action set before power failure. MAN: Starts from manual operation status RESET: Continues action set before power failure and starts computation from the preset output value.	CONT		_

D T14	Restart timer	0 to 10 sec.	0 sec.	
R.TM	Trootair timo	Sets time between power on and the instant where controller starts computation.	0 000.	
GRP	PID group number	Allows you to determine how many groups of setpoint, alarm and PID parameters the controller should show. 1: Show one set. 2: Show two sets. 3: Show three sets. 4: Show four sets. 5 to 8: Show as many groups of parameters as have been set.	8	
1.RP1	Zone PID reference point-1	0.0 to 100.0% of PV input range. Note that 1.RP1 ≦ 2.RP1 ≦ 3.RP1 ≦ 4.RP1 ≦ 5.RP1 ≦ 6.RP1. Sets reference points at which switching is carried out between groups of PID constants according to the given temperature zone. You can set	100.0% of PV input range	
2.RP1	Zone PID reference point-2	a maximum of six reference points and therefore a maximum of seven temperature zones.		
3.RP1	Zone PID reference point-3	The example below sets reference points 1 and 2 to provide 3 zones to switch PID constants automatically.		Ref.5.1(2)
4.RP1	Zone PID reference point-4	Maximum value of PV input range RH1 Setpoint The Controller is operated with the 3rd group of PID constants.		1.0.1(2)
5.RP1	Zone PID reference point-5	Reference point 2 2.RP1 Zone 2 The controller is operated with the 2nd group of PID constants.		
6.RP1	Zone PID reference point-6	Minimum value of PV input range RL1 Time Time Time Tone 1 Tone 1 The controller is operated with the 1st group of PID constants.		
RHY1	Zone switching hysteresis	0.0 to10.0% of PV input range span Allows hysteresis to be set for switching at a reference point.	0.5% of PV input range span	
RDV1	Reference deviation	Used to select a group of PID parameters according to a deviation from the given program setpoint. The controller uses the PID parameters of the number selected in PID group number (GRP) of PID parameters if the PV input falls outside the given deviation range. The following example shows a case when only the reference deviation is set without setting any reference point. The selected group of PID parameters is as follows. Since region 1 is within the deviation range, the controller uses the 1st group of PID parameters. Since region 1 is within the deviation range, the controller uses the PID parameters of the number selected in PID group number (GRP). Maximum value of PV input range Reference deviation (RDV1) seppoint range support range seppoint	OFF	

Analog Input Computation Parameters Located in: Main menu = CMLP; Submenu = AIN

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM			
A.BS1	Analog input-1 bias	Used to correct the PV input value beforehand. When in normal operation, use the PV Input Bias (BS) operating parameter. -100.0% to 100.0% of PV input range span	0.0% of PV input range span		Ref.1.1(6)			
A.FL1	Analog input-1 filter	OFF: Disable 1 to 120 sec.	OFF					
A.SR1	Analog input-1 square-root computation	Performs square-root computation for the PV input value. OFF: Do not compute the square root ON: Compute the square root	OFF		Ref.1.1(3)			
A.LC1	Analog input-1 low signal cutoff	0.0% to 5.0% The slope equals 1 at levels below the low-signal cutoff point.	1.0%					
A.BS2 Although not used in single-loop control, it is shown on the display.								
A.FL2	Although not used in single-loop control, it is shown on the display.							
A.SR2	Although not used in	single-loop control, it is shown on the display.			Ref.1.1(3)			
A.LC2	Although not used in	Although not used in single-loop control, it is shown on the display.						
A.BS3	Although not used in	single-loop control, it is shown on the display.			Ref.1.1(6)			
A.FL3	Although not used in	Although not used in single-loop control, it is shown on the display.						
A.SR3	Although not used in	single-loop control, it is shown on the display.			D-64 4(0)			
A.LC3	Although not used in	single-loop control, it is shown on the display.			Ref.1.1(3)			

Retransmission Output Parameters Located in: Main menu = CMLP; Submenu = RET

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
RET1	Retransmission output-1 type	OFF: Disable 1: PV1, 2: SP1, 3: OUT1, 4: LPS loop power supply (15 V), 5: PV2, 6: SP2, 7: OUT2 Setpoints 5 to 7 are not available for single-loop control. Retransmission output 1 is always provided via terminals 14 and 15. In heating/cooling control, an output value before allocation to heating/cooling control is transmitted if setpoint 3 is selected. (0% to 50%: Cooling-side output; 50% to 100%: Heating-side output)	1		Ref.2.2(1)
RTH1	Maximum value of retransmission output-1 scale	RET1=1, 2: RTL1 + 1 digit to 100.0% of PV input range RET1=3: RTL1 + 1 digit to 100.0%	100.0% of PV input range		Ref.2.2(1)
RTL1	Minimum value of retransmission output-1 scale	RET1=1, 2: 0.0% of PV input range to RTH1 - 1 digit RET1=3: 0.0% to RTH1 - 1 digit	0.0% of PV input range		Kei.z.z(i)
RET2	Retransmission output-2 type	Retransmission output-2 is available when the type of control output is not current or voltage pulse. The output is provided via terminals 16 and 17. OFF: Disable 1: PV1, 2: SP1, 3: OUT1, 4: LPS loop power supply (15 V), 5: PV2, 6: SP2, 7: OUT2 Setpoints 5 to 7 are not available for single-loop control. In heating/cooling control, an output value before allocation to heating/cooling control (0% to 100%) is transmitted if setpoint 3 is selected. (0% to 50%: Cooling-side output; 50% to 100%: Heating-side output)	OFF		Ref.2.2(1) Ref.2.2(3)
RTH2	Maximum value of retransmission output-2 scale	RET2=1, 2: RTL2 + 1 digit to 100.0% of PV input range RET2=3: RTL2 + 1 digit to 100.0%	-		Ref.2.2(1)
RTL2	Minimum value of retransmission output-2 scale	RET2=1, 2: 0.0% of PV input range to RTH2 - 1 digit RET2=3: 0.0% to RTH2 - 1 digit	-		Nel.2.2(1)

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Deviation Trend Parameters

Located in: Main menu = CMLP; Submenu = TRND

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
TSC1	Deviation trend scale	Allows the deviation axis of the Deviation Trend operating display to be rescaled. 0.1 to 100.0% of PV input range span	0.5% of PV input range span		Def C 4(2)
TTM	Deviation trend time	Allows the time axis of the Deviation Trend operating display to be rescaled. 1 to 600 sec	5 sec.		Ref.6.1(2)

Security-related Parameters

Located in: Main menu = CMLP; Submenu = LOCK

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM		
▼/▲	Locking of front panel	OFF: Unlock	OFF				
V / A	up/down keys (▲and▼)	ON: Lock					
PT.No	Locking of front panel	OFF: Unlock	OFF				
F I .INO	PT.No key	ON: Lock					
RUN	Locking of front panel	OFF: Unlock	OFF				
NON	RUN key	ON: Lock					
MODE	Locking of front panel	OFF: Unlock	OFF				
MODE	MODE key	ON: Lock					
PROG	Locking of operating	OFF: Unlock	OFF				
PROG	parameter main menu	ON: Lock					
	PROG display						
LP1	Operating parameter	OFF: Unlock	OFF		Ref.7.1(2)		
LFI	submenu [LP1] lock	ON: Lock					
LP2	P2 Although not used in single-loop control, it is shown on the display.						
חוח	Operating parameter	OFF: Unlock	OFF				
PID	main menu [PID] lock	ON: Lock					
USR	Although not used in sin	gle-loop control, it is shown on the display.					
PYS1	Operating parameter	OFF: Unlock	OFF		1		
PISI	main menu [PYS1] lock	ON: Lock					
PYS2	Although not used in sin	gle-loop control, it is shown on the display.	1	I			
PWD	Password setting	0: Password not set	0				
PVVD		1 to 30000			Dof 7 1/1\		
		Note: If a password is set, the setup parameters cannot be			Ref.7.1(1)		
		displayed without entering the correct password.					

SELECT Display Parameters

Located in: Main menu = CONF; Submenu = CSEL

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
C.S1	SELECT display-1 registration	OFF, 101 to 1023 Select the desired parameter from among the operating and setup parameters, then register the number	OFF		
C.S2	SELECT display-2 registration	(D register No.) accompanying that parameter. For example, registering 231 for C.S1 allows you to change instrument alarm-1 setpoint in operating display.			
C.S3	SELECT display-3 registration	Numbers for registering instrument alarm SP parameter for operating display: Instrument alarm-1 setpoint: 231			Ref.6.1(1)
C.S4	SELECT display-4 registration	Instrument alarm-2 setpoint: 232 Instrument alarm-3 setpoint: 233 Instrument alarm-4 setpoint: 234			
C.S5	SELECT display-5 registration				

Contact Output Registration Parameters

Located in: Main menu = CONF; Submenu = DO

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
DO1	Relay output flag registration for DO1	The following setpoints are registration numbers for single-loop control only.	5705		
DO2	Relay output flag registration for DO2	5705: PV event 1 output 0: No function 5706: PV event 2 output	5706		
DO3	Relay output flag registration for DO3	5689: Instrument alarm 1 output 5129: Time event 1 output	5689		
DO4	Open-collector transistor output flag registration for DO4	5130: Time event 2 output 5131: Time event 3 output 5133: Time event 4 output	5129		-Ref.3.2(2)
DO5	Open-collector transistor output flag registration for DO5	See "External contact output" in "6. Terminal Wiring Diagrams," of the <i>[Installation User's Manual</i>).	5130		1(61.5.2(2)
DO6	Open-collector transistor output flag registration for DO6		5131		
DO7	Open-collector transistor output flag registration for DO7		5133		
R151	Output flag registration	For contact I/O expansion module-1 See GREEN series Communication Functions "7. Contact I/O	5707		
R152	Output flag registration	expansion"	5709		
R153	Output flag registration	5709: PV event 4 output 5134: Time event 5 output 5135: Time event 6 output	5134		
R154	Output flag registration		5135		
R155	Output flag registration	5137: Tlme event 7 output 5138: Time event 8 output 5145: Time event 9 output	5137		
R156	Output flag registration	5145. Time event 9 output 5146: Time event 10 output	5138		
R157	Output flag registration		5145		
R158	Output flag registration		5146		
R251	Output flag registration	For contact I/O expansion module-2 See GREEN series Communication Functions "7. Contact I/O	5710		Ref.3.2(3)
R252	Output flag registration	expansion"	5711		
R253	Output flag registration	5710: PV event 5 output 5711: PV event 6 output	5147		1
R254	Output flag registration	5147: Time event 11 output 5149: Time event 12 output	5149]
R255	Output flag registration	5150: Time event 13 output 5151: Time event 14 output 5153: Time event 15 output	5150		1
R256	Output flag registration	5153: Time event 15 output 5154: Time event 16 output	5151		1
R257	Output flag registration		5153		1
R258	Output flag registration		5154		1

Contact Input Registration Parameters

Located in: Main menu = CONF; Submenu = DI

Parameter Symbol	Name of Parameter				Setti	ng Rar	ige an	d Des	cription	n		Initial Va	lue User Setting	Target Item in CD-ROM
PROG	Start of program operation (When "DIn" changes from OFF to ON)	m		electio			listed (left.	nput to	use to	5165		
RST	Stop of program operation (When "DIn" changes from OFF to ON)	DI	2: 51 3: 51 4: 51	63								5166		
LOC	Start of local-mode operation (When "Dln" changes from OFF to ON)	DI DI	5: 51 6: 51 7: 51	66 67								5167		
HOLD	Start of hold-mode operation (When "DIn" changes from OFF to ON)	Co	ontac	t input n (see	s 1 to 4 below	1 (DI1 ()): Prog	ram p	attern	numbe	г 0		
ADV	Advance of segment (When "DIn" changes from OFF to ON)	Co	ontac	t input	6 (DI6): Stop	t of pro of pro t of loo	ogram	opera			0		
A/M1	Loop-1 AUTO/MAN switching (AUTO when contact input is ON; MAN when contact input is OFF)	Pr	ograr	n patte	ern nur	mber s	electio	on 5	6	7	8	0		
A/M2	Loop-2 AUTO/MAN switching		DI1	ON OFF	OFF ON	ON ON	OFF	ON OFF	OFF	ON ON	OFF OFF	0		
L/C	LOCAL/CASCADE switching Not used for single-loop control.		DI3 DI4	OFF OFF	OFF OFF	OFF OFF	ON OFF	ON OFF	ON OFF	ON OFF	OFF ON	0		Ref.3.1(7)
PTN.0	Bit 0 of program pattern number		DI1	9 ON	10 OFF	11 ON	12 OFF	13 ON	14 OFF	15 ON		5161		
PTN.1	Bit 1 of program pattern number		DI2	OFF	ON	ON OFF	OFF	OFF	ON	ON		5162		
PTN.2	Bit 2 of program pattern number		DI3	ON	ON	ON	ON	ON	ON	ON		5163		
PTN.3	Bit 3 of program pattern number						t" in "6 User			/iring		5164		
PTN.4	Bit 4 of program pattern number											0		
PTN.5	Bit 5 of program pattern number											0		
PTN.6	Bit 6 of program pattern number											0		
PTN.7	Bit 7 of program pattern number											0		
PTN.8	Bit 8 of program pattern number											0		
DP1	Operating display interruption 1											0		
DP2	Operating display interruption 2											0		
MG1	Interruptive message display 1											0		
MG2	Interruptive message display 2											0		
MG3	Interruptive message display 3											0		
MG4	Interruptive message display 4											0		

UP Mode Parameters

Located in: Main menu = UPMD; Submenu = MD

		•			
Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
UPM	Controller mode (UP mode)	Single-loop control For another controller mode, see the User's Manual (Reference) (CD-ROM version).	1		
SMP	PV sampling period setting	100, 200 and 500 ms The controller restarts if any change is made to the PV sampling period; this does not affect other parameter settings at all, however.	200 ms		Ref.1.1(4)
SMEC	Sampling period error counter (reading only)	0 to 30000	Shows 0 at power-on.		Ref.1.1(5)

Input-related Parameters

LIDMD

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
IN1	PV input type (INPUT 1 terminals) Terminals ①, ② and ③	Specify the type of PV input as a range code. See "Instrument Input Range Codes" in <i>Initial Settings User's Manual</i>	OFF		_
UNI1	PV input unit	Select the unit of PV input. %: Percent °F: Fahrenheit °C: Degree Celsius -: No unit	Depends on the PV input type.		_
RH1	Max. value of PV input range	Set the PV input range (RL1 < RH1).	Depends on the PV		_
RL1	Min. value of PV input range	- For temperature input - Set the range of temperature that is actually controlled For voltage input - Set the range of a voltage signal that is applied. The scale across which the voltage signal is actually controlled should be set using the parameters Maximum Value of PV Input Scale (SH1) and Minimum Value of PV Input Scale (SL1).	input type.		_
SDP1	PV input decimal point position (shown when in voltage-input mode)	Set the position of the decimal point of voltage-mode PV input. 0 to 4 0: No decimal place, 1: One decimal place, 2 to 4: Two, three, four decimal places	Depends on the PV input type.		_
SH1	Max. value of PV input scale (shown when in voltage-input mode)	Set the read-out scale of voltage-mode PV input19999 to 30000, where SL1 < SH1, SH1 - SL1 \leqq 30000	Depends on the PV input type.		_
SL1	Min. value of PV input scale (shown when in voltage-input mode)				_
BSL1	Selection of PV input burnout action	Allows the PV input value to be determined as shown below in case of PV input burnout. • 105% of PV input range if set to "Upscale" • -5.0% of PV input range if set to "Downscale" OFF: Disable UP: Upscale DOWN: Downscale	Depends on the PV input type.		_
RJC1	Presence/absence of PV input reference junction compensation	Allows input compensation to be applied to thermocouple input. OFF: Absent ON: Present	ON		_
IN2	Although not used in	single-loop control, it is shown on the display.			
UNI2	Although not used in	single-loop control, it is shown on the display.			
RH2	Although not used in	single-loop control, it is shown on the display.			
RL2	Although not used in	single-loop control, it is shown on the display.			
SDP2	Although not used in	single-loop control, it is shown on the display.			
SH2	Although not used in	single-loop control, it is shown on the display.			
SL2	Although not used in	single-loop control, it is shown on the display.			
BSL2	Although not used in	single-loop control, it is shown on the display.			

Although not used in single-loop control, it is shown on the display.

IN3	Auxiliary analog input type (INPUT 3 terminals) Terminals ② and ②	Although not used in single-loop control, it is shown on the disp	olay.						
UNI3	Auxiliary analog input unit	Although not used in single-loop control, it is shown on the disp	olay.						
RH3	Maximum value of auxiliary analog input range	Although not used in single-loop control, it is shown on the disp	olay.						
RL3	Minimum value of auxiliary analog input range	Although not used in single-loop control, it is shown on the disp	olay.						
SDP3	Auxiliary analog input decimal point position	Although not used in single-loop control, it is shown on the disp							
SH3	Max. value of auxiliary analog input scale	Although not used in single-loop control, it is shown on the disp	gh not used in single-loop control, it is shown on the display.						
SL3	Min. value of auxiliary analog input scale	Although not used in single-loop control, it is shown on the disp	nough not used in single-loop control, it is shown on the display.						
BSL3	Auxiliary analog input burnout action selection	nough not used in single-loop control, it is shown on the display.							
P.UN1	PV unit	Set the unit of PV. %: Percent °F: Fahrenheit °C: Degree Celsius -: No unit	Same as the unit of PV input						
P.DP1	PV decimal point position	Under normal operation, set the same value as in the PV Input Decimal Point Position (SDP1) parameter. To shift the decimal point for temperature input, use this parameter. For example, set as P.DP1 = 0 to change a temperature reading of one decimal place to that of no decimal places. This involves reconfiguring the P.RH1 and P.RL1 parameters. 0 to 4							
P.RH1	Maximum value of PV range	Under normal operation, keep the values of these parameters between the maximum and minimum values of the PV input range.	Maximum value of PV input range or scale	Ref.1.1(8)					
P.RL1	Minimum value of PV range	-19999 to 30000 P.RL1 < P.RH1, where P.RH1 and P.RL1 ≤ 30000	Minimum value of PV input range or scale						
P.UN2	Although not used in	single-loop control, it is shown on the display.							
P.DP2	Although not used in	single-loop control, it is shown on the display.							
P.RH2	Although not used in	single-loop control, it is shown on the display.							
P.RL2	Although not used in	single-loop control, it is shown on the display.							

Output-related Parameters

Located in: Main menu = UPMD; Submenu = OUT

Parameter Symbol	Name of Parameter		Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
OT1	Control output	0	Time proportional PID relay contact output (terminals ① - ② - ③)	0		
OH	type	1	Time proportional PID voltage pulse output (terminals (6) - (7))			
		2	Current output (terminals 66 - 170)			
		3	ON/OFF control relay contact output (terminals ① - ② - ③)			
		4	Heating-side relay output (terminals ① - ② - ③), cooling-side			
		-	relay output (terminals (4 - 7))	-		
		5	Heating-side pulse output (terminals (⑥ - ⑦), cooling-side relay output (terminals ④ - ⑦)			
		6	Heating-side current output (terminals (6) - (7)), cooling-side relay output (terminals (4) - (7))			
		7	Heating-side relay output (terminals ① - ② - ③), cooling-side pulse output (terminals ③ - ⑤)			
		8	Heating-side pulse output (terminals (6 - (7)), cooling-side pulse			
		_	output (terminals (4) - (5))	-		
		9	Heating-side current output (terminals (6 - (7)), cooling-side pulse output (terminals (3) - (5))			
		10	Heating-side relay output (terminals① -② -③), cooling-side	1		
			current output (terminals 4 - 5)			
		11	Heating-side pulse output (terminals ® - ⑦), cooling-side current output (terminals ® - ⑤)			
		12	Heating-side current output (terminals ® - ⑦), cooling-side			
OT4	Control output cycle	1 1	current output (terminals (4) - (5)	30 sec.		
CT1	time	Ι.,	1 1 1 1 1	00 000.		
	Heating-side control		 			
	output cycle time in		On O			
	heating/cooling control	-	Off Off			
	Control		Cycle time Cycle time			
			Relay s Behavior when Cycle Time = 10 sec			
		For 2	20% of Control Output For 50% of Control Output For 80% of Control Output			
			10 sec 10 sec 10 sec			
			-state duration: 2 sec On-state duration: 5 sec On-state duration: 8 sec			
			-state duration: 8 sec Off-state duration: 5 sec Off-state duration: 2 sec			
CTc1	Cooling-side control output cycle time	1 t	to 1000 sec.	30 sec.		
AO1	Analog output-1 type	Allo	ows control output or retransmission output to be presented	0		
AUT	(OUTPUT 1:	as	one of the following current signals.			
	Terminals (6) and (7) Analog output-2 type	1	0: 4 to 20 mA 1: 0 to 20 mA	0		-
AO2	(OUTPUT 2:		2: 20 to 4 mA	"		
	Terminals (6) and (7)		3: 20 to 0 mA			
AO3	Analog output-3 type	1		0		
703	(OUTPUT 3:					
	Terminals (4) and (5)	80	t the values of aggregated points for the 09/ and 1009/ autnut	100.0 %		-
A1H	Analog output-1 100% segmental point		t the values of segmental points for the 0% and 100% output els at which the values are presented via OUTPUT-1	100.0 %		Ref.2.1(7)
/ \						1.01.2.1(//
	Analog output-1 0%		rminals ® and ⑦). See ■ Performing Split Computations below.	0.0 %		
A1L	Analog output-1 0% segmental point	(tei	-5.0% to 105.0%, where A1L < A1H			1
	Analog output-1 0% segmental point Analog output-2 100%	(te	-5.0% to 105.0%, where A1L < A1H t the values of segmental points for the 0% and 100% output	100.0 %		
A1L A2H	Analog output-1 0% segmental point Analog output-2 100% segmental point Analog output-2 0%	Sei lev	-5.0% to 105.0%, where A1L < A1H t the values of segmental points for the 0% and 100% output els at which the values are presented via OUTPUT-2 rminals (and (). See ■ Performing Split Computations below.			
A1L A2H A2L	Analog output-1 0% segmental point Analog output-2 100% segmental point	Sei lev (tei	-5.0% to 105.0%, where A1L < A1H t the values of segmental points for the 0% and 100% output els at which the values are presented via OUTPUT-2 rminals and one Deforming Split Computations below5.0% to 105.0%, where A2L < A2H t the values of segmental points for the 0% and 100% output	100.0 %		
A1L A2H	Analog output-1 0% segmental point Analog output-2 100% segmental point Analog output-2 0% segmental point	Sei lev (tei	-5.0% to 105.0%, where A1L < A1H t the values of segmental points for the 0% and 100% output els at which the values are presented via OUTPUT-2 rminals and D. See Performing Split Computations below5.0% to 105.0%, where A2L < A2H	100.0 %		

■ Performing Split Computations

V-mode Output

The following explains an example of letting "Analog OUTPUT-1 (terminals ® and ①)" and "Analog OUTPUT-3 (terminals @ and ⑤)" present the V-mode character-

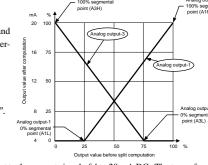
istics of split computations.
[1] Set the Control Output Type (OT1) parameter to "2"

This sets the control output to "current output."

[2] Set the Retransmission Output1 (RET1) parameter to "3".

This sets the retransmission output to "control output retransmission." [3] Set the Analog Output-1 100% Segmental Point (A1H) parameter to "100%".

[4] Set the Analog Output-1 0% Segmental Point (A1L) parameter to "25%". [5] Set the Analog Output-3 100% Segmental Point (A3H) parameter to "0%". [6] Set the Analog Output-3 0% Segmental Point (A3L) parameter to "75%".



The figure on the right shows an example where both analog outputs-1 and 3 are set to the current signal of 4 to $20 \, \text{mA}$ DC. The type of output signal can be determined separately for each of the analog outputs listed above, using the following three parameters. Analog output-1: Analog output-1 type (AO1)

Analog output-2: Analog output-2 type (AO2)

Analog output-3: Analog output-3 type (AO3)

Parallel-mode Output The following explains an example of letting "Analog OUTPUT-1 (terminals ® and @)" and "Analog OUTPUT-3 (terminals @ and @)" present the parallelmode characteristics of split computation

[1] Set the Control Output Type (OT1) parameter to "2". This sets the control output to "current output." [2] Set the Retransmission Output1 (RET1) parameter to "3".

This sets the retransmission output to "control output retransmission." [3] Set the Analog Output-1 100% Segmental Point (A1H) parameter to

[4] Set the Analog Output-1 0% Segmental Point (A1L) parameter to "25%". [5] Set the Analog Output-3 100% Segmental Point (A3H) parameter to

[6] Set the Analog Output-3 0% Segmental Point (A3L) parameter to "0%".

The figure on the right shows an example where both analog outputs-1 and 3 are set to the current signal of 20 to 0 mA DC. The type of output signal can be determined separately for each of the analog outputs listed above, using the following three parameter Analog output-1: Analog output-1 type (AO1)

Analog output-2: Analog output-2 type (AO2) Analog output-3: Analog output-3 type (AO3) Communication Parameters

 $\mathsf{Located\ in:\ Main\ menu} = UPMD\ ;\ \mathsf{Submenu} = R485$

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM		
PSL1	Protocol selection	0: PC link communication 1: PC link communication (with sum check) 2: Ladder communication 3: Coordinated master station 7: MODBUS (ASCII) 8: MODBUS (RTU) 9: Coordinated master station (2 loop mode) Terminal numbers: ②, ②, ③, ③ and ② (terminals for 4-wire connection)	0				
BPS1	Baud rate	600, 1200, 2400, 4800, 9600 (bps)	9600				
PRI1	Parity	NONE: None EVEN: Even ODD: Odd	EVEN				
STP1	Stop bit	1, 2	1				
DLN1	Data length	7, 8; 7 is fixed for MODBUS (ASCII) 8 is fixed for MODBUS (RTU), Ladder	8				
ADR1	Address	1 to 99 However, the maximum number of stations connectable is 31.	1				
RP.T1	Minimum response time	0 to 10 (× 10 ms)	0		Communi- cation		
PSL2	Protocol selection	0: PC link communication 1: PC link communication (with sum check) 2: Ladder communication 3: Coordinated master station 5: I/O expansion (for single-controller applications) 6: I/O expansion (for dual-controller applications) 9: Coordinated master station (2 loop mode) Terminal numbers: 3: 3 and (terminals for 4-wire connection)	0		Function		
BPS2	Baud rate	600, 1200, 2400, 4800, 9600, 19.6k, 38.4k (bps)	9600				
PRI2	Parity	NONE: None EVEN: Even ODD: Odd	EVEN		1		
STP2	Stop bit	1, 2	1				
DLN2	Data length	7, 8; 8 is fixed for Ladder	8				
ADR2	Address	1 to 99 However, the maximum number of stations connectable is 31.	1				
RP.T2	Minimum response time	0 to 10 (× 10 ms)	0		1		

Parameter-initializing Parameters

Located in: Main menu = UPMD; Submenu = INIT

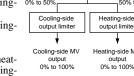
Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
INI	Parameter initialization	OFF: -	OFF		

■ Tips about Heating/Cooling Control

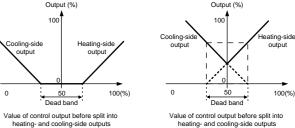
In heating/cooling control, the controller outputs the result of computation after splitting it into heating-purpose and cooling-purpose signals. In addition, the controller can perform PID control or ON/OFF control on the heating and cooling sides separately. When performing ON/OFF control, set the proportional band to "0". The controller splits the result of computation (0 to 100%) into heating-side and

cooling-side signals, as described below. •0% to 50% of the computation result is presented as a 0% to 100% cooling-

• 50% to 100% of the computation result is presented as a 0% to 100% heatingside output.



Heating/cooling control provides two methods in which either none of the heating- and cooling-side outputs are presented or both of the heating- and coolingside outputs are presented, as shown in the following figures.



Precautions in Heating/Cooling Control

• Keep the ratio of the heating-side proportional band (P) to the cooling-side proportional band (Pc) equal to or below 5. • If neither the heating-side nor the cooling-side is performing ON/OFF control, setting the integral time (I or Ic) of one

side to "0" results in the Integral Time parameters of both sides being set to "OFF", irrespective of the integral time setting of the other side.