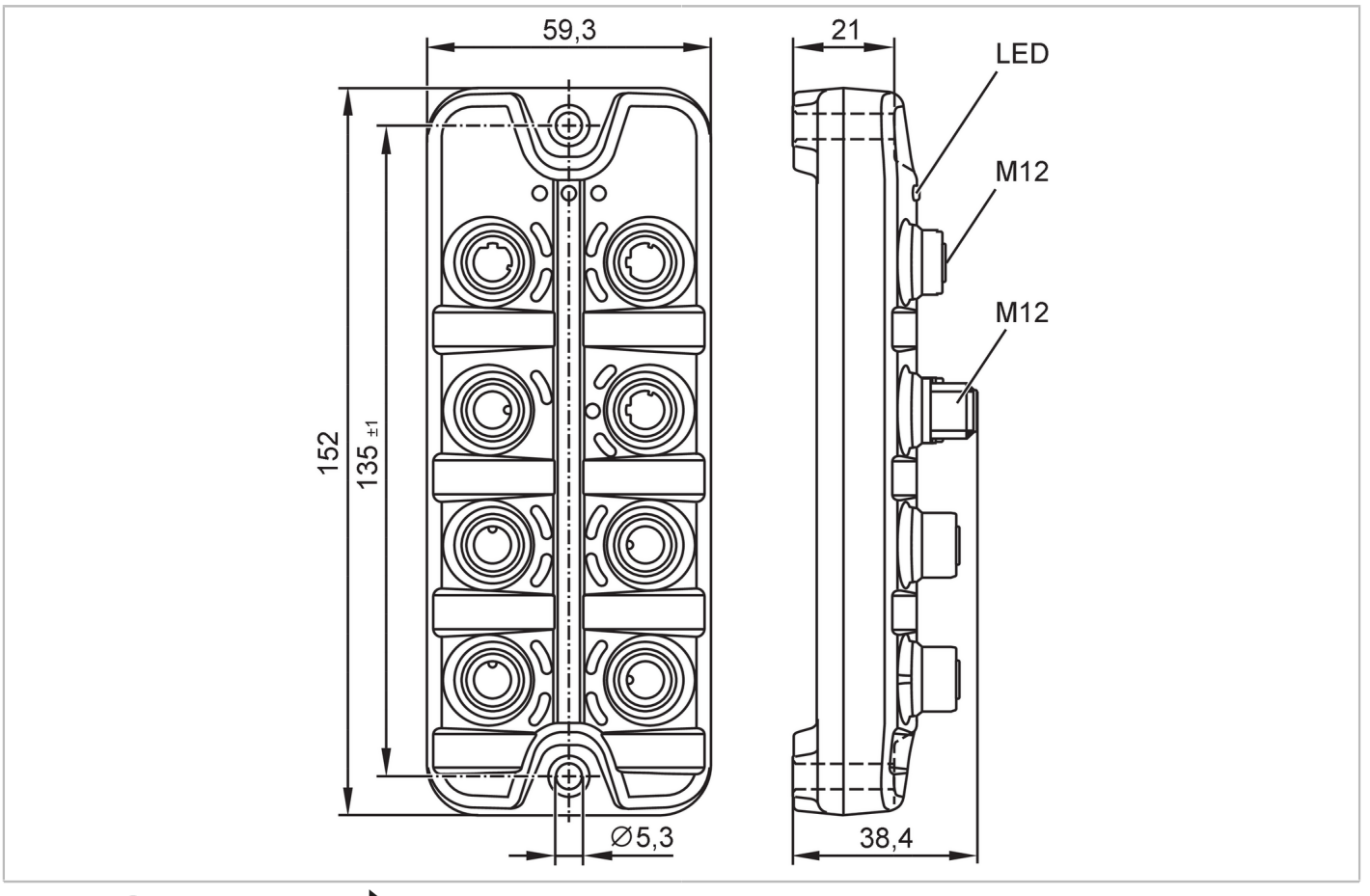
AL1330

IO-Link master with EtherCAT interface

IO-Link Master DL EC 4P IP67



Application		
Application		I/O modules for field applications
Daisy-chain function		fieldbus interface
Electrical data		
Operating voltage	[V]	20...30 DC; (US ; to SELV/PELV)
Current consumption	[mA]	300...3900; (US)
Protection class		III
Sensor supply US		
Max. current load total	[A]	3.6
Inputs / outputs		
Total number of inputs and outputs		8; (configurable)
Number of inputs and outputs		Number of digital inputs: 8; Number of digital outputs: 4
Inputs		
Number of digital inputs		8; (IO-Link Port Class A: 4 x 2)
Switching level high	[V]	11...30
Switching level low	[V]	0...5
Digital inputs protected against short circuits		yes

AL1330

IO-Link master with EtherCAT interface

IO-Link Master DL EC 4P IP67

Outputs			
Number of digital outputs		4; (IO-Link Port Class A: 4 x 1)	
Max. current load per output	[mA]	300	
Short-circuit proof		yes	
Interfaces			
Communication interface		Ethernet; IO-Link	
Ethernet - EtherCAT			
Transmission standard		100Base-TX	
Transmission rate		100 MBit/s	
Protocol		EtherCAT	
Factory settings		MAC address: see type label	
Note on interfaces		AoE (ADS over EtherCAT)	
		CoE (CANopen over EtherCAT)	
		EoE (Ethernet over EtherCAT)	
		FoE (File Access over EtherCAT)	
Ethernet - Internet of Things			
Transmission standard		10Base-T; 100Base-TX	
Transmission rate		10 MBit/s; 100 MBit/s	
Protocol		MQTT JSON	
Factory settings		IP address: 169.254.x.x	
		subnet mask: 255.255.0.0	
		gateway IP address: 0.0.0.0	
		MAC address: see type label	
Note on interfaces		Safety protocol: HTTPS	
IO-Link Master			
Transmission type		COM1 (4,8 kBaud); COM2 (38,4 kBaud); COM3 (230,4 kBaud)	
IO-Link revision		1.1	
Number of ports class A		4	
Operating conditions			
Ambient temperature	[°C]	-25...60	
Storage temperature	[°C]	-25...85	
Max. relative air humidity	[%]	90	
Protection		IP 65; IP 66; IP 67	
Protection rating (NEMA 250)		6P	
Pollution degree		2	
Chemical media		ISO 16750-5	AA, BA, BD, HLP, CC, DB, DC, DD, CA
		NEMA 250 5.13.1	AA
Tests / approvals			
EMC		EN 61000-6-2	
		EN 61000-6-4	
Shock resistance		DIN EN 60068-2-27	
Vibration resistance		DIN EN 60068-2-64 2009-04	
		DIN EN 60068-2-6 2008-10	
MTTF	[years]	95	

AL1330

IO-Link master with EtherCAT interface

IO-Link Master DL EC 4P IP67

Mechanical data		
Weight	[g]	302.5
Housing		rectangular
Type of mounting		Backplane mounting
Dimensions	[mm]	152 x 59.3 x 38.4
Material		housing: PA orange; Socket: brass nickel-plated
Sealing material		FKM

Remarks	
Remarks	Further information is available in the manual.
Pack quantity	1 pcs.

Electrical connection - Ethernet

Connector: 2 x M12; coding: D; Contacts: 4; sealing: FKM

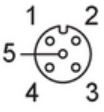


EtherCAT X21, X22	
1	TX +
2	RX +
3	TX -
4	RX -
5	not used

IoT X23	
1	TX +
2	RX +
3	TX -
4	RX -
5	not used

Electrical connection - IO-Link

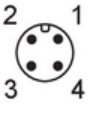
Connector: 4 x M12; coding: A; Contacts: 4; sealing: FKM



IO-Link Port Class A X01...X04	
1	Sensor supply (US) L+
2	Digital input
3	Sensor supply (US) L-
4	C/Q IO-Link
5	not used

Electrical connection - voltage supply

Connector: 1 x M12; coding: A; Contacts: 4



AL1330

IO-Link master with EtherCAT interface

IO-Link Master DL EC 4P IP67

X31	
1	+ 24 V DC (US)
2	not used
3	GND (US)
4	not used

Operating instructions

IO-Link master with EtherCAT interface
DataLine
4 ports
IP 65 / IP 66 / IP 67

AL1330

Firmware: 3.1.x

English

80284123 / 03 10 / 2021

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1 Preliminary note

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1.1 Legal and copyright information

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1.2 Purpose of the document

34227

This document is only for device types "IO-Link master - EtherCAT gateway (DataLine) 4 port IP 65 / IP 66 / IP 67" (art. no.: AL1330).

It is part of the device and contains information about the correct handling of the product.

► Read this document before using the device.

► Keep this document during the service life of the device.

1.3 Explanation of Symbols

34171

WARNING

Warning of serious personal injury.

Death or serious irreversible injuries may result.

CAUTION
Warning of personaly injury.
Slight reversible injuries may result.

NOTICE
Warning of damage to property

Important note
Non-compliance can result in malfunction or interference

Information
Supplementary note

► ... Request for action

> ... Reaction, result

→ ... "see"

abc Cross-reference

123 Decimal number
0x123 Hexadecimal number
0b010 Binary number

[...] Designation of pushbuttons, buttons or indications

1.4 Change history

61145

Version	Topic	Date
00	New creation of the document	04 / 2019
01	Correction: Technical data - current rating per output	09 / 2019
02	▪ Added: New IoT core functions ▪ Added: IoT Core Visualizer ▪ Correction: Description of the IoT Core Service getsubscriptioninfo	10 / 2020
03	Deleted: ifm IoT Core – DNS support	10 / 2021

2 Safety instructions

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Safety symbols on the device 7
IT security 8

28333

2.1 General

58525

- The device described is a subcomponent for integration into a system. The manufacturer is responsible for the safety of the system. The system manufacturer undertakes to perform a risk assessment and to create documentation in accordance with legal and normative requirements to be provided to the operator and user of the system. This documentation must contain all necessary information and safety instructions for the operator, the user and, if applicable, for any service personnel authorised by the manufacturer of the system.
- Read this document before setting up the product and keep it during the entire service life.
- The product must be suitable for the corresponding applications and environmental conditions without any restrictions.
- Only use the product for its intended purpose (→ **Intended use** (→ P. 9)).
- If the operating instructions or the technical data are not adhered to, personal injury and/or damage to property may occur.
- The manufacturer assumes no liability or warranty for any consequences caused by tampering with the product or incorrect use by the operator.
- Installation, electrical connection, set-up, programming, configuration, operation and maintenance of the product must be carried out by personnel qualified and authorised for the respective activity.
- Protect units and cables against damage.

2.2 Required background knowledge

34185

This document is intended for specialists. Specialists are people who, based on their relevant training and experience, are capable of identifying risks and avoiding potential hazards that may be caused during operation or maintenance of the product.

The document contains information about the correct handling of the product.

2.3 Safety symbols on the device

34199



General warning
Observe instructions in chapter "Electrical connection" (→ **Electrical connection** (→ P. 14))!

2.4 IT security

54678

NOTICE!

If the device is operated in an unprotected network environment.

> Unauthorised read or write access to data is possible.

> Unauthorised manipulation of the device function is possible.

► Check and restrict access options to the device:

- Restrict access to authorised persons.
- Do not connect the device to open networks or the internet.

If access from the internet is inevitable:

► choose a safe method to connect with the device (e. g. VPN).

► Use encrypted data transmission (e. g. https / TLS).

3 Intended use

58283

The device may only be used for the following purposes:

- as IO-Link master for configuration, administration and operation of IO-Link devices
- as gateway between IO-Link devices and AS-i network

The device is designed for use without a control cabinet in plant construction.

► Only use the device within the limits of the technical data (→ **Technical data** (→ p. 88)).

4 Function

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4.1 Communication, parameter setting, evaluation

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33860

4.1.1 IO-Link

34084

The device offers the following IO-Link functions:

- IO-Link master (IO-Link revision 1.0 and 1.1)
- 4 IO-Link ports for connection of IO-Link devices
- Provision of process data of the connected IO-Link devices for LR SMARTOBSERVER monitoring software (→ www.ifm.com)

4.1.2 EtherCAT

33676

The device offers the following EtherCAT functions:

- Provision of the functions of a EtherCAT slave
- 2 port switch for access to the EtherCAT interface (X21/X22)
- Gateway for transmission of the process and parameter data between the connected IO-Link devices and the higher-level EtherCAT controller

4.1.3 Internet of Things (IoT)

54679

The device offers the following IoT functions:

- Gateway for the transmission of process, parameter and monitoring data between IO-Linkmaster / IO-Link devices and the IT network level
- REST-API to access process and parameter data
- Supported protocols: TCP/IP JSON, MQTT

4.1.4 Security mode

54697

The IoT interface offers the following optional sercurity functions:

- Secure data transfer via encrypted connection (Secure Layer Transport - TLS)
- Access protection via authentification

4.1.5 Parameter setting

34210

The device provides the following configuration options:

- Parameter setting of the IO-Link master of the AL1330 with LR DEVICE parameter setting software, EtherCAT projection software or ifm IoT-Core services.
- Parameter setting of the connected IO-Link devices (sensors, actuators) with LR DEVICE parameter setting software, EtherCAT projection software or ifm IoT-Core services
- Storage of parameter sets of the connected IO-Link devices for automatic recovery (data storage)

4.1.6 Visual indication

34192

The device has the following visual indicators:

- Status and error indication of the gateway, of the EtherCAT connection and of the system
- Status display of the voltage supply
- Status and activity display of the Ethernet connection
- Status, error and short circuit/overload indication of the IO-Link ports

4.2 Digital inputs

33817

The device has 4 additional digital inputs (type 2 according to EN 61131-2).

The digital inputs are on pin 2 of the ports X01...X04.

All inputs refer to the potential of the device supply (pin 3).

4.3 IO-Link supply

34077

The device has 4 supplies for IO-Link devices.

The IO-Link ports X01...X04 are ports class A.

Every supply provides short circuit monitoring.

The device ensures fire protection for the connected IO-Link devices by providing a power-restricted circuit at the IO-Link ports (according to IEC61010-1 and Class 2 according to UL1310).

5 Mounting

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34058

5.1 Mount the device

34059

- ► Disconnect the system from power before installation.
- ► For installation choose a flat mounting surface.
- ► Please observe the maximum tightening torque.

► Fix the unit to the mounting surface using 2 M5 mounting screws and washers.
  - Tightening torque: 1.8 Nm

► Ground the unit via the two mounting screws of the upper mounting lugs.

6 Electrical connection

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6.1 Notes

51957

A qualified electrician must connect the unit.

► The national and international for regulations setting up electrical equipment must be complied with.

The unit is only suitable for operation using SELV/PELV voltages.

► Please note the information concerning IO-Link wiring!

This unit contains components that may be damaged or destroyed by electrostatic discharge (ESD).

► Please observe the required precautions against electrostatic discharge!

The M12 connection parts in the device comply with the ingress resistance requirements of the standard EN 61076-2-101. To adhere to the protection rating, only cables certified to this standard must be used. The system creators undertake to ensure ingress resistance for cables which they cut to length themselves.

► Carry out the fitting according to the indications of the cable manufacturer. A maximum of 0.8 Nm is permitted.

► During installation, place the M12 connector vertically so that the coupling nut will not damage the thread.

► Depending on the mounting conditions, cables must be provided with a strain relief to avoid unacceptable loads on the mounting points and M12 connections.

► Make sure that the M12 connection parts are correctly seated and mounted correctly. The specified protection rating can not be guaranteed if this is not observed.

For UL applications:

► To connect the IO-Link master and the IO-Link devices, only use UL-certified cables of the CYJV or PVVA category with a minimum temperature of 80 °C (75 °C in case of maximum ambient temperature of 40 °C).

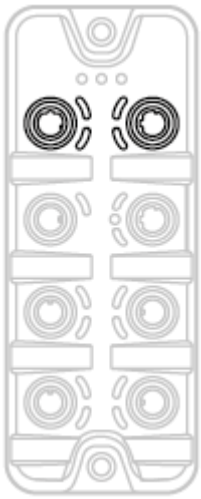
Wiring: → **Technical data** (→ p. 88)

By means of basic insulation according to EN61010-1, the circuits are separated from each other and from device surfaces that could be touched (secondary circuit with 30 V DC maximum, supplied from mains circuit up to 300 V overvoltage category II).

By means of basic insulation according to EN61010-1, the communication interfaces are separated from each other and from device surfaces that could be touched (secondary circuit with 30 V DC maximum, supplied from mains circuit up to 300 V overvoltage category II). They are designed for network environment 0 according to IEC TR62102.

6.2 Connecting the EtherCAT ports

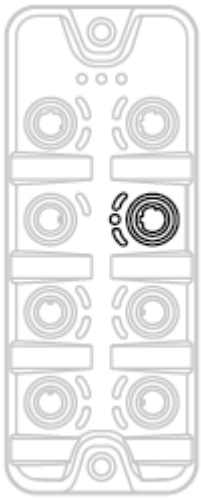
33671



- ► Connect the device via the M12 socket X21 and/or X22 to the EtherCAT network
  (e.g. EtherCAT PLC, additional EtherCAT device)
- ► To connect the devices, use M12 connectors with protection rating IP 65 / IP 66 / IP 67 or higher (→ **Accessories** (→ p. 86)).
- ► Cover the unused sockets with M12 protective caps (art no. E73004).

6.3 Connecting the IoT port

34044



- ► Connect the device via the M12 socket X23 to the IT network (e.g. laptop/PC with LR DEVICE parameter setting software, laptop/PC with LR SMARTOBSERVER monitoring software, laptop/PC with software capable of processing http requests).
- ► To connect the devices, use M12 connectors with protection rating IP 65 / IP 66 / IP 67 or higher (→ **Accessories** (→ p. 86)).
- ► Cover the unused sockets with M12 protective caps (art no. E73004)

6.4 IO-Link ports

51958

The IO-Link ports of the AL1330 meet the requirements of the IO-Link specifications 1.0 to 1.1.2.

► Please note the information concerning IO-Link wiring!

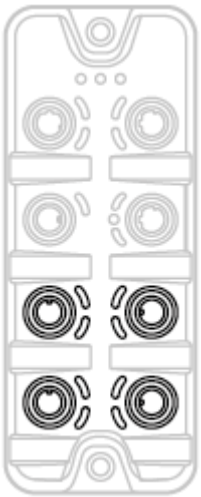
► Cover unused sockets with M12 protective caps (art. no.: E73004).

6.4.1 Connecting IO-Link devices for Class A operation

51959

Wiring information:

- The connected IO-Link devices must be supplied exclusively via the IO-Link master.
- The additional digital inputs IO-Link ports X01...X04 (pin 2) have a type 2 behaviour according to the standard EN61131-2. The connected electronics must be electrically suited for this.



► Connect the connectors of the IO-Link devices with the M12 sockets of the IO-Link ports X01...X04.

  ▪ Maximum cable length per IO-Link port: 20 m

► To connect the devices, use M12 connectors with protection rating IP 65 / IP 66 / IP 67 or higher (→ **Accessories** (→ p. 86)).

6.4.2 Connecting IO-Link devices for Class B operation

51960

Notes on wiring:

- For Class B operation, the IO-Link device must be supplied with an additional auxiliary voltage UA using a Y connection cable.

WARNING

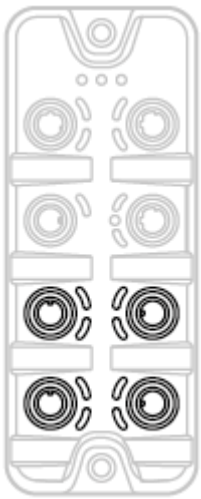
Non-compliance with the electrical separation of the circuits

> Risk of fire!

► Ensure that the external supply UA is galvanically separated from the circuit of the IO-Link Master by assuring basic insulation (according to IEC 61010-1, secondary circuit with 30 V DC maximum, supplied from mains circuit up to 300 V of overvoltage category II).

► Ensure that the IO-Link devices and the connection technology support the galvanic separation.

In case of operation as port class B, the additional digital input of the IO-Link port (pin 2) is not available!



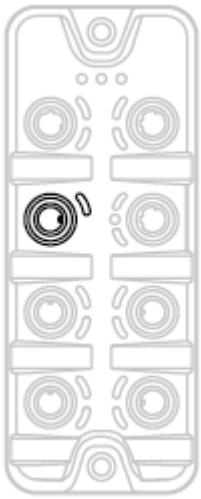
► Connect the connectors of the IO-Link devices via a Y connection cable with the M12 sockets of the IO-Link ports X01...X04.

► Connect the Y cable to 24 V DC (20...30 V SELV/PELV)

► To connect the devices, use M12 connectors with protection rating IP 65 / IP 66 / IP 67 or higher (→ **Accessories** (→ p. 86))!

6.5 Connecting the device

33882



- ► Disconnect power.
- ► Connect the IO-Link Master via M12 socket X31 to 24 V DC (20...30 V SELV/PELV; according to EN61010-1, secondary circuit with maximum 30 V DC supplied by mains circuit up to 300 V of overvoltage category II).
  - Maximum cable length: 25 m
- ► To connect the device, use M12 connectors with protection rating IP 65 / IP 66 / IP 67 or higher (→ **Accessories** (→ p. 86)).

When using cable length greater than 25 m keep in mind the voltage drop as well as the required minimum voltage supply of 20 V!

7 Operating and display elements

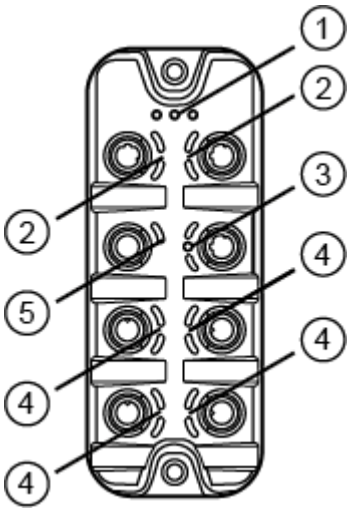
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7.1 Overview

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1. RDY, RUN and ERR status LEDs
   → **Status LEDs** (→ p. 20)
2. Status LEDs L/A of the EtherCAT interfaces 1 (X21) and 2 (X22)
   → **EtherCAT interface** (→ p. 20)
3. LNK, ACT status-LEDs and IoT LED of the IoT interface (X23)
   → **IoT port** (→ p. 21)
4. IOL and DI status-LEDs of the IO-Link port (X01...X04)
   → **IO-Link Ports (Class A)** (→ p. 21)
5. US status LED of the voltage supply (X31)
   → **Voltage supply** (→ p. 21)

7.2 LED indicators

34047

The device only has the following LED indicators:

7.2.1 Status LEDs

34198

The RDY LED indicates the status of the gateway.
The RUN LED indicates the current state of the EtherCAT state machine.
The ERR LED inidcates occuring errors.

Status LED			Description
RDY	green	on	Status: OK
		flashes 5 Hz	Status: Error
		flashes (200 ms on, 800 ms off)	Status: Firmware update is running
		off	Status: Gateway not running or gateway booting
RUN	green	on	Device in OPERATIONAL state
		flashes 2.5 Hz	Device in PRE-OPERATIONAL state
		flahes (200 ms on, 1000 ms off)	Device in SAFE-OPERATIONAL state
		flashes 10 Hz	Device is booting and not yet in INIT state or device is in BOOTSRAP state
		off	Device in INIT state
ERR	red	on	Error in application controler
		flashes 10 Hz	Boot error
		flashes (200 ms on, 200 ms off, 200 ms on, 1000 ms off)	Watchdog error (EtherCAT or process data)
		flashes (200 ms on, 1000 ms off)	Local error
		flashes 2.5 Hz	Invalid configuration
		off	No error

7.2.2 EtherCAT interface

33682

Each EtherCAT interface (X21, X22) has 1 L/A LED. The LED indicates the status of the Ethernet connection.

Status LED			Description
L/A	green	on	Ethernet connection established
		flashes	Data is transmitted via the Ethernet interface.
		off	No Ethernet connection

7.2.3 IoT port

34043

The IoT port has the 3 LNK, ACT and IoT LEDs. The LEDs indicate the status of the Ethernet connection and the device identification.

Status LED			Description
LNK	green	on	Ethernet connection established
		off	No Ethernet connection
ACT	yellow	flashes	Data is transmitted via the Ethernet interface.
		off	No data transmission
IoT	green	flashes	Device identification active

7.2.4 Voltage supply

34191

The interface for voltage supply (X31) has the LED that is marked as US. The LED indicates the status of the voltage supply.

Status LED			Description
US	green	on	The supply voltage Us is applied.
		off	No supply voltage is applied or the applied supply voltage is too low.

7.2.5 IO-Link Ports (Class A)

34074

Each IO-Link Port Class A has 2 LEDs labelled IOL and DI. The LEDs indicate the status of the IO-Link port.

Status LED			Description
IOL	yellow	Off	Port configured as DI/DO: pin 4 (C/Q) = OFF
		on	Port configured as DI/DO: pin 4 (C/Q) =ON
	green	flashing 1 Hz	Port configured asIO-Link: no IO-Link device found
		Flashing with 2 Hz	Port configured asIO-Link: Status PREOPERATE
		on	Port configured asIO-Link: Status OPERATE
	red	Flashing with 2 Hz	Port configuration error or short circuit / overload on US
		on	Transmission Error
DI	yellow	Off	Digital input: pin 2 = OFF
		on	Digital input: pin 2 = ON

8 Set-up

52811

When the supply voltage is switched on, the AL1330 starts with the factory settings. The display elements signal the current operating mode (→ **Operating and display elements** (→ p. 19)).

To enable parameter setting of the AL1330, the IoT interface and / or the fieldbus interface must be configured according to the network environment.

► Configure fieldbus interface (→ **Fieldbus: Configuring the fieldbus interface** (→ p. 48, "**Integrate the IO-Link master into the TwinCAT project**" → p. 77)).

► Configure IoT interface (LR DEVICE: → **IoT: Configure IP settings** (→ p. 25) or → **IoT: Configuring IP settings** (→ p. 44)).

> IoT / fieldbus interface has valid settings.

> User can set the parameters of the AL1330.

Further steps:

- Optional: Update firmware of AL1330 (→ **Updating the firmware** (→ p. 84)).
- Set the parameters of the AL1330 (→ **Configuration** (→ p. 23)).

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9.1 LR DEVICE

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33692

On delivery, the AL1330 is configured with the factory settings (→ **Factory settings** (→ p. 85)).

Required software: LR DEVICE (1.5.0.x or higher) (art.-no.: QA0011/QA0012)

9.1.1 Remarks

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34180

Offline parameter setting

34060

The AL1330 supports the offline parameter setting. In this context, the user creates and stores a configuration for the IO-Link master and the connected IO-Link devices without being connected to the AL1330 (OFFLINE mode). The configuration created in this way can be stored as a file (*.lrp) and loaded to the AL1330 and activated at a later date.

Further information about offline parameter setting: → Operating instructions LR DEVICE

Fail-safe values of the IO-Link ports

52521

The AL1330 has no failsafe function for the outputs of the IO-Link ports. If the fieldbus connection is interrupted, the last used output values are written and marked as invalid.

9.1.2 IoT: Configure IP settings

34049

For access to the IO-Link master via the IT infrastructure the user has to set the IP settings of the IoT port.

To configure the IP settings with DHCP, a DHCP server has to be active in the IT network. If no DHCP server can be reached in the IT network, an IP address is automatically assigned to the IoT port with the Zeroconfig protocol (address range: → **Factory settings** (→ p. 85)).

To configure the IP settings of the IoT interface:

► Select [IoT] menu.

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[DHCP]	Activate/deactivate the DHCP client of the device	[Static IP]	IP settings were set by the user
		[DHCP]	IP settings are set by a DHCP server in the network.
[IP address]*	IP address of the IoT port	Factory setting: 169.254.X.X	
[Subnet mask]*	Subnet mask of the Ethernet network	Factory setting: 255.255.0.0	
[Default gateway IP address]*	IP address of the network gateway	Factory setting: 0.0.0.0	
[MAC address]	MAC address of the IoT port	The value is firmly set.	

* ... can only be edited if parameter [DHCP] = [Static IP]

► Save changed values on the device.

9.1.3 IoT: Configure security mode

54680

The IoT interface of the IO-Link offers a security mode. It enables secure data transmission via transport encryption and restriction of the access to IO-Link masters and IO-Link devices via user authentication.

To configure the security mode:

► Select [IoT] menu.

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Security mode HTTPS]	Set the security mode	[Disabled]	Security mode disabled
		[Enabled]	Security mode enabled
[Security password]	Password Note: The set password is not displayed.		

► Save changed values on the device.

The security mode only protects the access to the device via the IoT interface.
The user name "administrator" cannot be changed.

The security mode can be enabled without setting the password. During the attempt to write to the device, LR DEVICE requires to enter and confirm the password.

After entering the password, the user has unrestricted access to IO-Link masters and connected IO-Link devices. The password will only be requested again if the current LR DEVICE session is over (e. g. after restarting the LR DEVICE).

To change the set password:

► Sign in with a valid password.

► Enter the new password in the field [Security password].

► Write changes to the device.

> The new password is set.

9.1.4 IoT: Configuring access rights

34046

The access rights define which instance may read and / or write the parameter data, process data and event/diagnostic messages.

In order to configure the access rights to the IO-Link master:

► Select [IoT] menu.

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Access Rights]	The access rights to the parameter data, process data and the event/diagnostic messages of the IO-Link master as well as the connected IO-Link devices	[EtherCAT + IoT]*	▪ EtherCAT and IoT Core have read and write access rights to parameters and process data ▪ EtherCAT and IoT Core have read access rights to events/alarms
		[EtherCAT + IoT (read-only)]	▪ EtherCAT has read and write access rights to parameters and process data ▪ EtherCAT has read access rights to events/alarms ▪ IoT Core only has read access rights to parameters, process data and events/alarms
		[IoT only]	▪ IoT Core has read and write access rights to parameters and process data ▪ IoT has read access rights to events/alarms ▪ EtherCAT has no access rights

* ... Factory setting

► Save changed values on the device.

If in LR DEVICE and EtherCAT projection software the parameter [Access Rights] is = [EtherCAT + IoT], the parameter values set in the EtherCAT projection software will always apply.

If the parameter [Access Rights] in LR DEVICE is = [IoT only], set the parameter [Access Rights] = [Keep settings] in the EtherCAT projection software.

If the parameter [Access Rigts] in LR DEVICE is = [<Fieldbus> + IoT (read-only)], write access to the device configuration via LR DEVICE and IoT core services is blocked. To enable write access again, set the parameter to [<Fieldbus> + IoT] via fieldbus configuration software.

Changes of the parameter [Access Rights] will only be effective after restarting the IO-Link master (→ **Firmware: Reboot the device** (→ p. 32)).

9.1.5 IoT: Configure the interface to LR AGENT or LR SMARTOBSERVER

34048

To enable transfer of process data from the IO-Link master to LR AGENT or LR SMARTOBSERVER, the interface has to be configured accordingly.

► Select [IoT] menu.

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[IP address LR Agent or SMARTOBSERVER]	IP address of LR AGENT or LR SMARTOBSERVER	Factory setting: 255.255.255.255	
[Port LR Agent or SMARTOBSERVER]	Port number that is used to send process data to LR AGENT or LR SMARTOBSERVER	0 ... 65535	Factory setting:: 35100
[Interval LR Agent or SMARTOBSERVER]	Cycle time for the transfer of the process data to LR AGENT or LR SMARTOBSERVER (value in milliseconds)	[Off]	no transfer
		500 ... 2147483647	500 ms ... 2147483647 ms
[Application Tag]	Source identifier of the IO-Link master in the structure of LR AGENT or LR SMARTOBSERVER (String32)	Factory setting: AL1330	

After changing the parameter [Port LR Agent or SMARTOBSERVER] or [Application Tag], it may take 120 seconds before the device establishes a new TCP connection.

To prevent the delay:

► Reboot the device after changing the the parameter.

► Save changed values on the device.

9.1.6 Fieldbus: Configure EtherCAT interface

33828

The user can assign a name for the identification of the IO-Link master in the EtherCAT projection software.

The address of the EtherCAT port is assigned via the EtherCAT projection software.

To configure the fieldbus port:

► Select [Fieldbus] menu.

> The menu page shows the current settings.

> Set the following parameters as required:

Parameter	Description	Possible values
[Hostname]	Name of the device in the EtherCAT network	e.g. al1xxx
[MAC address]	MAC address of the device	The value is firmly set.

► Save changed values on the device.

9.1.7 IO-Link ports: Activate data transfer to LR AGENT or LR SMARTOBSERVER

33690

The user can decide separately for each IO-Link port whether the process data of the connected IO-Link devices should be transferred to LR AGENT or LR SMARTOBSERVER.

To transfer process data the interface to the LR AGENT or LR SMARTOBSERVER has to be correctly configured (→ **IoT: Configure the interface to LR AGENT or LR SMARTOBSERVER** (→ p. 28)).

To activate / deactivate data transfer:

► Select [Port x] menu (x = 1...4).

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Transmission to LR Agent or SMARTOBSERVER]	Transfer of process data of the connected IO-Link device to LR AGENT oder LR SMARTOBSERVER	[Disabled]	Transfer process data
		[Enabled]	Don't transfer process data

► Save changed values on the device.

9.1.8 IO-Link ports: Configure operating mode

33694

The IO-Link ports X01...X04 of the device support the following operating modes:

- Disabled: no data transfer at pin 4 (C/Q) of the IO-Link port
- Digital input (DI): binary input signal at pin 4 (C/Q) of the IO-Link port
- Digital output (DO): binary output signal at pin 4 (C/Q) of the IO-Link port
- IO-Link: IO-Link data transfer via pin 4 (C/Q) of the IO-Link port

The user can set the operating mode separately for each IO-Link port.
To set the operating mode of an IO-Link port:

► Select [Port x] menu (x = 1...4).

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Mode Pin4 US]	Operating mode of pin 4 of the IO-Link port	[Disabled]	Port deactivated
		[DI]	Operation as digital input
		[DO]	Operation as digital output
		[IO-Link]	Operation as IO-Link interface
[Cycle time actual]**	Current cycle time of the data transfer between IO-Link master and IO-Link device on the port (value in microseconds)	Parameter can only be read	
[Cycle time preset]*	Cycle time of the data transfer between the IO-Link master and the IO-Link device at the port (value in microseconds)	0	The device automatically sets the fastest possible cycle time.
		1 ... 132800	1 microsecond ... 132800 microseconds
[Bitrate]**	Current transmission rate of the data transfer between the IO-Link master and the IO-Link device on the port	Parameter can only be read	

* ... Parameter only available if [Mode] = [IO-Link]
** ... Parameter only visible if the IO-Link device is connected to the IO-Link port.

► Save changed values on the device.

9.1.9 IO-Link ports: Set the device validation and data storage

33697

The user can choose how the IO-Link ports are to behave with regard to the device validation and the storage / recovery of parameter data of the connected IO-Link device.

The following options are available:

Option	Validation of the IO-Link device	Storage of the parameter values	Recovery of the parameter values
[No check and clear]	no	no	no
[Type compatible V1.0 device]	yes, test the compatibility with IO-Link standard V1.0	no	no
[Type compatible V1.1 device]	yes, test the compatibility with IO-Link standard V1.1	no	no
[Type compatible V1.1 device with Backup + Restore]	yes, test the compatibility with IO-Link standard V1.1 and identity of design (vendor ID and device ID)	yes, automatic storage of the parameter values; changes of the current parameter values will be stored	yes, recovery of the parameter values when connecting an identical IO-Link device with factory settings
[Type compatible V1.1 device with Restore]	yes, test the compatibility with IO-Link standard V1.1 and identity of design (vendor ID and device ID)	no, there is no automatic storage changes of the current parameter values will not be stored	yes, recovery of the parameter values when connecting an identical IO-Link device with factory settings

The options only apply if the IO-Link port is in the operating mode "IO-Link".

For options [Type compatible V1.1 device with Backup + Restore] and [Type compatible V1.1 device with Restore]: If the vendor ID and device ID are changed in the online mode, the data memory will be deleted and a new backup of the parameter values of the connected IO-Link device will be created in the IO-Link master.

To configure the device validation and the data storage:

► select [Port x] menu (x = 1...4).

> The menu page shows the current settings.

► Set the following parameters as required:

Name	Description	Possible values	
[Validation / Data Storage]	Supported IO-Link standard and behaviour of the IO-Link master when connecting a new IO-Link device at port x (x = 1...4)	[No check and clear]	
		[Type compatible V1.0 device]	
		[Type compatible V1.1 device]	
		[Type compatible V1.1 device with Backup + Restore]	
		[Type compatible V1.1 device with Restore]	
[Vendor ID]	ID of the manufacturer that is to be validated	0...65535	Factory setting: 0# ifm electronic: 310
[Device ID]	ID of the IO-Link device that is to be validated	0...16777215	Factory setting: 0

► Save changed values on the device.

9.1.10 Info: Show device information

34065

To read the general information of the ifm IO-Link master:

► Select [Info] menu.

> The menu page shows the current settings.

Name	Description	Possible values
[Product code]	Article number of the IO-Link master	AL1330
[Device family]	Device family of the IO-Link master	IO-Link master
[Vendor]	Vendor	ifm electronic gmbh
[SW-Revision]	Firmware of the IO-Link master	
[HW revision]	Hardware version of the IO-Link master	
[Bootloader revision]	Bootloader version of the IO-Link master	
[Serial number]	Serial number	

9.1.11 Firmware: Reset device to factory settings

33838

When the IO-Link master is reset, all parameters are set to the factory settings:

To reset the device to factory settings:

► Select [Firmware] menu.

> The menu page shows the current settings.

► Click on [Factory Reset] to reset the device.

> LR DEVICE sets the device to the factory settings.

9.1.12 Firmware: Reboot the device

33832

When rebooting the device, all settings are kept.

To restart the AL1330:

► Select [Firmware] menu.

> The menu page shows the current settings.

► Click on [Reboot] to reboot the device.

> LR DEVICE reboots the ifm IO-Link master.

9.1.13 Configure IO-Link devices

33856

To configure the IO-Link devices connected to the device with the LR DEVICEparameter setting software:

Requirements:

> IO-Link master is correctly installed and connected to the LR DEVICE parameter setting software.

> The IO-Link device is connected correctly with the AL1330.

> Operating mode of the IO-Link port is "IO-Link" (→ **IO-Link ports: Configure operating mode** (→ p. 30)).

> IoT has write access rights to the IO-Link master (→ **IoT: Configuring access rights** (→ p. 27)).

1 Select IO-Link master

► Start LR DEVICE.

► Update IODD file library
OR:
Import IODD file of the IO-Link device manually.

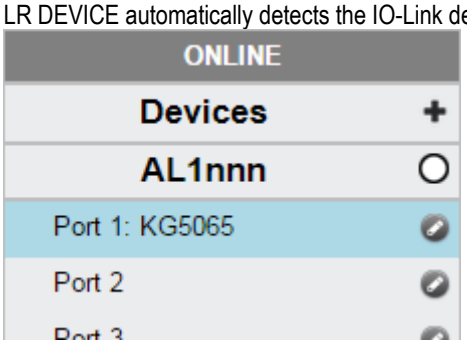
► Scan network for devices.

> LR DEVICE detects IO-Link master.

2 Add IO-Link device

► Under [ONLINE]: Click on the required IO-Link master.

> LR DEVICE automatically detects the IO-Link devices connected to the IO-Link master (e.g. ifm sensor KG5065).



3 Configure IO-Link device

► Mouse click on the port to which the IO-Link device is connected.

> LR DEVICE reads and shows the current parameter values of the IO-Link device.

► Configure IO-Link device.

Information about the available parameters of the IO-Link device: → IO Device Description (IODD) des IO-Link Devices

► Save the changed configuration on the IO-Link device.

9.2 ifm IoT Core

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52244

General notes on the ifm IoT Core: → **Programmers' notes** (→ p. 35)

9.2.1 Programmers' notes

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34229

IoT Core: General information

52256

The DataLine device family has an IoT Core. The IoT Core allows the user to address the AL1330 from IT networks via a REST API and to integrate it into Internet-of-Things applications.

A device description is stored on the AL1330. This device description is a structured, machine-readable data object in JSON format. All current values of parameters, process data, diagnostic data and device information are mapped in this data object. These data values can be read and changed by means of services.

Access the ifm IoT Core

52257

The user can access the ifm IoT Core via HTTP requests. The following request methods are available.

GET request

33804

Using the GET method the user has read access to a data point.

The syntax of the request to the IoT Core is:

```
http://ip/datapoint/service
```

Parameter	Description
ip	IP address of the IoT interface
data_point	Data point which is to be accessed
service	Service

The syntax of the return of the IoT Core is:

```
{
"cid":id,
"data":{"value":resp_data},
"code":diag_code
}
```

Parameter	Description
id	Correlation ID for the assignment of request and return
resp_data	Value of the data point; depending on the data type of the data point
diag_code	Diagnostic code (→ **IoT Core: Diagnostic codes** (→ p. 38))

Example: GET request

54033

Request (via browser):

```
http://192.168.0.250/devicetag/applicationtag/getdata
```

Response:

```
{
"cid":-1,
"data":{"value":"AL1330"},
"code":200
}
```

POST request

54700

Using a POST request the user has read and write access to a data point.

The syntax of the request to the IoT Core is:

```
{
"code":"code_id",
"cid":id,
"adr":"data_point/service",
"data":{req_data},
"auth":{"user":"usr_id","passwd":"password"}
}
```

Field	Parameter	Description	
code	code_id	Service class	
		▪ request	Request
		▪ transaction	Transaction
		▪ event	Event
cid	id	Correlation ID for the assignment of request and response; ID freely assignable by the user	
adr	data_point	Data point of the element tree which is to be accessed	
	service	Service to be performed (→ **Overview: IoT services** (→ p. 122))	
data*	req_data	Data to be transferred to the IoT Core (e.g. new values); syntax depending on the service	
auth**	usr_id	user name (base64 coded); default value: administrator	
	password	password (base64 coded)	

* = optional; only required for services, that submit data to the IoT core (e. g. setdata)
** = optional; only required, if security mode is activated

The syntax of the return of the IoT Core is:

```
{
"cid":id,
"data":{resp_data},
"code":diag_code
}
```

Field	Parameter	Description
cid	id	Correlation ID for the assignment of request and response (see request)
data*	resp_data	Value of the data point; syntax depending on the service
code	diag_code	Diagnostic code (→ **IoT Core: Diagnostic codes** (→ p. 38))

* = optional; only required for services, that receive data from the IoT core (e.g. getdata)

Example: POST request

54035

Request:

```
{
"code":"request",
"cid":4711,
"adr":"devicetag/applicationtag/getdata"
}
```

Response:

```
{
"cid":4711,
"data":{"value":"AL1330"},
"code":200
}
```

IoT Core: Diagnostic codes

54688

Code	Text	Description
200	OK	Request successfully processed
230	OK but needs reboot	Request successfully processed; IO-Link master must be restarted
231	OK but block request not finished	Request successfully processed; blockwise request, but not yet finished
232	Data has been accepted, but internally modified	New values have been accepted, but were adjusted by the IO-Link master (Master cycle time)
233	IP settings (of IoT-Port) have been updated. Application needs to reload device. Wait at least 1 second before reloading device.	IP settings have been successfully changed, IO-Link master will be reloaded; wait for at least 1 second
400	Bad request	Invalid request
401	Unauthorized	Non authorised request
403	Forbidden	Forbidden request
500	Internal Server Error	Internal fault
503	Service Unavailable	The service is not available (e. g. IO-Link port in wrong operating mode; no IO-Link device at IO-Link port)
530	The requested data is invalid	Invalid process data
531	IO-Link error	Error in IO-Link Master / device
532	PLC connected Error	Error while setting data, because IO-Link master is still connected to fieldbus PLC

9.2.2 First steps

52245

To read the device description of the AL1330:

► Send the following POST request to the AL1330:
`{"code":"request","cid":-1,"adr":"gettree"}`

> AL1330 returns the device description as structured JSON object.

► Identify all substructures and the data points contained therein in the tree structure of the JSON object.

► Identify the applicable services for the access to substructures and the data points contained therein.

9.2.3 General functions

61148

The AL1330 has the type `device` (→ **Overview: IoT types** (→ p. 121)).

The following services can be used on the root element of the type `device`:

Service	Description
../gettree	Provide the complete tree or subtree of the device description (JSON)
../getidentity	Reading device information
../getdatamulti	Reading several parameter values sequentially
../getelementinfo	Reading detailed information of an element
../getsubscriberlist	Print a list of all active notification subscriptions
../querytree	Search device description for specific elements

Depending on the read and write access rights, the following services can be applied to elements of type `data`:

Service	Description
../getdata	Reading the value of the element
../setdata	Write the value of the element

Example: Reading properties of an element

59782

Task: Determine the data type and value range of the accessrights parameter.

Solution: Read the properties of the element `iotsetup/accessrights` of the getelementinfo service. The fields type (data type) and valuation (range of values) contain the required information.

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"getelementinfo",
"data":{"adr":"iotsetup/accessrights"}
}
```

- Response:

```
{
"cid":4711,
"data":{
"identifier":"accessrights",
"type":"data",
"uid":null,
"profiles":["parameter"],
"format":{
"type":"enum",
"namespace":"json",
"encoding":"integer",
"valuation":{
"valuelist":{
"0":"Fieldbus + IoT",
"1":"Fieldbus + IoT (read-only)",
"3":"IoT only"}}}},
"code":200
}
```

The accessrights parameter has the data type ENUM with the valid values "Fieldbus + IoT", "Fieldbus + IoT (read only)" and "IoT only".

Example: output subtree

61149

Task: Output all direct sub-elements of the node `firmware`.

Solution: Use the service gettree to output the required subtree (root node: firmware, sub-levels to be shown: 1)

- Request:


```
{
"code":"request",
"cid":4711,
"adr":"gettree",
"data":{
"adr":"firmware",
"level":1}
}
```


- Response:


```
{
"cid":4711,
"data":{
"identifier":"firmware",
"type":"structure",
"profiles":[
"software","software/uploadablesoftware"],
"subs":[
{
"identifier":"version","type":"data","profiles":["parameter"],
"format":{"type":"string","namespace":"json","encoding":"UTF-8"}},
{
"identifier":"type","type":"data",
"format":{"type":"string","namespace":"json","encoding":"UTF-8"}},
{
"identifier":"install","type":"service"},
{
"identifier":"factoryreset","type":"service"},
{
"identifier":"signal","type":"service"},
{
"identifier":"container","type":"data",
"format":{"type":"binary","namespace":"json","encoding":"base64"}},
{
"identifier":"reboot","type":"service"}]
},
"code":200
}
```

Example: Read several parameter values of the IO-Link master simultaneously

33840

Task: The following current values are to be read by the IO-Link master: temperature, serial number

Solution: Read the current parameter values using the getdatamulti service (data point temperature: /processdatamaster/temperature; data point serial number: /deviceinfo/serialnumber)

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"/getdatamulti",
"data":{"datatosend":["/processdatamaster/temperature","/deviceinfo/serialnumber"]
}
}
```

- Response:

```
{
"cid":4711,
"data":{"processdatamaster/temperature":{"code":200,"data":44},
"deviceinfo/serialnumber":{"code":200,"data":"000174210147"}},
"code":200
}
```

Example: Browsing device description

61150

Task: List all elements with the designation "status" and the profile "runcontrol".

Solution: Use the service querytree to browse the device description with the parameters "status" (name) and "runcorntrol" (profile)

- Request:

```
{
"cid":4711,
"adr":"querytree",
"code":"request",
"data":{
"profile":"runcontrol",
"name":"status"}
}
```

- Response:

```
{
"cid":4711,
"data":{
"adrList":[
"device/connections/mqttConnection/status",
"device/connections/mqttConnection/mqttCmdChannel/status"]},
"code":200
}
```

DNS support

61151

The IoT Core supports the Domain Name System (DNS) service. Instead of the concrete IP address, the corresponding host name can be used in requests. DNS can be used both for addressing the IoT core and for addressing network participants.

Example: Using DNS support

61152

Example 1: gettree

Synonymous requests:

- `http://192.168.23.70:8080/gettree`
- `http://example.org:8080/gettree`

Example 2: subscribe

Synonymous requests:

- with IP address

```
{
"cid": 11
"code": 10,
"adr." "setasync/datachanged/subscribe",
"data":{
"datatosend":["setasync"],
"callback":"192.168.23.70:8080/dump"}
}
```

- with host name

```
{
"cid": 11
"code": 10,
"adr": "setasync/datachanged/subscribe",
"data":{
"datatosend":["setasync"],
"callback":"http://example.com:8080/dump"}
}
```

9.2.4 IoT: Configuring access rights

59785

Substructure: `iotsetup`

Available data points:

Name	Description	Access
../accessrights	Access rights to the IO-Link master	rw

rw ... read and write

If in IoT and EtherCAT projection software the parameter [Access Rights] is = [EtherCAT + IoT], the parameter values set in the EtherCAT projection software will always apply.

If in IoT the parameter [Access Rights] is = [IoT only], set the parameter [Access Rights] = [Keep settings] in the EtherCAT projection software.

If in LR DEVICE the parameter [Access Rigts] is = [EtherCAT + IoT (read-only)], write access to the device configuration via LR DEVICE and IoT core services is blocked. To enable write access again, set the parameter to [EtherCAT + IoT] via fieldbus configuration software.

Changes of the parameter [Access Rights] will only be effective after restarting the IO-Link master (→ **Firmware: Reboot the device** (→ p. 32)).

9.2.5 IoT: Configuring IP settings

61155

Substructure: `iotsetup`

Available data points:

Name	Description	Access
../network/dhcp	Configuration of the IP settings of the IoT port	rw
../network/ipaddress	IP address of the IoT port	rw
../network/subnetmask	Subnet mask of the network segment	rw
../network/ipdefaultgateway	IP address of the network gateway	rw

rw ... read and write

Applicable services:

Name	Description
../network/setblock	Write all values of the substructure blockwise

Change the IP parameters in the substructure network only blockwise with the setblock service!

9.2.6 IoT: Configuring security mode

54683

The access to the IoT interface of the IO-Link master can be protected with a security mode:

Substructure: `iotsetup`

Available data points:

Name	Description	Access
../security/securitymode	active security mode	rw
../security/password	Password for authentication (Base64 coded)	w

rw ... read and write
w ... write only

Valid character set for the Base64 coding / decoding of the password: UTF-8
Online tool for coding / decoding: → www.base64encode.org)

Note: Security mode

54684

The security mode enables restricting access to the IO-Link master and the connected IO-Link devices from the IT network. In the activated security mode, the following restrictions apply:

- Access only with authentication (password-protected user account)
- Access only via secure https connection (Transport Layer Security - TLS)

The security mode only protects the access to the device via the IoT interface.
The standard value for users is: administrator
The set password cannot be read with getdata.

The current status of the security function can be read with the getidentity service (→ **Servicet: getidentity** (→ p. 125)).

For the authentication, the user must additionally provide the POST requests with a valid user name and password in the field "auth". The user name and the password will be shown as Base64-coded character strings (→ **Example: Request with authentication** (→ p. 46)).

The following requests can be done if the security mode is enabled, also without authentication:

- /getidentity
- /deviceinfo/vendor/getdata
- /deviceinfo/productcode/getdata

Example: Activate security mode

54701

Task: Activate the security mode of the IO-Link interface of the IO-Link master. Set the password "password" (Base64 coded: cGFzc3dvcmQ=)

Solution: The activation sonsists of 2 steps:

1 Activate security mode

Use service setdata with datapoint iotsetup/security/securitymode to activate the security mode.

- Request:

```
{
"code":"request",
"cid":-1,
"adr":"/iotsetup/security/securitymode/setdata",
"data":{"newvalue":"1"}
}
```

- Response:

```
{
"cid":-1,
"code":200
}
```

2 Set required password

Use service setdata with data point iotsetup/security/password to set the required password.

- Request:

```
{
"code":"request",
"cid":-1,
"adr":"/iotsetup/security/password/setdata",
"data":{"newvalue":"cGFzc3dvcmQ="}
}
```

- Response:

```
{
"cid":-1,
"code":200
}
```

Example: Request with authentication

54685

Task: The temperature of the IO-Link master is to be read. The security function is enabled (current password: password).

Solution: Read the data point processdatamaster/temperature with the getdata service. The request must be sent using https. The user name and the password are transferred as a Base64-coded character string ("administrator" = "YWRtaW5pc3RyYXRvcg==", "password" = "cGFzc3dvcmQ=")

- Request:

```
{
"code":"request",
"cid":-1,
"adr":"processdatamaster/temperature/getdata",
"auth":{"user":"YWRtaW5pc3RyYXRvcg==","passwd":"cGFzc3dvcmQ="}
}
```

- Response:

```
{
"cid":-1,
"data":{"value":37},
"code":200
}
```


Example: reset password

54686

Task: The existing password is to be reset.

Solution: To reset a password, disable the security mode. To disable it, enter the user name and the password (the fields "user" and "passwd").

- Request:


```
{
"code":"request",
"cid":-1,
"adr":"iotsetup/security/securitymode/setdata",
"data":{"newvalue":0},
"auth":{"user":"YWRtaW5pc3RyYXRvcg==","passwd":"SW9UNGlmbQ=="}
}
```


- Response:


```
{
"cid":-1,
"code":200
}
```

9.2.7 Fieldbus: Configuring the fieldbus interface

33892

The AL1330 in das EtherCATnetwork can be integrated via the field bus interface (ports X21 / X22).
Substructure: `fieldbussetup`
Available data points:

Name	Description	Access
../hostname	Name of the IO-Link master in the fieldbus project	rw
../fieldbusfirmware	Firmware version of the IO-Link master	r
../connectionstatus	Status of the connection to the EtherCAT network	r

r ... read only
rw ... read and write

9.2.8 IO-Link ports: Setting the operating mode of pin 4 (US)

59793

Substructure: `iolinkmaster/port[n]` (n = 1...4).
Available data points:

Name	Description	Access
../mode	Operating mode of the IO-Link port	rw*
../mastercycletime_preset	Cycle time of the data transfer at the IO-Link port (value in ms)	rw*
../mastercycletime_actual	Current cycle time of the data transfer at the IO-Link port (value in ms)	r
../comspeed	Data transfer rate of the IO-Link port	r

r ... read only
rw ... read and write
* ... only changeable, if the <Feldsbus> plc is not in RUNNING state

9.2.9 IO-Link ports: Configuring device validation and data storage

59792

Substructure: `iolinkmaster/port[n]` (n = 1...4).

Available data points:

Name	Description	Access
../validation_datastorage_mode	Response of the IO-Link port when a new IO-Link device is connected	rw*
../validation_vendorid	IO-Link ID of the manufacturer that is to be validated	rw*
../validation_deviceid	IO-Link ID of the device that is to be validated	rw*
../datastorage	Structure for port data storage	rw
../datastorage/maxsize	Maximum size of the data storage content (in bytes)	r
../datastorage/chunksize	Size of a data segment (in bytes)	r
../datastorage/size	Size of the data storage content (in bytes)	r

r ... read only
rw ... read and write
* ... can only be changed if the EtherCAT PLC is not in RUNNING state

Applicable services:

Service	Description
../validation_useconnecteddevice	Validate the IO-Link device connected to the IO-Link port*
../datastorage/getblobdata	Reading the content of the data storage area
../datastorage/stream_set	Transfer an individual data segment*
../datastorage/start_stream_set	Start sequential transmission of several data segments*

* ... can only be changed if the EtherCAT PLC is not in the RUNNING state

Example: Clone the Data Storage of an IO-Link port

52344

Task: Save the Data Storage of IO-Link port X02 of IO-Link master 1 and restore the data at IO-Link master 2.

Solution: The cloning process consists of 2 steps. In the first step, the Data Storage of the IO-Link port of IO-Link master 1 is saved. In the second step, the saved data is restored at the Data Storage of port IO-Link port of IO-Link master 2.

Save Data Storage:

1 Preparations

- ► Read size of segments of Data Storage (h = number of bytes):
  {"code":"request", "cid": -1,"adr":"/iolinkmaster/port[2]/datastorage/chunksize/getdata"}
  Example: h = 256
- ► Read total size of Data Storage area (g = number of bytes):
  {"code": "request", "cid": -1, "adr": "/iolinkmaster/port[2]/datastorage/size/getdata"}
  Example: g = 550
- ► Calcuate the number of reading steps n: n = first integer value to which the following applies: g < n*h
  Example: n= 3, because 550 < 3*256

2 Read Data Storage of IO-Link port

- ► Read Data Storage segment by segment ("pos" is the byte offset, at which the reading process with length "length" starts).
  {"code": "request", "cid": -1, "adr": "/iolinkmaster/port[2]/datastorage/getblobdata", "data": {"pos": 0, "length": h}}
  {"code": "request", "cid": -1, "adr": "/iolinkmaster/port[2]/datastorage/getblobdata", "data": {"pos": h, "length": h}}
  {"code": "request", "cid": -1, "adr": "/iolinkmaster/port[2]/datastorage/getblobdata", "data": {"pos": 2*h, "length": h}}

...
{"code": "request", "cid": -1, "adr": "/iolinkmaster/port[2]/datastorage/getblobdata", "data": {"pos": n*h, "length": h}}
Example:
1st read request: pos = 0, length = 256
2nd read resquest: pos = 256, length =256
3rd read request: pos = 512, length = 256

> Each segment value will be returned as BASE64 coded string.

► Join segments.

Restore Data Storage:

1 Preparations

► Determine the size of the saved Data Storage value (n = number of bytes).
Example: n = 550

► Read size of segments (s = number of bytes):
{"code":"request", "cid": -1,"adr":"/iolinkmaster/port[1]/datastorage/chunksize/getdata"}
Example: s = 256

2 Transfer Data Storage strings

► Start transfer of Data Storage string ("size" = size of Data Storage string):
{"code":"request", "cid": -1, "adr":"/iolinkmaster/port[1]/datastorage/start_stream_set", "data": {"size": n}}
Example: size = 550

► Transfer Data Storage string segment by segment ("value" = string value of length s):
{"code": "request", "cid": -1, "adr": "/iolinkmaster/port[1]/datastorage/stream_set", "data": {"value": "aWZtfgIAAABBTDF4NXhfY25faXRfdDIuMi43Nw..."}

9.2.10 IO-Link ports: Configuring data transfer to LR AGENT or LR SMARTOBSERVER

59795

Substructure: `iolinkmaster/port[n]` (n = 1...4).

Available data points:

Name	Description	Access
../senddatatosmob	Process data to LR AGENT or LR SMARTOBSERVER	rw

rw ... read and write

9.2.11 IO-Link ports: Reading / writing process data

61156

Substructure: `iolinkmaster/port[n]` (n = 1...4)

Available data points:

Name	Description	Access
../pin2in	Value of the digital input on pin 2 of the IO-Link port	r
../iolinkdevice/pdin	Value of the IO-Link input on pin 4 of the IO-Link port	r
../iolinkdevice/pdout	Value of the IO-Link output on pin 4 of the IO-Link port	rw*

r ... read only
rw ... read and write
*... can only be changed if the fieldbus PLC is not in RUNNING state

Example: Read IO-Link process data (operating mode "IO-Link")

33842

Task: Read the current measured value of the ifm temperature sensor TN2531 at IO-Link port X02
Solution: Read the data point for the process input data with the `getdata` service.

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"/iolinkmaster/port[2]/iolinkdevice/pdin/getdata"
}
```

- Response:

```
{
"cid":4711,
"data":{"value": "03C9"},
"code":200
}
```

The return value is given in hexadecimal format. Besides the temperature value the return value comprises additional information (→ IO Device Description (IODD) of the sensor). The temperature value is shown in bits 2 to 15.

0x03C9 = 0b**1111001**001

Temperature value: 0b11110010 = 242

Therefore: The current temperature value is 24.2 °C.

Example: Writing IO-Link value (operating mode "IO-Link")

59804

Task: Switch on the buzzer of DV2500 at IO-Link Port X2. The DV2500 operates in On/Off mode.

Solution: The IODD of the DV2500 shows the structure of the IO-Link process value (→ e.g. LED activity). The buzzer will be switched using bit 40 of the process value (OFF = 0, ON = 1).

To switch the buzzer:

1. Read the current process value (→ **Example: Read IO-Link process data (operating mode "IO-Link")** (→ p. 51)).
2. Set bit 40 of the read value to 1.
3. Write the process value to the IO-Link device.

Example:

Read process value:

0x0000 0000 004D = 0b0000 0000 0000 0000 0000 0000 0000 0000 0000 0000 0100 1101

New process value:

0b0000 000**1** 0000 0000 0000 0000 0000 0000 0000 0000 0100 1101 = 0x0100 0000 004D

- Request:

```
{
"code":"request",
"cid":10,
"adr":"iolinkmaster/port[2]/iolinkdevice/pdout/setdata",
"data":{"newvalue":"01000000004D"}
}
```

- Response:

```
{
"cid":10,
"code":200
}
```

Example: Writing digital output (operating mode "DO")

59803

Task: Set the output value of the IO-Link devices at IO-Link Port X1 to "ON". The operating mode of the IO-Link port is "Digital Output (DO)".

Solution: Write the value 1 to data point pdout. The value has to be written as hexadecimal value with a length of 1 byte (OFF = "00", ON = "01").

- Request:

```
{
"code":"request",
"cid":10,
"adr":"iolinkmaster/port[1]/iolinkdevice/pdout/setdata",
"data":{"newvalue":"01"}
}
```

- Response:

```
{
"cid":10,
"code":200
}
```

Example: Reading digital input (operating mode "DI")

59802

Task: Read the current input value of the IO-Link device at IO-Link port X5. The operating mode of the IO-Link port is "Digital Intput (DI)".

Solution: Read the value of data point pdin. The value will be returned as hexadecimal value with a length of 1 byte (OFF = "00", ON = "01"").

- Request:


```
{
"code":"request",
"cid":10,
"adr":"iolinkmaster/port[5]/iolinkdevice/pdin/getdata"
}
```


- Response:


```
{
"cid":10,
"data":{"value":"00"},
"code":200
}
```

9.2.12 IO-Link ports: Indicating port events

59796

Substructure: iolinkmaster/port[n] (n = 1...4).

Available data points:

Name	Description	Access
../portevent	Indication of the following events at IO-Link port n: ▪ plugging IO-Link device ▪ pulling IO-Link device ▪ changing operating mode of IO-Link port	r

r ... read only



Subscribing events: → **Subscribing to notifications** (→ p. 60)

9.2.13 IO-Link devices: Accessing parameters

59800

The ifm IoT Core supports the configuration of the connected IO-Link devices. A parameter is accessed via IO-Link index and subindex (→ IO Device Description (IODD) of the device).

Substructure: `iolinkmaster/port[n]/iolinkdevice` (n = 1...4)

Applicable services:

Service	Description
../iolreadacyclic	Read a parameter of an IO-Link device (acyclic)
../iolwriteacyclic	Write a parameter of an IO-Link device (acyclic)

Example: Read the parameter value of an IO-Link device

33847

Task: Read the serial number of the ifm temperature sensor TN2531 at IO-Link port X02

Solution: Read the serial number with the `iolreadacyclic` service from the IO-Link device (index: 21, subindex: 0)

- **Request:**

```
{
"code":"request",
"cid":4711,
"adr":"/iolinkmaster/port[2]/iolinkdevice/iolreadacyclic",
"data":{"index":21,"subindex":0}
}
```

- **Return:**

```
{
"cid":4711,
"data":{"value":"4730323134323830373130"},
"code":200
}
```

The returned value is given in hexadecimal format. The conversion of the HEX value in a STRING value is: G0214280710

Example: Change the parameter value of an IO-Link device

33844

Task: Set the output configuration OUT1 of the ifm temperature sensor TN2531 at IO-Link port X02 to the value "Hnc / hysteresis function, normally closed".

Solution: Change the parameter [ou1] of the sensor to the value 4 using the iolwriteacyclicdata service. The parameter can be accessed via IO-Link index 580, subindex 0 (→ IO-Link description of the sensor).

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"/iolinkmaster/port[2]/iolinkdevice/iolwriteacyclic",
"data":{"index":580,"subindex":0,"value":"34"}
}
```

The value has to be given in hexadecimal format. The conversion of the STRING value in a HEX value is: 34.

- Response:

```
{
"cid":4711,
"code":200
}
```

9.2.14 IO-Link devices: Reading an writing device information

59797

Substructure: `iolinkmaster/port[n]/iolinkdevice` (n = 1...4)
Available data points:

Name	Description	Access
../status	Status of the connected IO-Link device	r
../vendorid	IO-Link ID of the vendor	r
../deviceid	IO-Link ID of the IO-Link device	r
../productname	Product name of the IO-Link device	r
../serial	Serial number of the IO-Link device	r
../applicationspecifictag	Device-specific identification (application tag)	rw

r ... read only
rw ... read and write

9.2.15 IO-Link devices: Indicating IO-Link events

59798

Substructure: `iolinkmaster/port[n]/iolinkdevice` (n = 1...4).
Available data points:

Name	Description	Access
../iolinkevent	Indication of IO-Link events	r

r ... read only



Subscribing events: → **Subscribing to notifications** (→ p. 60)

9.2.16 Gateway: Resetting, rebooting and localising the device

59790

Substructure: `firmware`
Applicable services:

Name	Description
../factoryreset	Reset IO-Link master to factory settings
../reboot	Reboot IO-Link master
../signal	Trigger the flashing of the status LED

9.2.17 Gateway: Reading device information

52254

Substructure: `deviceinfo`

Available data points:

Name	Description	Access
../productcode	Article number	r
../vendor	Manufacturer	r
../devicefamily	Device family	r
../hwrevision	Hardware revision	r
../serialnumber	Serial number	r
../revision	Firmware version	r
../bootloaderrevision	Bootloader version	r
../extensionrevisions	Firmware and bootloader version	r
../fieldbustype	Fieldbus	r

r ... read only

Additional information about the AL1330 can be read with the service `getidentity` (→ **Servicet: getidentity** (→ p. 125)).

9.2.18 Gateway: Reading status and diagnostic information

61157

Substructure: `processdatamaster`

Available data points:

Name	Description	Access
../temperature	Temperature of the IO-Link master (value in °C)	r
../voltage	Present voltage value of the supply voltage US (value in mV)	r
../current	Present current value of the sensor supply US (value in mA)	r
../supervisionstatus	Status of the device supply US	r

r ... read only

9.2.19 Gateway: Updating the firmware

59789

Substructure: `firmware`

Available data points:

Name	Description	Access
../version	Software version	r
../type	Software type	r
../container	Structure for updating the firmware	w
../container/maxsize	Maximum size of the container structure (in bytes)	r
../container/chunksize	Size of a data segment (in bytes)	r
../container/size	Size of the container content (in bytes)	r

r = only read
w = write only

Applicable services:

Name	Description
../install	Install firmware transferred to the IO-Link master
../container/stream_set	Transfer an individual data segment
../container/start_stream_set	Start sequential transmission of several data segments

Example: Update firmware

52252

Task:

Update the firmware of the device; size of the firmware file: 356676 bytes

Solution:

The firmware is transferred to the device in fragments (chunks). The size of the fragments depends on the size of the flash memory of the IO-Link master. To transfer the firmware, the firmware file must be converted into a character string using BASE64.

1 Preparations

► Determine the size of the fragments (g = number of bytes):
{"code":"request", "cid": -1, "adr":"/firmware/container/chunksize/getdata"}

► Convert the firmware file into a BASE64 string.

2 Start the transfer of the firmware

► Start the transfer of the firmware via the service start_stream_set (parameter "size": size of the firmware file):
{"code":"request", "cid": -1, "adr":"/firmware/container/start_stream_set", "data":{"size":356676}}

3 Load the firmware into the flash memory of the IO-Link master

► Send the BASE64 string of the firmware file to the IO-Link master fragment by fragment (value = string value with length g).
{"code": "request", "cid": -1, "adr": "/firmware/container/stream_set", "cid": -1, "data": {"value": "aWZtfgIAAABBTDF4NXhfY25faXRfdDIuMi43Nw..."}

► Repeat step 3 until all fragments of the firmware file have been sent to the IO-Link master.

> IO-Link master stores the segments received in the container area.

4 Install firmware

► Start the installation of the transmitted firmware.
{"code": "request", "cid": -1, "adr": "/firmware/install", "data": {}}

9.2.20 Gateway: Setting the application tag

59791

Substructure: `devicetag`

Available data points:

Name	Description	Access
../applicationtag	Name of the IO-Link master (application tag)	rw

rw ... read and write

For the storage of the applicationtag 32 bytes are available on the IO-Link master. If the memory area is exceeded during writing with setdata, the IoT core aborts the write process and returns the diagnostics code 400.

When writing the application tag, note the different memory requirements of the individual UTF-8 characters:

- characters 0-127: 1 byte per character
- characters >127: more than 1 byte per character

Example: Change name of the IO-Link master

a33823

Task: Set the name of the IO-Link master to AL1330 for the representation in the LR SMARTOBSERVER.

Solution: Change the parameter [Application Tag] with the setdata service to the value [AL1330].

The data point of the parameter [Application Tag] in the device description object is /devicetag/applicationtag.

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"/devicetag/applicationtag/setdata",
"data":{"newvalue":"AL1330"}
}
```

- Response:

```
{"cid":4711,"code":200}
```

9.2.21 Subscribing to notifications

61159

If a data point has the sub-element `datachanged`, the user can subscribe to notifications on value and condition changes. Notifications can be triggered by the expiration of a timer or an event. The IoT Core supports the output of notifications in CSV or JSON format.

Available data points:

Name	Description	Access
timer[x]/counter	Timer for triggering a notification	rw
timer[x]/interval	Cycle time of the update of the subscribed values	rw
iolinkmaster/port[n]/portevent	Display of the following events on IO-Link port n: ▪ IO-Link device connected ▪ IO-Link device disconnected ▪ Operating mode of the IO-Link port changed	rw
iolinkmaster/port[n]/iolinkdevice/iolinkevent	Display of IO-Link events	rw

r ... read only
rw ... read and write
x = [1,2]
n = 1...4

Applicable services:

Name	Description
../datachanged/subscribe	Subsrscibe to notification
../datachanged/unsubsribe	Unsubscribe notification
../datachanged/getsubscriptioninfo	Show information about notifications

Additionally, the user can use **Service: getsubscriberlist** (→ p. 126) show all active subscriptions.

Example: Subscribing to notifications

61160

Task: The current values of the following parameters are to be sent regularly to a network server with IP address 192.168.0.4:

- cyclic input data of the IO-Link Devices an IO-Link port X02
- Operating temperature of the IO-Link master.

Solution: Subscribe to the required data using the subscribe service.

The following options are additionally available:

- via WebSockets (ws://): **Example: Subscribing notifications via WebSocket** (→ p. 63)
- via MQTT (mqtt://): **Example: Configuring the MQTT command channel** (→ p. 67)

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"/timer[1]/counter/datachanged/subscribe",
"data":
{
```

```
"callback":"http://192.168.0.4:80/temp",
"datatosend":[
"/iolinkmaster/port[2]/iolinkdevice/pdin",
"/processdatamaster/temperature"]
}
}
```

In addition, the time interval of the timer[1] must be set to a value between 500 ms and 2147483647 ms.

- Request:

```
{
"code":"request",
"cid":4712,
"adr":"/timer[1]/interval/setdata",
"data":{"newvalue":500}
}
```

- Response:

```
{
"cid":4712,
"code":200
}
```

- Notification (JSON)

```
{
"code":"event",
"cid":4711,
"adr":"",
"data":{
"eventno":"6317",
"srcurl":"/timer[1]/counter/datachanged",
"payload":{
"/timer[1]/counter":{"code":200,"data":1},
"/processdatamaster/temperature":{"code":200,"data":39},
"/iolinkmaster/port[2]/iolinkdevice/pdin":{"code":200,"data":"03B0"}}}
}
```

Example: Changing a subscription

61161

Task: The existing subscription (**Example: Subscribing to notifications** (→ p. 60)) is to be changed. Instead of the temperature of the IO-Link master, the operating voltage applied is to be transmitted.

Solution: Overwrite the existing subscription. For this purpose, the parameter values for "cid" and "callback" in the request must be the same as those of the existing subscription.

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"/timer[1]/counter/datachanged/subscribe",
"data":{
"callback":"http://192.168.0.4:80/temp",
"datatosend":[
"/iolinkmaster/port[2]/iolinkdevice/pdin",
"/processdatamaster/voltage"]}
}
```

Example: Subscribing to notifications in CSV format

61162

Task: Every 2 seconds, the current values of the following parameters are to be sent to a network server with the IP address 192.168.0.4

- cyclic IO-Link input data of the IO-Link device at port X02
- Operating temperature of the IO-Link master.

The data should be transmitted in CSV format (comma separator).

Solution:

► Use the subscribe service to subscribe to the required data and set the output format to "csv0".



Data in CSV format can only be sent via TCP protocol.

- Request:

```
{
"cid": 1,
"adr":"/timer[1]/counter/datachanged/subscribe",
"code":"request",
"callback":"tcp://192.168.50.59:1883/topic",
"codec":"csv0",
"data":{
"datatosend":[
"/iolinkmaster/port[2]/iolinkdevice/pdin",
"/processdatamaster/temperature"]}
}
```

► Set the interval of the timer to 2 seconds:

- Request:

```
{
"code":"request",
"cid":4712,
"adr":"/timer[1]/interval/setdata",
"data":{"newvalue":2000}
}
```

The cyclically sent notification has the following structure:

```
/timer[1]/counter/datachanged,6317,200,1,200,39,200,03B0
```

Example: Unsubscribing from notifications

61163

Task: The existing subscription (**Example: Subscribing to notifications** (→ p. 60)) is to be deleted.

Solution: Use the unsubscribe service to delete the subscription. For this purpose, the value of the parameter "callback" in the request must be equal to the value of the existing subscription.

```
{
"code":"request",
"cid":4711,
"adr":"/timer[1]/counter/datachanged/unsubscribe",
"data":{
"callback":"http://192.168.0.4:80/temp"
}
```

Example: Checking subscriptions

61164

Task: Information about the existing subscription (**Example: Subscribing to notifications** (→ p. 60)Show **Example: Subscribing to notifications** (→ p. 60)).

Solution: Use the service getsubscriptioninfo and the parameter values cid, "adr" and "callback" of the existing subscription to retrieve the information.

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"/timer[1]/counter/datachanged/getsubscriptioninfo",
"data":{
"callback":"http://192.168.0.4:80/temp"}
}
```

- Response:

```
{
"cid." 4711,
"data":{
"callback":"http://192.168.0.4:80/temp",
"datatosend":[
"/iolinkmaster/port[2]/iolinkdevice/productname",
"/iolinkmaster/port[2]/iolinkdevice/pdin",
"/processdatamaster/temperature"]},
"code":200
}
```

9.2.22 Using Web Socket

61165

The IoT Core supports communication via WebSocket protocol. With Web Sockets, the user can establish a full-duplex communication channel via a TCP connection.

WebSockets can be used for the following services:

- subscribe / unsubscribe

Maximum number of WebSocket connections: 8

Fail-safe WebSocket connections (wss://) are not supported.

To transmit notifications via a WebSockets connection:

► Establish the WebSocket connection (e.g. "`ws://192.168.0.55:80/websocket`")

- Option 1: without parameter "callback”

► make subscribe/unsubscribe request without parameter "callback".

> IoT-Core sends notifications about existing WebSocket connections.

- Option 2. with parameter "callback”

► make subscribe/unsubscribe requests with parameter "callback" ("`ws:///myTopic`").

> IoT-Core sends notifications about existing WebSocket connections to the topic `myTopic`.

Example: Subscribing notifications via WebSocket

61166

Task: The current values of the following parameters are to be sent regularly to the data sink `myTopic` via an existing WebSocket connection:

- Product name of the IO-Link Devices an IO-Link port X02
- cyclic input data of the IO-Link Devices an IO-Link port X02
- Operating temperature of the IO-Link master.

Solution: Subscribe to the required data using the subscribe service.

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"/timer[1]/counter/datachanged/subscribe",
"data":{
"callback":"ws:///myTopic",
"datatosend":[
"/iolinkmaster/port[2]/iolinkdevice/productname",
"/iolinkmaster/port[2]/iolinkdevice/pdin",
"/processdatamaster/temperature"]}
}
```

If the notifications are to be transmitted via the existing WebSocket connection, but without a special data sink, the callback parameter is not required.

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"/timer[1]/counter/datachanged/subscribe",
"data":{
"datatosend":[
"/iolinkmaster/port[2]/iolinkdevice/productname",
"/iolinkmaster/port[2]/iolinkdevice/pdin",
"/processdatamaster/temperature"]}
}
```

9.2.23 MQTT support

61168

The IoT Core supports the MQTT protocol. The protocol allows an MQTT client to communicate with the IoT Core via an MQTT broker to request and receive data. The IoT Core can publish data via the MQTT connection.

Configuring the MQTT command channel

61169

To enable MQTT communication, the user needs to activate and configure an MQTT command channel.

Substructure: `connections/mqttConnection`

Name	Description	Access
../type	Type of the connection (MQTT)	r
../status	Global MQTT status	r
../status/preset	Presetting of the MQTT status; Basic settings: running	r
../MQTTSetup	Substructure for general MQTT settings	w
../MQTTSetup/QoS	Quality of Service of the MQTT communication ▪ 0: QoS Level 0 - PUBLISH (without confirmation) ▪ 1: QoS Level 1 - PUBLISH > PUBREC (one-time confirmation) ▪ 2: QoS Level 2 - PUBLISH > PUBREC > PUBREL > PUBCOMP (double confirmation)	rw
../MQTTSetup/version	MQTT version	r
../mqttCmdChannel	Substructure of the MQTT command channel	w
../mqttCmdChannel/type	Type of the MQTT command channel	r
../mqttCmdChannel/status	Status of the MQTT command channel	r
../mqttCmdChannel/status/preset	Presetting of the MQTT status; Basic setting: stopped	r
../mqttCmdChannel/mqttCmdChannelSetup	Structure for settings of the command channel	w
../mqttCmdChannel/mqttCmdChannelSetup/brokerIP	IP address of the MQTT broker	rw
../mqttCmdChannel/mqttCmdChannelSetup/brokerPort	Port number of the MQTT broker	rw
../mqttCmdChannel/mqttCmdChannelSetup/cmdTopic	Designation of the MQTT topic	rw
../mqttCmdChannel/mqttCmdChannelSetup/defaultReplyTopic	Standard response topic	rw

Applicable services:

Name	Description
../status/start	Enable MQTT
../status/stop	Deactivate MQTT
../status/reset	Reset MQTT
../mqttCmdChannel/status/start	Activate MQTT command channel
../mqttCmdChannel/status/stop	Deactivate MQTT command channel
../mqttCmdChannel/status/reset	Reset MQTT command channel

Notes on the states of an MQTT connection: **Note: Connection states** (→ p. 66)

To create an MQTT connection, perform the following steps in sequence:

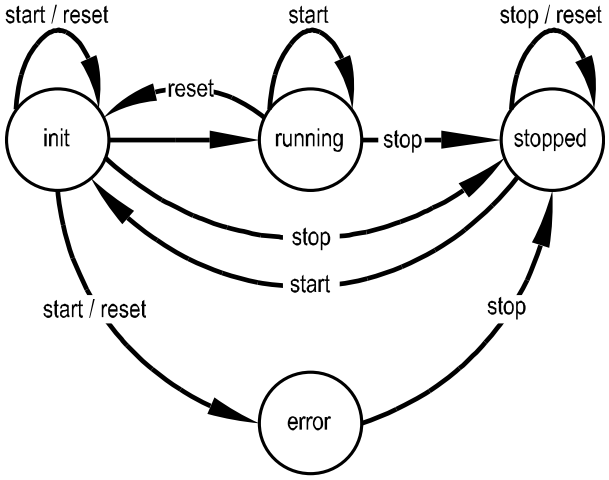
Ensure that the MQTT broker can be reached and that the selected port of the MQTT broker is enabled for data transmission.
Max. number of simultaneous MQTT connections: 10
Wildcards "+" and "#" in topics are not supported.

- ► Activate MQTT command channel.
- ► Set the IP address of the MQTT.
- ► Set the port number of the MQTT broker.
- ► Set topic.
- ► Set standard response topic.
- > The command channel is created with the selected properties.
- > The user can publish on the topic with the IoT Core.
- > MQTT clients can subscribe to the topic.

Note: Connection states

61170

The following status diagram shows the influence of the services "start", "stop" and "reset" on the status of an MQTT connection:



After the initialisation in the "init" state has been completed, the connection automatically changes to the "running" state.

The connection automatically switches to the "error" state if at least one of the following events occurs:

- no MQTT broker available

Example: Configuring the MQTT command channel

61171

Task: Configuring and activating the MQTT command channel (IP address MQTT broker: 192.168.82.100, port: 1883, topic: abc).

Solution:

► Check whether MQTT broker can be reached and the port has been released.

► Activate command channel

- Request:

```
{
"code":"request",
"cid":4711,
"adr":"/connections/mqttConnection/MQTTSetup/mqttCmdChannel/status/start"
}
```

► Set the IP address of the MQTT broker/server.

- Request:

```
{
"code":"request",
"cid":4712,
"adr":"/connections/mqttConnection/mqttCmdChannel/mqttCmdChannelSetup/brokerIP/set
data"
"data":{"192.168.82.100"}
}
```

► Set the port number of the MQTT broker/server.

- Request:

```
{
"code":"request",
"cid":4713,
"adr":"/connections/mqttConnection/mqttCmdChannel/mqttCmdChannelSetup/brokerPort/s
etdata"
"data":{"1883"}
}
```

► Set topic.

- Request:

```
{
"code":"request",
"cid":4714,
"adr":"/connections/mqttConnection/mqttCmdChannel/mqttCmdChannelSetup/cmdTopic/set
data"
"data":{"abc"}
}
```

► Set standard response topic.

- Request:

```
{
"code":"request",
"cid":4715,
"adr":"/connections/mqttConnection/mqttCmdChannel/mqttCmdChannelSetup/defaultReply
Topic/setdata"
"data":{"xyz"}
}
```

► Set the QoS.

- Request:

```
{
"code":"request",
"cid":4716,
"adr":"/connections/mqttConnection/MQTTSetup/QoS/setdata",
"data":{"QoS2"}
}
```

Example: Publish the temperature to an MQTT broker

54687

Task: Publish the temperature of the IO-Link master to an MQTT broker (IP address MQTT broker: 192.168.82.100, port: 1883, topic: abc

Solution:

- Request:

```
{
"code":"request",
"cid":-1,
"adr":"/timer[1]/counter/datachanged/subscribe",
"data":{
"callback":"mqtt://192.168.82.100:1883/abc",
"datatosend":["processdatamaster/temperature"}
}
```

- Response:

```
{
"cid":-1,
"code":200
}
```

9.2.24 Using the IoT-Core Visualizer

Content

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Searching for elements in the device tree 72
Configuring IO-Link the master 73
Reading and writing process data 74
Updating the firmware 75

61173

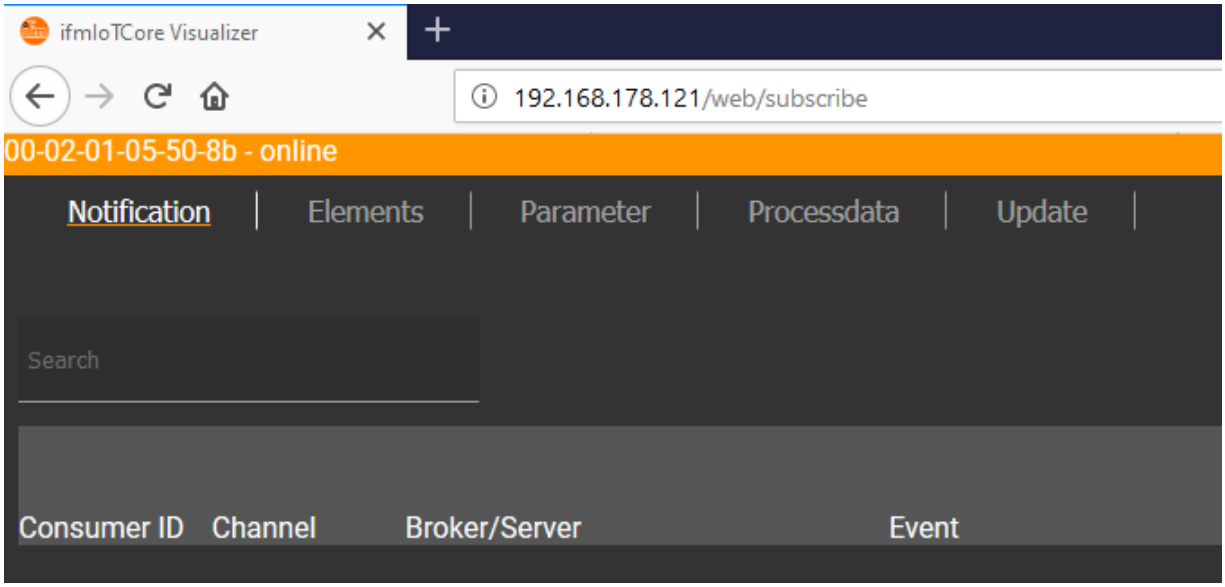
The ifm-IoT Core Visualizer of the IO-Link master provides a graphical user interface for accessing functions of the ifm-IoT Core.

To start the IoT Core Visualizer:

► Start web browser.

► Call the following address: http://ipaddress/web/subscribe

> Browser shows IoT Core Visualizer:



The navigation menu gives the user access to the following functions:

- [Notification]: Creating and managing notifications (subscribe / unsubscribe)
- [Elements]: Searching for elements in device description
- [Parameter]: Configuring IO-Link master
- [Processdata]: Reading and writing process data
- [Update]: Updating the firmware of the IO-Link master

Managing notifications

61174

The menu page allows you to perform the following functions

- Creating notifications
- Showing active notifications
- Deleting notifications (single, all)

Requirements:

- Iot-Core Visualizer has been started.

► Click on [Notification].

> The menu page for managing notifications appears.

> The menu page shows all registered notifications in a table

Creating a new notification

61175

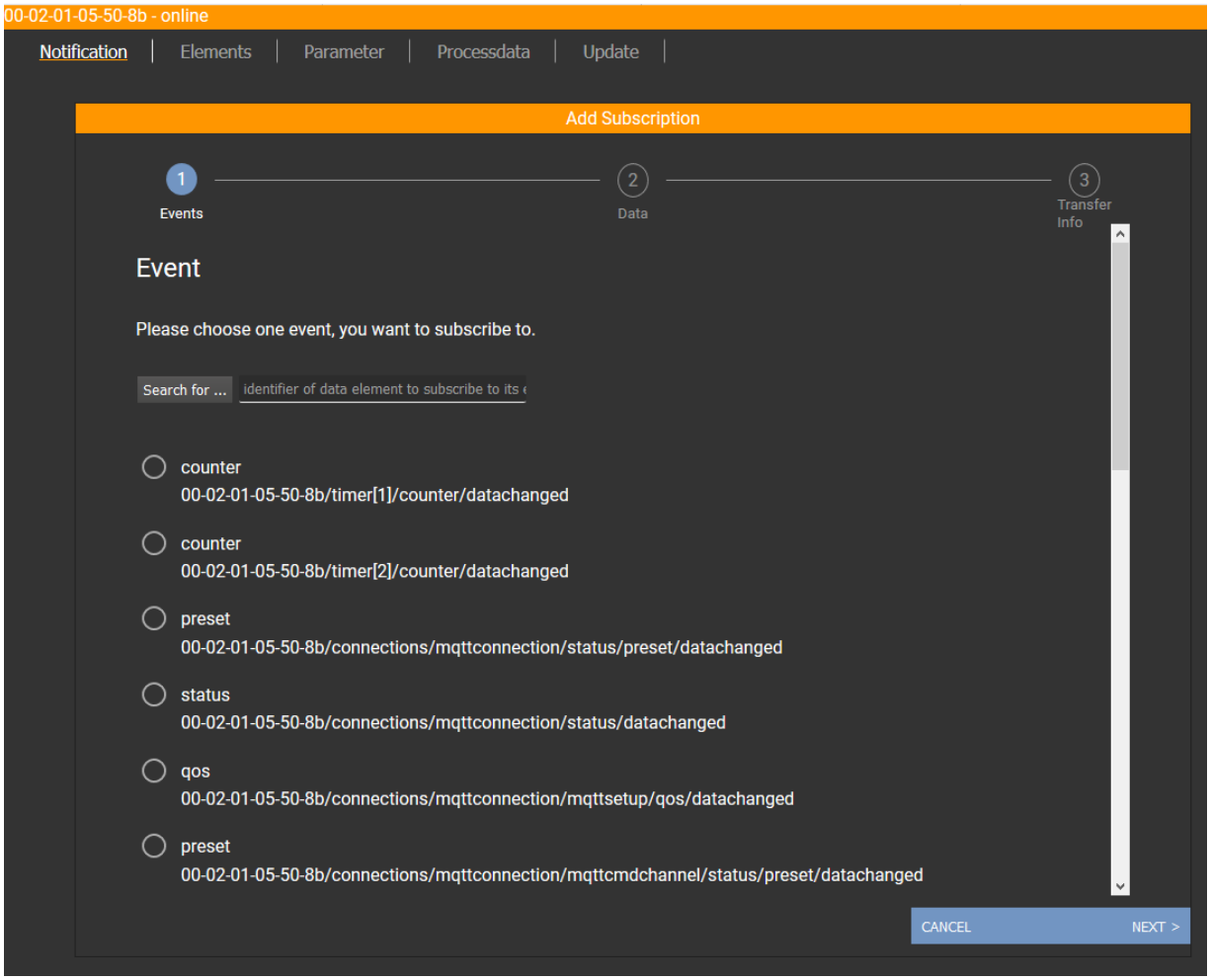
A wizard is used to register new notifications.

Requirements:

- The [Notification] menu page is open.

► Click on [+] on the right side of the table.

> The wizard for the creation of notifications appears.



► Use the wizard to enter the required notification parameters step by step.
> Created notification subscription is displayed in the table.

For cyclical notifications via timer[1] or timer[2], the user also needs to set the interval time of the timer in question.

Deleting a notification

61176

Requirements:

- The [Notification] menu page is open.
- At least one notification is active.

► Click on [x] in the column [Unsubscribe].
> The selected notification will be deleted (unsubscribe).

Searching for elements in the device tree

61177

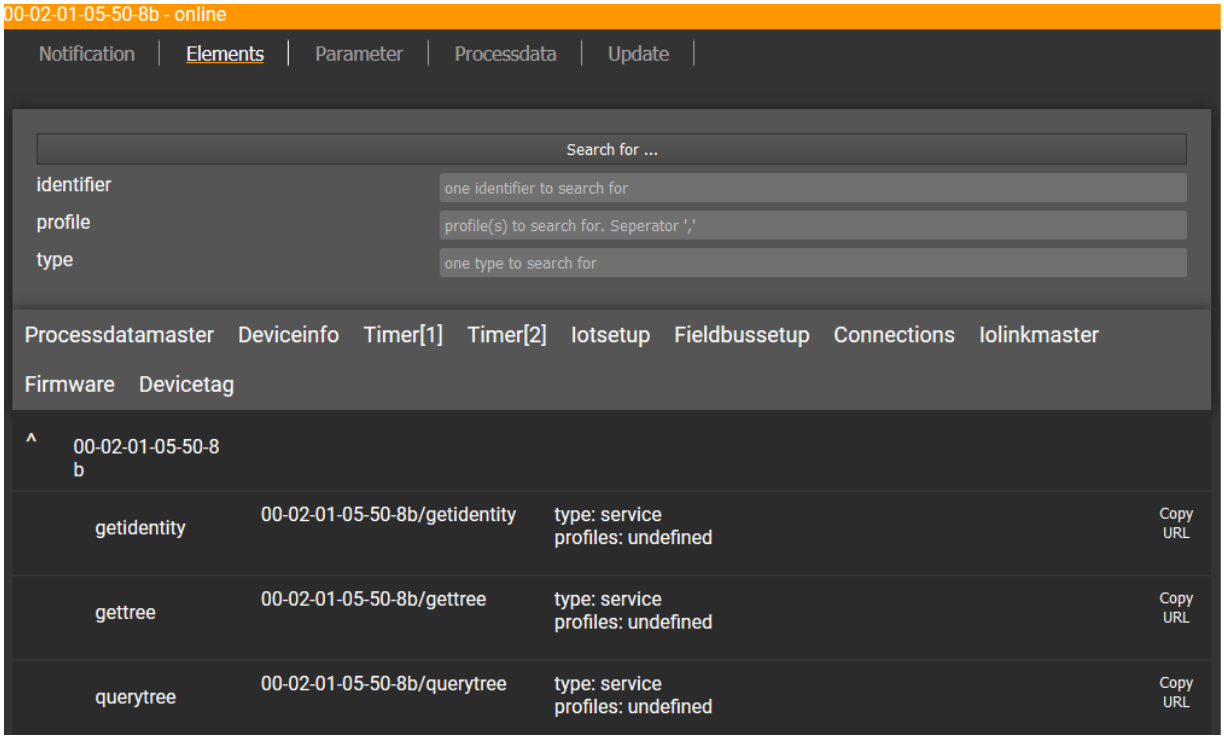
The [Elements] menu page allows you to search the device description for elements with specific properties (status, profile, name) and to output the results.

Requirements:

- Iot-Core Visualizer has been started.

► Click on [Elements].

> The input mask appears.



► Enter the search criteria of the required item in the [identifier], [profile] and [type] boxes.

► Click on [Search for ...].

> IoT-Core Visualizer searches device description for elements with selected search criteria.

> The result list shows all elements found.

Configuring IO-Link the master

61178

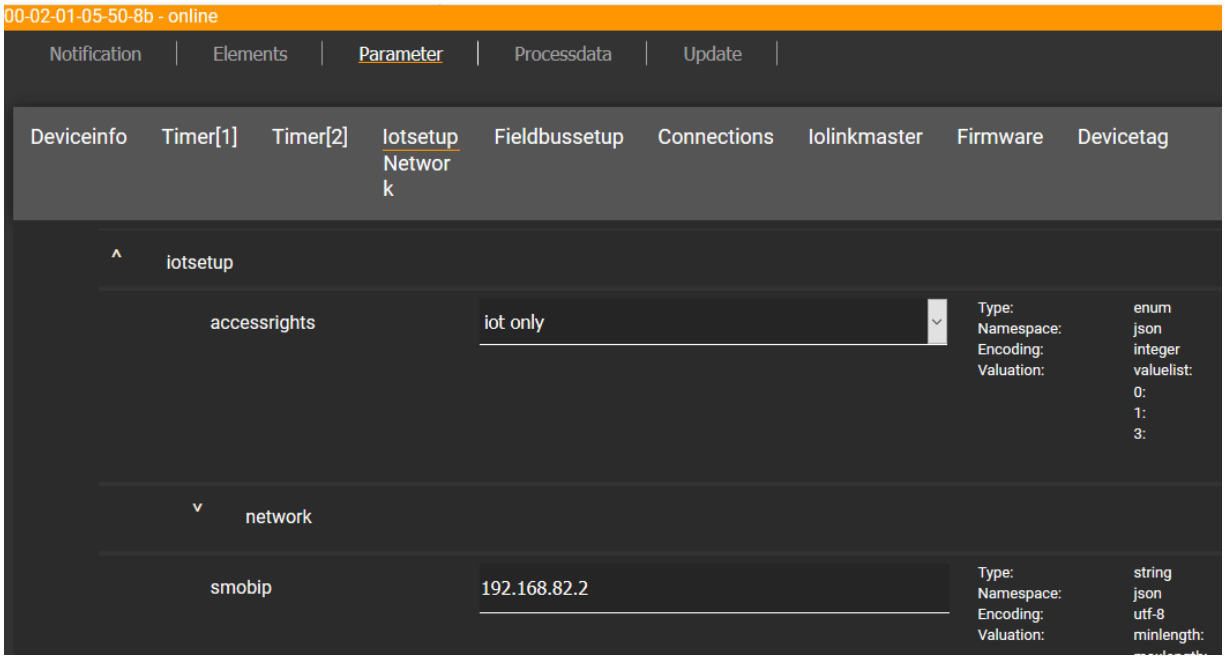
The [Parameter] menu page allows you to configure the IO-Link master.
Available options:

- Reading and writing individual parameters
- Backup and restore the current configuration of the machine.

Requirements:

- Iot-Core Visualizer has been started.

► Click on [Parameter].
> The menu page shows the available parameters of the IO-Link master.
> Current parameter values are displayed.
> Editable parameters can be changed.



To change a parameter:

► Navigate to the desired parameter in the device description.
► Changing the parameter value
► Click on the pencil icon to save the change on the IO-Link master.
> The changed parameter value is active.
► Optional: Repeat the procedure to change further parameter values.

Reading and writing process data

61179

The menu page allows the process data of the IO-Link master and the connected IO-Link devices to be read and written.

Requirements:

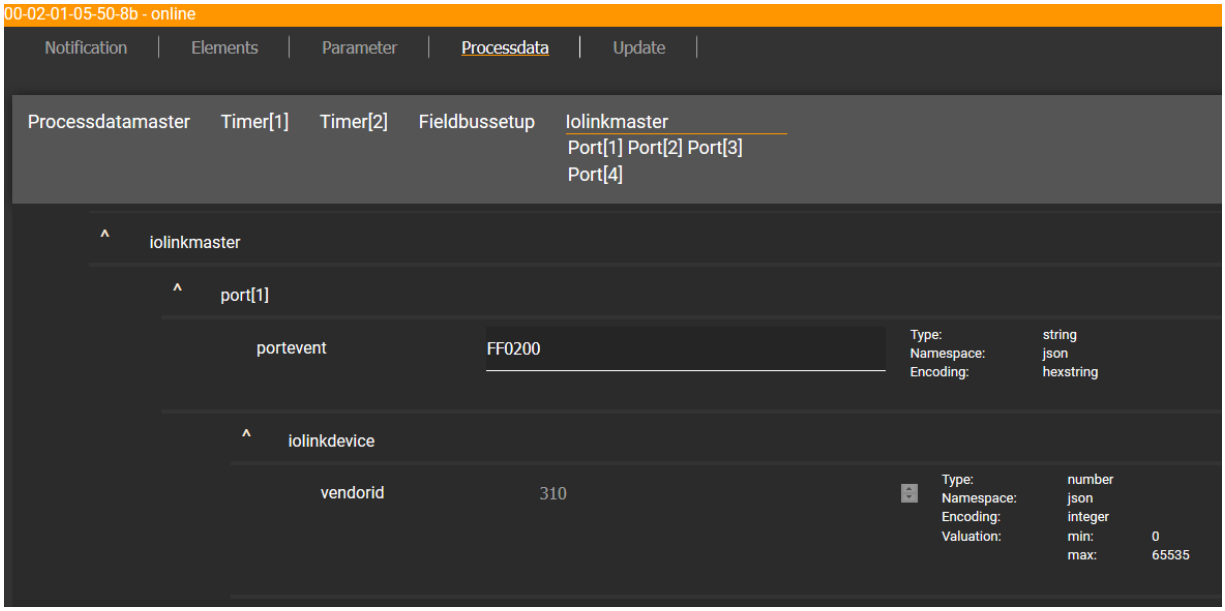
- Iot-Core Visualizer has been started.

► Click on [Processdata].

> Menu page shows the substructures of the device description that contain process data and events.

> The current process values are displayed.

> Editable process data can be changed.



To change the value of a process date:

► Navigate to the required process date in the device description.

► Change the process value.

► Click on the pencil icon to save the change on the IO-Link master.

> The changed process value is active.

► Optional: Repeat the procedure to change further process values.

Updating the firmware

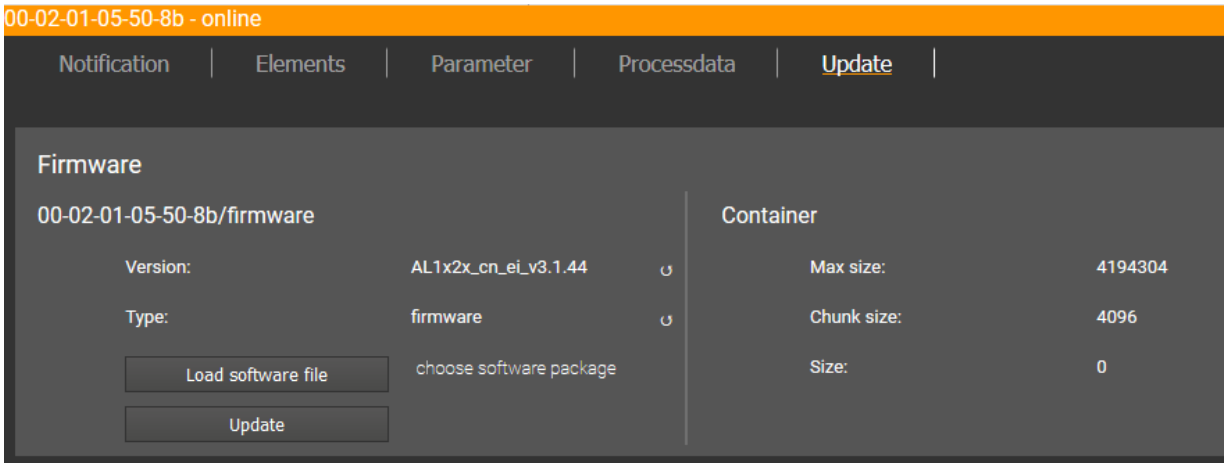
61180

The [Update] menu page allows you to update the firmware of the IO-Link master:
Requirements:

- Iot-Core Visualizer has been started.

► Click on [Update].

> Menu page displays information about the current firmware version.



► Click on [Load software file] and select a new firmware file (*.bin).

► Click on [Update] to start the update process.

> The firmware of the IO-Link master will be updated.

> The area shows the progress bar.

> If the update process has been successful, the IO-Link master will restart automatically.

9.3 EtherCAT

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33673

On the field bus side, the device can be configured with any EtherCAT compatible projection software.

The information in the following sections refers to the EtherCAT projection software TwinCAT 3.1.

9.3.1 Install ESI file

34067

To represent the AL1330 in a field bus projection software ifm electronic provides an ESI file (→ www.ifm.com)). In the ESI file, all parameters, process data and their valid value ranges are defined.

To integrate the ESI file into EtherCAT projection software TwinCAT 3.1:

► Download ESI file of the device.

► Copy downloaded file to the following subdirectory of the TwinCAT installation directory:
`..\3.1\Config\Io\EtherCAT`

► Start TwinCAT.

> TwinCAT loads the device description to the device catalogue.

9.3.2 Integrate the IO-Link master into the TwinCAT project

34080

The device is integrated into the project as EtherCAT slave.

Requirements

> The ESI file of the IO-Link master is installed (→ **Install ESI file** (→ p. 76)).

1 Create/open EtherCAT project

► Launch EtherCAT projection software.

► Create a new project.
OR
Open an existing project.

2 Configure EtherCAT PLC and IO periphery

► Select and configure EtherCAT PLC and requested I/O periphery.

> Project contains EtherCAT PLC and I/O periphery.

3 Insert the IO-Link master into the project

► In the Solution Explorer: Right-click on device to which the IO-Link master is connected.

> Context menu appears.

► In the context menu: Select [Add new item...].

> Window [Insert EtherCAT Device] appears.

► Select the IO-Link master in the device tree under [ifm electronic] > [ifm IO-Link master].

► Click on [OK] to add the selected device to the project.

> TwinCAT adds IO-Link master to the project.

4 Save the project

► Save the project.

9.3.3 Configure IO-Link master

33867

The IO-Link master is configured via the CoE interface (→ TwinCAT-online help). The configuration is made via the following parameters:

Name	Description	Reference
Current Use Case	Access rights to the IO-Link master	→ **Manufacturer Specific Index (0x2000)** (→ p. 97)
Reset To Factory	Reset IO-Link master to factory settings	→ **Manufacturer Specific Index (0x2000)** (→ p. 97)

9.3.4 Configure IO-Link ports

33886

The IO-Link ports are configured via the CoE interface (→ TwinCAT-online help). The user can configure each IO-Link port separately. The configuration is made via the following parameters:

Name	Description	Reference
IO Settings	Configuration of the IO-Link ports X01...X04	→ **Port Configuration (0x8000)** (→ p. 101)
Vendor Specific IO Settings	Manufacturer-specific settings of the IO-Link ports X01...X04	→ **Port Configuration (0x8000)** (→ p. 101)

The AL1330 has no failsafe function for the outputs of the IO-Link ports. If the fieldbus connection is interrupted, the last used output values are written and marked as invalid.

9.3.5 Configure cyclic process data

33884

Type and number of cyclic input and output data on the IO-Link ports are defined via the fieldbus modules (→ **EtherCAT modules** (→ p. 93)). In the factory settings, all slots are configured with the module "IOL_4/4_I/O".

To configure the cyclic process data:

Requirements

> AL1330 is integrated (→ **Integrate the IO-Link master into the TwinCAT project** (→ p. 77, "**Example: Reading properties of an element**" → p. 40)).

1 Open the device editor

► In the Solution Explorer: Double-click on the node of the AL1330.

> The window shows the available configuration options.

► Select the tab [Slots].

> The window shows the current configuration of the cyclic data.

2 Assign fieldbus modules

► In the left half of the table: Select click on slot of the requested IO-Link port.

► In the right half of the table: Click on the requested fieldbus module.

► Click on [<] to assign the requested fieldbus module to the slot.

3 Configure more IO-Link ports

► optional: repeat step 1 for further IO-Link ports.

> Cyclic data is assigned to the fieldbus slots.

> The Solution Explorer shows the configured modules as subelements of the device node.

4 Save the project

► Save the project.

9.3.6 Read and write cyclic process data

34217

► To check the validity of the cyclic process data, evaluate the PQI byte (→ **Mapping: Port Qualifier (0xF101)** (→ p. 106)).

Even with an interruption of the fieldbus connection the PQI byte indicates that the process data is valid. This can have unintended impact on the control process.

► Take suitable measures to detect an interruption of the fieldbus connection.

They cyclic process data of the IO-Link-Ports X01...X04 is accessible via the following index groups:

Name (Index)	Description	Reference
IO-Link inputs (0x6000)	Cyclic input data at the IO-Link ports X01...X04	→ **IO-Link Inputs (0x6000)** (→ p. 99)
IO-Link outputs (0x7000)	Cyclic output data at the IO-Link ports X01...X04	→ **IO-Link Outputs (0x7000)** (→ p. 100)

In operating mode "Digial Input (DI)" the digital process value of the IO-Link port will be mapped to the first byte of the input data (sub-index 0x01).

In operating mode "Digial Output (DO)" the digital process value of the IO-Link port will be mapped to the first byte of the output data (sub-index 0x01).

Valid values:

- 0x000 = OFF
- 0x001 = ON

During the configuration of the fieldbus slots TwinCAT automatically creates variables for the cyclic input and output data. They are found in groups in the folders under the respective fieldbus modules. The user can link the variables directly with the elements of a global variable list (GVL).

The following variables are created:

Group > Variable	Variable	Description
[TxPDO]	[input byte n]	Byte n of the cyclic input data of the fieldbus module
[RxPDO]	[output byte m]	Byte m of the cyclic output data of the fieldbus module

n = 0...(max. number of bytes on configured input data)-1
m = 0...(max. number of bytes on configured output data)-1

9.3.7 Read diagnostic and status information

34222

Diagnostic and status information is accessible via the following index groups:

Name (Index)	Description	Reference
MDP Standard Information (0x1000)	▪ Device information via IO-Link master ▪ Identity Object ▪ Diagnostic history	→ **MDP Standard Information (0x1000)** (→ p. 96)
IO Info Data (0x9000)	Information about IO-Link devices at IO-Link-Ports X01...X04	→ **Port Mode (0x9000)** (→ p. 102)
IO Diag Data (0xA000)	Diagnostic data of the IO-Link ports X01...X04	→ **Diagnostics Data (0xA000)** (→ p. 103)
Device Status (0xF000)	▪ Status of the IO-Link devices at the IO-Link port X01...X04 ▪ Port qualifier	→ **Device Status / Port Status (0xF000)** (→ p. 104)

When the IO-Link master is integrated into a EtherCAT project, TwinCAT automatically creates variables for diagnostic and status information in the Solution Explorer. They are grouped in folders under the device node. The user can link the variables directly with the elements of a global variable list (GVL).

The following variables are created:

Group > Variable	Description
[TxPDO IO-Link Device Status] > [State of IO-Link Ch.n]	Status of the IO-Link device at the IO-Link port X0n
[TxPDO IO-Link Port Qualifier] > [Qualifier of IO-Link Ch.n]	Port qualifier bits of the IO-Link port X0n
[TxPDO New Diagnosis Message available] > [New Message Available Flag]	Notification of new diagnostic messages

n ... 1...4

9.3.8 Read IO-Link events

33662

IO-Link Events will be stored in the "Diagnosis History" (→ **Diagnosis History (0x10F3)** (→ p. 107)).

The IO-Link Master stores a maxiumum of 32 events.

The single events will be stored in a ring buffer. The AL1330 supports the following operation modes for writing the ring buffer:

- Overwrite Mode: If the buffer memory is full, the oldest event will be overwritten by new incoming events.

- Acknowledge Mode: Events will only be overwritten, when they are read and acknowledged.

The configuration is done via sub-index 0x05. The eventsare stored in sub-indexes 0x06...0x26.

9.3.9 Configure IO-Link devices

33881

The IO-Link master supports the configuration of the connected IO-Link devices from the EtherCAT projection software. The parameters of an IO-Link device are set via IO-Link index and subindex. The number of the configurable parameters depends on the connected IO-Link device.



Available parameters of the IO-Link devices: → IO Device Description (IODD) of the IO-Link device

The user can read and write IO-Link index and subindex using the following methods:

- Acyclic communication: → **Use acyclic services** (→ p. 81)

9.3.10 EtherCAT: Programmers' notes

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Use acyclic services 81

33665

Use acyclic services

34187

The AL1330 supports following services for acyclic read and write processes:

- AoE - ADS over EtherCAT (→ **Use ADS over EtherCAT** (→ p. 81)
- CoE - CANopen over EtherCAT (→ **Use CANopen over EtherCAT** (→ p. 82)

Use ADS over EtherCAT

34190

AoE is suited for interruption-free access to the connected IO-Link devices during the operating time of the device. Access to the IO-Link master with AoE is not supported.

The function blocks for using AoE are part of the `tc2_system.lib`TwinCAT library.

The following rules apply to the inputs of the ADS function blocks:

Input	Description		Possible values	
PORT	ADS communication port = 0x1000 + IO-Link port number		0x1001 0x1002 ... 0x1004	IO-Link port X01 IO-Link port X02 ... IO-Link port X04
IDXGRP	AoE index group		0xF302	
IDXOFFS	Index Offset		e. g. access to index 21, subindex 0: 0x0021°0x00°0x00	
	Bits 0-7:	IO-Link subindex		
	Bits 8-15:	00000000		
	Bits 16-31:	IO-Link index		
ERRID	ADS error code		e. g. access to parameters of the IO-Link device refused: 0x0700°8023	
	Bits 0-15:	Error code of the IO-Link device		
	Bits 16-31:	ADS device error = 0x0700		

Use CANopen over EtherCAT

34193

CoE is suited for acyclic access to the IO-Link master and the connected IO-Link devices. CoE uses the fieldbus objects "IO-Link acyclic command" (→ **IO-Link Acyclic Command (0x3100)** (→ p. 98)). A separate fieldbus object is provided for each IO-Link port.

To have acyclic access to the device via CoE the user can use the following function blocks:

- FB_EcCoESdoRead: read SDO of an EtherCAT slave
- FB_EcCoeSdoWrite: write SDO of an EtherCAT slave

The function blocks for using CoE are part of the `Tc2_EtherCAT.library` function library.

► Add Tc2_EtherCAT.library function block library to the project

Description of the function blocks: → Help function of TwinCAT

The following rules apply to the inputs of the CoE function blocks:

Input	Description	Possible values	
sNetId	AMS net ID of the EtherCAT master to which the IO-Link master is connected	depends on the project; e.g. 172.16.2.131.2.1	
nSlaveAddr	EtherCAT address of the IO-Link port on the IO-Link master = 0x1000 + IO-Link port number	0x1001 0x1002 ... 0x1004	IO-Link port X01 IO-Link port X02 ... IO-Link port X04
nSubIndex	IO-Link subindex of the parameter	depends on the device; → IODD	
nIndex	IO-Link index of the parameter	depends on the device; → IODD	

Principle of the acacylic command processing

34201

General processing of acyclic communication:

1 Write command request

► In the command buffer (0x310n:sub-index 0x01): write required request data.

> Request data is transmitted.

> Command processing is initiated.

> Request channel is locked.

2 Check status

► In the status byte (0x310n:sub-index 0x02): read status information.

- If status == 0xFF: command processing is pending, repeat step 2.
- If status < 0xFF: command processing is finished, continue with step 3.

3 Read command response

► In the response buffer (0x310n:sub-index 0x03): read response data.

> The request channel is unlocked.

> Next command processing can be initiated.

The AL1330 can only process one CoE request at a time. If during an active request another CoE request is started, the device answers with an error (SDO abort code: 0x06090030).

10 Operation

Content

Using web-based management....83

34061

10.1 Using web-based management

61181

The device has an integrated web server The web server generates a website with the following data:

- Status information of the ports
- Access to product page of connected IO-Link devices (only ifm devices)
- Diagnostic information of the device
- Version information of the installed firmware components

To access the web interface of the IO-Link master:

► Connect the IO-Link master to the laptop / PC via the IoT port.

► Optional: Check the IP settings of the IoT interface.

► Start web browser.

► In the address field of the web browser, enter the IP address of the IoT interface and confirm with [ENTER].

> The web browser shows the website with the status and diagnostic information of the device.

11 Maintenance, repair and disposal

Content

Cleaning process....84
Updating the firmware....84
Replacing IO-Link device....84

51990

The operation of the unit is maintenance-free.

► Dispose of the unit in an environmentally friendly way in accordance with the applicable national regulations when it is no longer used.

11.1 Cleaning process

51991

► Clean the surface of the unit when necessary.
► Do not use any caustic cleaning agents for this!
► In case of severe soiling, use a damp cloth.
► Do not use any caustic cleaning agents for this!

11.2 Updating the firmware

61183

The firmware of the IO-Link master can be updated via the IoT Core Visualizer↘→ **Updating the firmware** (→ p. 75, → p. 84)).

11.3 Replacing IO-Link device

34182

To replace an IO-Link device:

Requirement:

> New IO-Link device is with factory settings.
> New IO-Link device supports IO-Link standard 1.1 or higher.

1 Set data storage

► Set the following parameters of the IO-Link port
▪ Set Validation and Data Storage to [Type compatible V1.1 device with Restore] or [Type compatible V1.1. device with Backup + Restore]
▪ Set correct values to [Vendor ID] and [Device ID] according to properties of the IO-Link device.
► Save changes.

2 Replace IO-Link device

► Disconnect old IO-Link device from IO-Link master.
► Connect new IO-Link device with the same IO-Link port of the AL1330.
> IO-Link master copies parameter values from the data memory to the new IO-Link device.

12 Factory settings

33849

In the factory settings, the device has the following parameter settings:

Parameter	Factory setting
[IP address] (IoT interface)	169.254.X.X
[Subnet mask] (IoT interface)	255.255.0.0
[IP gateway address] (IoT interface)	0.0.0.0
[Host name]	blank
Data storage	empty

13 Accessories

33870

List of accessories of AL1330: → www.ifm.com > Product page > Accessories

14 Appendix

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33879

14.1 Technical data

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34188

14.1.1 Application

33878

Application	
Application	I/O modules for field applications
Daisy-chain function	Fieldbus interface

14.1.2 Electrical data

33808

Electrical data	
Operating voltage [V]	20...30 DC; (US; to SELV/PELV)
Current Consumption [mA]	300...3900; (US)
Protection class	III
Sensor supply US	
Max. current load total [A]	3.6

14.1.3 Inputs / outputs

34068

Inputs / outputs	
Total number of inputs and outputs	8; (configurable)
Number of Inputs and Outputs	Number of digital inputs: 8; Number of digital outputs: 4

14.1.4 Inputs

34069

Inputs	
Number of digital inputs	8; (IO-Link port Class A: 4 x 2)
Switching level high [V]	11...30
Switching level low [V]	0...5
Digital inputs protected against short circuits	yes

14.1.5 Outputs

34053

Outputs	
Number of digital outputs	4; (IO-Link port Class A: 4 x 1)
Max. current load per output [mA]	300
Short-circuit protection	yes

14.1.6 Interfaces

34078

Interfaces	
Communication interface	Ethernet; IO-Link
Communication interface	IO-Link; TCP/IP; EtherCAT
Ethernet	
Transmission standard	10Base-T; 100Base-TX
Transmission rate [MBit/s]	10; 100
Protocol	EtherCAT, Zero config
Factory settings	MAC address: see type label
IO-Link master	
Type of transmission	COM 1 / COM 2 / COM 3
IO-Link revision	V1.1
Number of ports Class A	4
IoT interface	
Transmission standard	10Base-T; 100Base-TX
Transmission rate [MBit/s]	10; 100
Protocol	DCP, DHCP, Auto IP
Factory settings	▪ IP address: 169.254.X.X ▪ Subnet mask: 255.255.0.0 ▪ Gateway IP address: 0.0.0.0 ▪ MAC address: see type label

14.1.7 Operating conditions

34062

Operating conditions	
Applications	Indoor use
Ambient temperature [°C]	-25...60
Storage temperature [°C]	-25...85
Max. perm. relative air humidity [%]	90
Max. height above sea level [m]	2000
Protection rating	IP 65; IP66 IP 67
Pollution Degree	2

14.1.8 Approvals / tests

33877

Approval / tests	
EMC	▪ EN 61000-6-2 ▪ EN 61000-6-4
MTTF [Years]	90

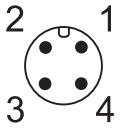
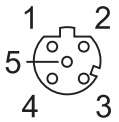
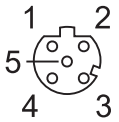
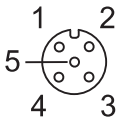
14.1.9 Mechanical data

34050

Mechanical data	
Weight [g]	302.5
Materials	Housing: PA; Socket: nickel-plated brass

14.1.10 Electrical connection

33806

Voltage supply IN X31			
Plug and socket connection	M12		
Wiring		1: 2: 3: 4:	+ 24 V DC (US) - GND (US) -
Ethernet IN / OUT X21, X22			
Plug and socket connection	M12		
Wiring		1: 2: 3: 4: 5:	TX + RX + TX - RX - -
IoT X23			
Plug and socket connection	M12		
Wiring		1: 2: 3: 4: 5:	TX + RX + TX - RX - -
Process connection IO-Link ports Class A X01...X04			
Plug and socket connection	M12		
Wiring		1: 2: 3: 4: 5:	Sensor supply (US) L+ DI Sensor supply (US) L- C/Q IO-Link -

14.2 EtherCAT

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33674

14.2.1 Parameter data

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34170

Fieldbus parameters

33830

The fieldbus parameters contain information about the integration of the device into the EtherCAT network:

Name	Description	Possible values
EtherCAT address	"Explicit Device ID" of the device	0...65534

EtherCAT modules

33680

Module	Description	
IOL_In_4Byte	IO-Link activated	4-byte input data
IOL_In_8Byte		8-byte input data
IOL_In_16Byte		16-byte input data
IOL_In_32Byte		32-byte input data
IOL_Out_4Byte		4-byte output data
IOL_Out_8Byte		8-byte output data
IOL_Out_16Byte		16-byte output data
IOL_Out_32Byte		32-byte output data
IOL_4/4_I/O bytes		4-byte input data / 4-byte output data (default)
IOL_8/8_I/O bytes		8-byte input data / 8-byte output data
IOL_4/16_I/O bytes		4-byte input data / 16-byte output data
IOL_16/4_I/O bytes		16-byte input data / 4-byte output data
IOL_16/16_I/O bytes		16-byte input data / 16-byte output data
IOL_32/32_I/O bytes		32-byte input data / 32-byte output data
Digital_IN	IO-Link deactivated	Digital input
Digital_OUT		Digital output
Deactivated	deactivated	

ESI file

33810

To represent the AL1330 in a field bus projection software ifm electronic provides an ESI file. The EDS file can be downloaded from ifm's website. In the ESI file, all parameters, process data and their valid value ranges are defined.

14.2.2 Cyclic data

Content

Process Data Objects (PDO).....94

33814

Process Data Objects (PDO)

34204

Selection of IO-Link Port via n (n = 0: Port X01, n = 1: Port X02,...)

Index	Name	Description	Data type / Access
0x1C12	RxPDO Assign	Outputs: List of references to RxPDO Mapping 0x160n; one subindex for each module	UINT16
0x1C13	TxPDO Assign	Inputs: List of references to TxPDO Mapping 0x1A0n; one subindex for each module	UINT16
0x160n	RxPDO Mapping	Outputs: List of references to RxPDO Data in Output Area; one index for each module; multiple subindices	UINT32 / rw
0x1A0n	TxPDO Mapping	Inputs: List of references to TxPDO Data in Input Area; one index for each module; multiple subindices	UINT32 / r
0x1A08	TxPDO Mapping of New Msg. Avail.	Inputs: Reference to TxPDO Data of New Message Available in 0x10F3:04 (1 bit) and 31 alignment bits	UINT32 / r
0x1A09	TxPDO Mapping of Timestamp	Inputs: Reference to TxPDO Data of Timestamp in 0x10F8 (64 bit)	UINT64 / r
0x1A81	TxPDO Mapping of Device Status	Inputs: References to TxPDO Data of Device Status in 0xF100:nn (8 bit), for all ports	UINT32 / r
0x1A82	TxPDO Mapping of Port Qualifier	Inputs: References to TxPDO Data of Port Qualifier in 0xF101:0n (8 bit), for all ports	UINT32 / r
0x70n0	Output Area, RxPDO Data	Outputs: RxPDOs (the cyclic data itself) of all modules; one index for each module; multiple subindices for multiple cyclic data objects	Octet String / rw
0x60n0	Input Area, TxPDO Data	Inputs: TxPDOs (the cyclic data itself) of all modules; one index for each module; multiple subindices for multiple cyclic data objects	Octet String / r
0x140n	RxPDO Parameter	Outputs: RxPDO Control for setting outputs valid/invalid; one index for each module; only subindex 8; unused here	Record / rw
0x180n	TxPDO Parameter	Inputs: TxPDO State for telling if inputs are valid/invalid; one index for each module; only subindex 7; unused here	Record / r
0xF100	Device Status	This status byte is included in input data of each module; one subindex for each module	UINT8 / r
0xF101	Port Qualifier	This status byte is included in input data of each module; one subindex for each module	UINT8 / r

14.2.3 Acyclic data

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33868

Note

34057

The device implements a "Modular Device Profile" with an "IO-Link profile" according to ETG.5001.1.

MDP Standard Information (0x1000)

34040

Identity information about the device and current and available process data constellations

Index	Sub-index	Description	Possible values / reference	Data type / Access
0x1000		Device Type	MDP Profile = 0x184C1389	UINT32 / r
0x1008		Manufacturer Device Name	"IO-Link master DL EC 4P IP67"	STRING / r
0x1009		Manufacturer Hardware Version	z.B. "AA"	STRING / r
0x100A		Manufacturer Software Version		STRING/ r
0x1018		Identity Object		
	▪ 0x1	Vendor ID	0x622	UINT32 / r
	▪ 0x2	Product Code	"AL1330"	UINT32 / r
	▪ 0x3	Revision Number:		UINT32 / r
	▪ 0x4	Serial Number		UINT32 / r
0x10F8		Timestamp (value in ns)		UINT64 / r

r ... read only
rw ... read and write

Manufacturer Specific Index (0x2000)

34036

Manufacturer-specific parameters

Index	Sub-index	Description	Possible values		Data type / Access
0x2001		Component Name	"EtherCAT IO-Link Gateway"		STRING / r
0x2002		Vendor Name	"ifm electronic"		STRING / r
0x2003		Vendor URL	"www.ifm.com"		STRING / r
0x2004		Order Number	"AL1330"		STRING / r
0x2005		Manufacturing Date			STRING / r
0x2006		QS Date			STRING / r
0x2007		Installation Location	user-defined; max. 20 characters		STRING / rw
0x200A		Equipment ID	user-defined; max. 20 characters		STRING /rw
0x2F00		Reset To Factory	0xA500:	Factory Reset of System + NVMEM	UINT16 / w
			0xA501:	Factory Reset of System	
0x2F01		Device Localization	0x00:	LED RDY blinking for 5 s	UINT8 / w
0x2F02		Current Use Case (Access Rights)	0xA500:	EtherCAT + IoT	UINT16 / rw
			0xA501:	EtherCAT + IoT (read only)	
			0xA502:	IoT (only)	

r ... read only
rw ... read and write
w ... write only

IO-Link Acyclic Command (0x3100)

33664

Selection of the IO-Link port via n (n = 0: port X01, n = 1: port X02,...)

Index	Sub-index	Description	Possible values		Data type / Access
0x310n		IO-Link Acyclic Command			
	▪ 0x01	Command Buffer	Byte 0:	Command (0x0 = Read, 0x1 = Write)	ARRAY_ OF_BYTE / rw
			Byte 1:	IO-Link Index, LSB	
			Byte 2:	IO-Link Index, MSB	
			Byte 3:	IO-Link Subindex	
			Byte 4:	For Write only: Length of following data (0x01...0xE8)	
			Byte 5:	For Write only: Data (0x00...0xE8)	
	▪ 0x02	Status	0x00:	Command completed: no error, no response data	UINT8 / r
			0x01:	Command completed: no error, response data available	
			0x02:	Command completed: error, no response data	
			0x03:	Command completed: error, response data available	
			0xFF:	Command is executing (pending)	
	▪ 0x03	Response Buffer	Byte 0:	Status (see Subindex 0x02)	ARRAY_ OF_BYTE / r
			Byte 1:	reserved	
			Byte 2:	If status = 0x1 | 0x3: Length of the following data	
			Byte 3..m:	If status = 0x1: Read data (0x00...0xE8) If status = 0x3: 1 byte IO-Link Error Code + 1 byte Additional Code	

r ... read only
rw ... read and write

IO-Link Inputs (0x6000)

33669

Input data of the IO-Link ports X01...X04
Selection of the IO-Link port via n (n = 0: port X01, n = 1: port X02,...)

Index	Sub-index	Description	Possible values	Data type / Access
0x60n0		IO-Link Inputs		
	▪ 0x01	Byte 1	je Byte: 0x00...0xFF	pro Byte: UINT8 / r
	...	...		
	▪ 0x20	Byte 32		

r ... read only

IO-Link Outputs (0x7000)

33667

Output data of the IO-Link ports X01...X04
Selection of the IO-Link port via n (n = 0: port X01, n = 1: port X02,...)

Index	Sub-index	Description	Possible values	Data type / Access
0x70n0		IO-Link Outputs		
	▪ 0x01	Byte 1	pro Byte: 0x00...0xFF	pro Byte: UINT8 / rw
	...	...		
	▪ 0x20	Byte 32		

rw ... read and write

Port Configuration (0x8000)

34214

Manufacturer-specific settings of the IO-Link ports X01...X04
Selection of the IO-Link port via n (n = 0: port X01, n = 1: port X02,...)

Index	Sub-index	Description	Possible values		Data type / Access
0x80n0		Port Configuration			
	▪ 0x04	Device ID	0x000000 ... 0xFFFFFF		UINT32 / rw
	▪ 0x05	Vendor ID	0x0000 ... 0xFFFF		UINT32 / rw
			0x136:	ifm electronic	
	▪ 0x20	IO-Link Revision	0x10:	IO-Link Revision 1.0	UINT8 / rw
			0x11:	IO-Link Revision 1.1	
	▪ 0x22	Cycle Time			UINT32 / rw
	▪ 0x24	Process Data In Length			UINT8 / rw
	▪ 0x25	Process Data Out Length			UINT8 / rw
	▪ 0x28	Master Control	0x00:	Deactivated	UINT16 / rw
			0x01:	Digital Input	
			0x02:	Digital Output	
			0x03:	IO-Link	
0x80n8		Vendor Specific Port Configuration			
	▪ 0x01	Validation ID	0x00:	No check	UINT8 / rw
			0x01:	V1.0 Device, no DS	
			0x02:	V1.1 Device, no DS	
			0x03:	V1.1 Device, Backup + Restore	
			0x04:	V1.1 Device, Restore	
	▪ 0x02	Reconfigure	0x00:	No action	UINT8 / rw
			0xFF:	Activate configuration	
	▪ 0x03	Byte Swap	0x00:	No action	UINT8 / rw
			0x01:	Byte swap	

rw ... read and write

Port Mode (0x9000)

34213

Current value of the connected IO-Link devices
Selection of the IO-Link port via n (n = 0: port X01, n = 1: port X02,...)

Index	Sub-index	Description	Possible values	Data type / Access
0x90n0		Port Mode		
	▪ 0x04	Device ID		UINT32 / r
	▪ 0x05	Vendor ID		UINT32 / r
	▪ 0x20	IO-Link Revision		UINT8 / r
	▪ 0x21	Frame Capability		UINT8 / r
	▪ 0x22	Cycle Time		UINT8 / r
	▪ 0x24	PD In Length		UINT8 / r
	▪ 0x25	PD Out Length		UINT8 / r

r ... read only

Diagnostics Data (0xA000)

33821

The device provides the following diagnostic data for each port:
Selection of the IO-Link port via n (n = 0: port X01, n = 1: port X02,...)

Index	Sub-index	Description	Possible values		Data type / Access
0xA0n0		Diagnostics Data			
	▪ 0x01	IO-Link State	0x00:	INACTIVE	UINT8 / r
			0x01:	DIGINPUT	
			0x02:	DIGOUTPUT	
			0x08:	OPERATE	
			0x09:	STOP	
	▪ 0x02	▪ Subindex 0x02: Lost Frames			UINT8 / r

r ... read only

Device Status / Port Status (0xF000)

33812

Status of the IO-Link device at the port X01...X04
Selection of the IO-Link port via n (n = 0: port X01, n = 1: port X02,...)

Index	Sub-index	Description	Possible values	Data type / Access
0xF000		Module Device Profile		
	▪ 0x01	▪ Module Index Distance	0x0010	UINT16 / r
	▪ 0x02	▪ Maximum number of modules	0x0004	UINT16 / r
0xF030		Configured Module Ident List		
0xF050		Detected Module Ident List		
0xF100		Device Status		UINT8 / r
	▪ 0x01	▪ IO-Link Port X01	→ **Mapping: Device Status (0xF100)** (→ p. 105)	
	...	...		
	▪ 0x0n	▪ IO-Link Port X04		
0xF101		IO-Link Port Qualifier		UINT8 / r
	▪ 0x01	▪ PQI Port X01	→ **Mapping: Port Qualifier (0xF101)** (→ p. 106)	
	...	...		
	▪ 0x0n	▪ PQI Port X04		

r ... read only

Mapping: Device Status (0xF100)

34039

Bit							
7	6	5	4	3	2	1	0
Error Code				Port State			

Legend:

- [Error Code] Error code of the IO-Link Device

  Note If more than one error occure at the same time. only one error will be shown. The other error messages will be surpressed.

0x0	No error
0x3	Invalid Device ID
0x4	Invalid Vendor ID
0x7	Invalid cycle time
0x8	Invalid length of PD In
0x9	Invalid length of PD Out
0xA	No device detected
0xB	Supply voltage low or short circuit
0xD	Unspecified error

- [Port State] State of the IO-Link port

0x0	Deactivated
0x1	Digital Input
0x2	Digital Output
0x3	OP: IO-Link, Operate state
0x4	STOP: IO-Link, not Operate state (fault or no device)
0x5	PreOP: IO-Link, device in PreOP state

Mapping: Port Qualifier (0xF101)

34041

Port Qualifier Information (PQI) contains diagnostic information about the IO-Link port. In addition to the process data, the IO-Link master sends the PQI to the EtherCAT controller.

Bit							
7	**6**	**5**	**4**	**3**	**2**	**1**	**0**
PVI	PE	DA	DACT	PVO	--	DI2	DI4

Legend:

▪ [DI4]	Signal status of the digital input on pin 4 (if used)	0x0	OFF
		0x1	ON
▪ [DI2]	Signal status of the digital input on pin 2 (if used)	0x0	OFF
		0x1	ON
▪ [PVO]	Port validity output: Validity of the output data of the IO-Link device	0x0	invalid
		0x1	valid
▪ [DACT]	Device deactivated: shows if the IO-Link port is configured and can be used	0x0	activated and can be used
		0x1	deactivated or not available
▪ [DA]	Device available: shows if the IO-Link device has been recognised and if the device is in the "preoperate" or in the "operate" state	0x0	No device
		0x1	device detected
▪ [PE]	Port error: shows if an error or a warning occurred (e.g. validation fault, short circuit); Note: The user needs to determine the cause of the fault separately via acyclic services.	0x0	no error
		0x1	Error
▪ [PVI]	Port validity input: Validity of the input data of the IO-Link device	0x0	invalid
		0x1	valid

14.2.4 Events

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33809

Diagnosis History (0x10F3)

33815

Index	Sub-index	Description	Possible values		Datentyp / Zugriff
0x10F3		Diagnosis History			
	0x01	Maximum Messages	0x00...0x0x20		UINT8 / r
	0x02	Newest Messages	0x00...0x0x20		UINT8 / r
	0x03	Newest Ack. Message	Override Mode (Subindex 5, Bit 4 = 0):		UINT8 / rw
			0	Reading: When the message queue will be overwritten, the slave shall set Subindex 0x03 to 0 Writing: the slave will clear all messages, i.e. resetting Subindex 0x02, 0x03, 0x04 and 0x5/Bit 5	
			1...5	Writing: the slave shall return SDO-Abort with codes 0x06090030 (value range of parameter exceeded) or 0x0609003	
			6...0x26	Writing: Subindex 0x03 = Written value without checking	
			0x26...255	Writing: SDO-Abort with codes 0x06090030 or 0x06090031(value of parameter written too high)	
			Acknowledge Mode (Subindex 5, Bit 4 = 1):		
			0	Read: No messages have been acknowledge so far Writing: All acknowledged messages will be deleted.	
			1...5	Writing: The slave shall return SDO-Abort with codes 0x06090030 (value range of parameter exceeded) or 0x06090032	
			6...0x26	Read: SubIndex of latest acknowledged diagnosis message Writing: Messages are acknowledged	
			0x26...255	Writing: SDO-Abort with codes 0x06090030 or 0x06090031(value of parameter written too high)	
	0x04	New Message Available	Override Mode:		BOOL / r
			0x0	newest msg. was read	
			0x1	newest msg. was not read	
			Acknowledge Mode:		
			0x0	no acknowledged message	
			0x1	diagnosis message are avalable which can be acknowledged (Subindex 0x02<>Subindex 0x03)	
	0x05	Flags	Bit 0:	Enable Emergency sending (according to ETG.1000-6)	UINT16 / rw

Index	Sub-index	Description	Possible values			Datentyp / Zugriff
				0	default if device does not support Emergency sending	
				1	new diagnosis messages shall be sent as Emergency message	
			Bit 1:	Disable info messages		
				0	Info messages are stored in the diagnosis message queue (default)	
				1	Info messages will not be stored in the diagnosis message queue	
			Bit 2:	Disable warning messages		
				0	Warning messages are stored in the diagnosis message queue (default)	
				1	Warning messages will not be stored in the diagnosis message queue	
			Bit 3:	Disable error messages		
				0	Error messages are stored in the message queue (default)	
				1	Error messages will not be stored in the diagnosis message queue	
			Bit 4:	Mode selection for diagnosis history handling		
				0	Overwrite Mode	
				1	Acknowledge Mode	
			Bit 5:	Overwrite/Discard Information		
				Overwrite Mode:		
				1	unacknowledged messages have been overwritten (=buffer overrun) (Subindex 0x03 is set to 0)	
				Acknowledge Mode:		
				1	message buffer is full with unacknowledged messages and a new massage is discarded.	
			Bit 6...15	reserved		
	0x06	Diagnosis Message 01	→**Mapping: Diagnosis Message** (→ p. 109)			OCTET STRING / r
	...					
	0x00x26	Diagnosis Message 32				

r ... read only
r/w ... read and write

Mapping: Diagnosis Message

SYS_OBJECTID>

Parameter	Content	Possible values			Data type / Access
Diag Code	Diagnostic code	Bit 0...15:	0x0000 - 0xDFFF	not used	UINT32 / r
			0xE000 - 0xE7FF	Bit 16...31: Manufacturer specific	
			0xE800	Bit 16...31: Emergency Error Code from DS301 or DS4xxx	
			0xE801 - 0xEDFF	reserved	
			0xEE00 - 0xEFFF	Bit 16...31: Profile specific	
			0xF000 - 0xFF00	not used	
			0xFF01	New IO-Link Event ▪ Byte 1: IO-Link Port (0x00 = Port 01, ...) ▪ Byte 2: Event Qualifier ▪ Byte 3+4: Event Code ▪ Byte 5: unused	
			0xFF02	Port Configuration has failed ▪ Byte 1...5: unused	
			0xFF03	IO-Link Device Lost (disconnected) ▪ Byte 1: IO-Link Port (0x00 = Port 01, ...)	
			0xFF04	IO-Link Device Fault (validation error or PD length mismatch) ▪ Byte 1: IO-Link Port (0x00 = Port 01, ...)	
			0xFF05	IO-Link Device Operating ▪ Byte 1: IO-Link Port (0x00 = Port 01, ...) ▪ Byte 2: Old status code ▪ Byte 3: Old info code ▪ Byte 4: New status code ▪ Byte 5: New info code	
Flags	Event type	Bit 0...3:	0x00	Info message	UINT16 / r
			0x01	Warning message	
			0x02	Error message	
Text ID	Text ID as reference to Diagnosis text as defined in ESI file	0x0000		no Text ID	UINT16 / r
		else		Text ID reference to ESI file	
Time Stamp	Time Stamp (value in ns)				UINT64 / r
Flags Parameter 1	Data type Parameter 1	0x0005		UINT8	UINT16 / r
Parameter 1	IO-Link Port	0x01		Port X01	UINT8 / r
		0x02		Port X02	
		...		...	

Parameter	Content	Possible values			Data type / Access
		0x04		Port X04	
Flags Parameter 2	Data type Parameter 2	0x0006		UINT16	UINT16 / r
Parameter 2	Event Code	geräteabhängig (→ IODD-Beschreibung des IO-Link Devices)			UINT16 / r
Flags Parameter 3	Data type Parameter 3	0x0005		UINT8	UINT16 / r
Parameter 3	Event Qualifier	Bit 0..2:	0x1	PHL	UINT8 / r
			0x2	DL	
			0x3	AL	
			0x4	APPL	
		Bit 3:	0x0	Source: Device	
			0x1	Source: Master	
		Bit 4...5:	0x1	Event Type: Info Message	
			0x2	Event Type: Warning Message	
			0x3	Event Error Message	
		Bit 6...7:	0x1	Message Type: Single	
			0x2	Message Type: Going	
			0x3	Message TYpe: Coming	

r ... read only
rw ... read and write

14.3 ifm IoT Core

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14.3.1 Overview: IoT profile

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34054

Profile: blob

52264

Element (identifier)	Properties	Mandatory	Comment
blobname	▪ type = data ▪ profiles = blob		labels element as device information
../size	type = data	mandatory	
../chunksize	type = data	mandatory	
../setblobdata	type = service	optional	
../getblobdata	type = service	optional	
../start_stream_set	type = service	optional	
../stream_set	type = service	optional	
../clear	type = service	optional	
../getcrc	type = service	optional	
../getmd5	type = service	optional	
../getdata	type = service	optional	
../setdata	type = service	optional	

Profile: deviceinfo

34207

Element (identifier)	Properties	mandatory	Comments
deviceinfo	▪ type = structure ▪ profile = deviceinfo		characterises the element as device information
../devicename	type = data	optional	
../devicefamiliy	type = data	optional	
../devicevariant	type = data	optional	
../devicesymbol	type = data	optional	
../deviceicon	type = data	optional	
../serialnumber	type = data	mandatory	
../productid	type = data	optional	
../productname	type = data	optional	
../productcode	type = data	mandatory	
../producttext	type = data	optional	
../ordernumber	type = data	optional	
../productiondate	type = data	optional	
../productioncode	type = data	optional	
../hwrevision	type = data	mandatory	
../swrevision	type = data	mandatory	
../bootloaderrevision	type = data	optional	
../vendor	type = data	optional	
../vendortext	type = data	optional	
../vendorurl	type = data	optional	
../vendorlogo	type = data	optional	
../productwebsite	type = data	optional	
../supportcontact	type = data	optional	
../icon	type = data	optional	
../image	type = data	optional	
../standards	type = data	optional	

Profile: devicetag

34206

Element (identifier)	Properties	mandatory	Comments
devicetag	▪ type = structure ▪ profile = devicetag		
../applicationtag	type = data	mandatory	
../applicationgroup	type = data	optional	
../machinecode	type = data	optional	
../tenant	type = data	optional	

Profile: iolinkdevice_full

52265

Element (identifier)	Characteristics	Mandatory	Comments
iolinkdevice	▪ type = structure ▪ profile = iolinkdevice_full		Structure of an IO-Link device
../vendorid	type = data	mandatory	
../deviceid	type = data	mandatory	
../productname	type = data	mandatory	
../serial	type = data	mandatory	
../applicationspecifictag	type = data	mandatory	
../pdin	type = data	mandatory	
../pdout	type = data	mandatory	
../status	type = data	mandatory	
../iolreadacyclic	type = data	mandatory	
../iolwriteacyclic	type = data	mandatory	
../iolinkevent	type = data	mandatory	

Profile: iolinkmaster

34205

Element (identifier)	Properties	Mandatory	Comments
masterport	▪ type = structure ▪ profile = iolinkmaster		Executable service
../mode	▪ type = data ▪ profile = parameter	mandatory	
../comspeed	▪ type = data ▪ profile = parameter	mandatory	
../mastercycletime_actual	▪ type = data ▪ profile = parameter	mandatory	
../mastercycletime_preset	▪ type = data ▪ profile = parameter	mandatory	
../validation_datastorage_mode	▪ type = data ▪ profile = parameter	mandatory	
../validation_vendorid	▪ type = data ▪ profile = parameter	mandatory	
../validation_deviceid	▪ type = data ▪ profile = parameter	mandatory	
../additionalpins_in	▪ type = data ▪ profile = processdata	optional	
../additionalpins_out	▪ type = data ▪ profile = processdata	optional	
../portevent	▪ type = data	mandatory	
../iolinkdevice	▪ type = structure ▪ profile = iolinkdevice_full	mandatory	

Profile: mqttCmdChannel

61186

Element (identifier)	Properties	Mandatory	Comment
mqttCmdChannel	▪ type = structure ▪ profile = commChannel		Profile of the MQTT command channel
../type	▪ type = data ▪ data type = STRING	mandatory	Protocol type of the interface
../status	▪ type = data ▪ data type = STRING	mandatory	Status of the MQTT command channel (possible values: init, running, stopped, error)
../mqttCmdChannelSetup	type = profile		Sub-profile: **Profile: mqttCmdChannelSetup** (→ p. 117)

Profile: mqttCmdChannelSetup

61187

Element (identifier)	Properties	Mandatory	Comment
mqttCmdChannelSetup	▪ type = structure ▪ profile = mqttCmdChannelSetup		Settings of the MQTT command channel
../brokerIP	▪ type = datat ▪ data type = STRING	optional	
../brokerPort	▪ type = data ▪ data type = STRING	optional	
../cmdTopic	▪ type = data ▪ data type = STRING	optional	
../defaultReplyTopic	▪ type = data ▪ data type = STRING	optional	

Profile: mqttConnection

61188

Element (identifier)	Properties	Mandatory	Comment
mqttConnection	▪ type = structure ▪ profile = commInterface		MQTT connection in the IoT Core
../type	▪ type = data ▪ data type = STRING	mandatory	Protocol type of the interface
../status	▪ type = data ▪ data type = STRING	mandatory	global status of the MQTT (possible values: init, running, stopped, error)
../mqttSetup	type = profile		Sub-profile: **Profile: mqttSetup** (→ p. 118)
../mqttCmdChannel	type = profile		Sub-profile: **Profile: mqttCmdChannel** (→ p. 117)

Profile: mqttSetup

61189

Element (identifier)	Properties	Mandatory	Comment
mqttSetup	▪ type = structure ▪ profile = mqttSetup		Settings of the MQTT command channel
../QoS	▪ type = data ▪ data type = Number	mandatory	Quality of Service of the MQTT connection
../version	▪ type = data ▪ data type = STRING	mandatory	

Profile: network

52266

Element (identifier)	Characteristics	Mandatory	Comments
network	▪ type = structure ▪ profiles = deviceinfo		Characterises the element as device information
../macaddress	▪ type = data ▪ profile = parameter	mandatory	
../ipaddress	▪ type = data ▪ profile = parameter	optional	
../ipv6address	▪ type = data ▪ profile = parameter	mandatory	
../subnetmask	▪ type = data ▪ profile = parameter	mandatory	
../ipdefaultgateway	▪ type = data ▪ profile = parameter	mandatory	
../dhcp	▪ type = data ▪ profile = parameter	optional	
../ipversion	▪ type = data ▪ profile = parameter	optional	
../hostname	▪ type = data ▪ profile = parameter	optional	
../autonegotiation	▪ type = data ▪ profile = parameter	optional	
../portspeed	▪ type = data ▪ profile = parameter	optional	
../enablenetwork	type = service	optional	
../disablenetwork	type = service	optional	

Profile: parameter

34215

The profile is used to mark the elements of type `data` as parameters (acyclic data). The profile defines no substructure.

Profile: processdata

34225

The profile is used to mark the elements of type `data` as process data (cyclic data). The profile does not define a substructure.

Profile: runcontrol

61190

Element (identifier)	Properties	Mandatory	Comment
runcontrol	▪ type = profile ▪ profile = runcontrol		Control of the MQTT command channel
../start	type = service	mandatory	**Service: start** (→ p. 133)
../stop	type = service	mandatory	**Service: stop** (→ p. 133)
../reset	type = service	mandatory	**Service: Reset** (→ p. 130)

Profile: service

34224

Element (identifier)	Properties	mandatory	Comments
service	▪ type = service ▪ profile = service		Executable service

Profile: software

34223

Element (identifier)	Properties	mandatory	Comments
software	▪ type = structure ▪ profile = software		characterises the element as software
../version	type = data	mandatory	
../type	type = data	mandatory	
../status	type = structure	optional	
../diag	type = structure	optional	

Profile: software/uploadedablesoftware

52267

Element (identifier)	Characteristics	Mandatory	Comments
software	▪ type = structure ▪ profiles = software/uploadablesoftware		Software that can be loaded to the device via the IoT Core
../lastinstall	type = data	optional	
../installhistory	type = data	optional	
../container	▪ type = data ▪ profile = blob	mandatory	
../preinstall	type = service	optional	
../install	type = service	mandatory	
../postinstall	type = service	optional	
../abortinstall	type = service	optional	
../installstatus	type = data	optional	

Profile: Timer

34226

Element (identifier)	Properties	Mandatory	Comment
timer	▪ type = structure ▪ profile = timer		
../counter	▪ type = data ▪ profile = parameter	mandatory	
../interval	▪ type = data ▪ profile = parameter	optional	
../start	type = service	optional	
../stop	type = service	optional	

14.3.2 Overview: IoT types

34055

The ifm IoT Core uses the following element types:

Name	Description
structure	Element is a structure element (like a folder in a file system)
service	Element is a service that can be addressed from the network
event	Element is an event that can be started by the firmware and sends messages.
data	Element is a data point
device	Root element a device represents

14.3.3 Overview: IoT services

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34056

Service: factoryreset

34184

Name: factoryreset

Description: The service sets the parameters of the device to the factory settings.

Request data (field "data"): none

Response data (field "data"): none

Example:

```
{
"code": "request",
"cid": 4711,
"adr": "/firmware/factoryreset"
}
```

Service: getblobdata

52345

Name: getblobdata
Description: The service reads a binary large object (blob).
Applicable to: datastorage
Request data (field "data"):

Data field	Required field	Data type	Default	Description
pos	mandatory	number	0	Byte position
length	mandatory	number	-	Size of the object (number of bytes)

Return data (field "data"):

Data field	Required field	Data type	Default	Description
data	mandatory	STRING	0	Data to be decoded (BASE64 coded)
crc	optional	HEX STRING		CRC of the data after decoding
md5	optional	HEX STRING		MD5 checksum of the data after decoding

Service: getdata

34183

Name: getdata
Description: Service reads the value of a data point and provides it.
Request data (field "data"): none
Return data (field "data"):

Data field	Required field	Data type	Description
value	mandatory	STRING	Value of the element/data point

Example:

```
{
"code":"request",
"cid":4711,
"adr":"devicetag/applicationtag/getdata"
}
```

Service: getdatamulti

34174

Name: getdatamulti

Description: The service sequentially reads the values of several data points and provides them. The value and the diagnostic code are provided for each data point.

Request data (field "data"):

Data field	Required field	Data type	Description
datatosend	mandatory	ARRAY OF STRINGS	List of data points to be requested; data points must support the service getdata ("datatosend":["url1","url2",...,"urlx"])

Response data (field "data"): for each requested data point

Data field	Required field	Data type	Description
url	mandatory	STRING	Data point request
code	mandatory	INT	Diagnostic code of the request
data	mandatory	STRING	Value of the data point

Service: getelementinfo

52269

Name: getelementinfo

Description: The service reads the properties of an element of the IoT tree.

Applicable to: Objects of the type `device`

Request data (field "data"):

Data field	Required field	Data type	Default	Description
adr	mandatory	STRING		URL of the element, which properties to be changed

Return data (field "data"):

Data field	Required field	Data type	Default	Description
identifier	mandatory	STRING		Identifier of the element
type	mandatory	STRING		Type of the element
format	optional	JSON object	blank	Format of the data or the service content
uid	optional	STRING	blank	
profiles	optional	JSON array	blank	
hash	optional	STRING	--	

Servicet: getidentity

54690

Name: getidentity
Description: The service reads the device information of the AL1330 and issues it.
Request data ("data" field): none
Return data ("data" field):

Data field	Required field	Data type	Description	
iot		Device	Device description as JSON object	
iot.name	mandatory	STRING		
iot.uid	optional	STRING		
iot.version	mandatory	STRING		
iot.catalogue	optional	ARRAY OF OBJECTS		
iot.deviceclass	optional	ARRAY OF STRING		
iot.serverlist	optional	ARRAY OF OBJECTS		
device	optional		AL1330	
device.serialnumber	optional		Serial number	
device.hwrevision	optional		Hardware version	
device.swrevision	optional		Software version	
device.custom	optional			
Security	optional		Security options	
security.securitymode	optional	ENUM	shows if the security mode is activated	
security.authscheme	optional	ENUM	shows the active authentication scheme	
security.ispasswordset	optional	BOOL	shows whether a password has been set	
security.activeconnection	optional	ENUM	shows the currently used communication interface	
			▪ tcp_if	unencrypted http connection at the IoT interface, port 80
			▪ tls_if	encrypted https connection at the IoT interface, port 443
			▪ fb_if	unencrypted http connection at the fieldbus interface, port 80

Service: getsubscriberlist

61191

Name: getsubscriberlist
Description: The service provides a list of all active subscriptions.
Request data ("data" field): none
Return data ("data" field): Array with the following data

Data field	Mandatory field	Data type	Description
adr	mandatory	STRING	Data source
datatosend	mandatory	ARRAY OF STRINGS	List with URLs of the subscribed data points
cid	mandatory	NUMBER	ID of the subscription
callbackurl	mandatory	STRING	Address to which IoT Core event notifications are to be sent;
duration	mandatory	STRING	Storage duration of the value

Example:

- **Request object:**

```
{
"code":"request",
"cid":4711,
"adr":"/getsubscriberlist"
}
```

- **Return object:**

```
{
"cid":4711,
"data":[
{
"adr":"/timer[1]/counter/datachanged/subscribe",
"datatosend":["/iolinkmaster/port[2]/iolinkdevice/pdin"],
"cid":1,
"callbackurl":"http://192.168.0.45:80/temp",
"duration":"lifetime"},
{
"adr":"/timer[1]/counter/datachanged/subscribe",
"datatosend":["/processdatamaster/temperature","/processdatamaster/voltage"],
"cid":2,
"callbackurl":"http://192.168.0.44:80/temp",
"duration":"lifetime"}
]
"code":200
}
```

Service: getsubscriptioninfo

61192

Name: getsubscriptioninfo
Description: The service provides information about an existing subscription (subscribe).

The following parameters of the existing subscription are to be used for the query:

- Value of the identifier cid (e.g. 4711)
- Number of the timer (e.g. timer[1])
- Name of the callback topic (e.g. B. temp)

Request data ("data" field):

Data field	Mandatory field	Data type	Description
callback	mandatory	STRING	Address to which IoT Core event notifications are to be sent; complete URL: http://ipaddress:port/path

Return data ("data" field):

Data field	Mandatory field	Data type	Description
subscription	mandatory	BOOL	Status of the transferred subscription parameter
datatosend	mandatory	ARRAY OF STRINGS	List with subscribed data points
cid	mandatory	NUMBER	ID of the subscribe request
callbackurl	mandatory	STRING	Address to which IoT Core event notifications are to be sent; complete URL: http://ipaddress:port/path

Example:

- **Request object:**

```
{
"code":"request",
"cid":4711,
"adr":"/timer[1]/counter/datachanged/getsubscriptioninfo",
"data":{
"callback":"http://192.168.0.44:80/temp"}
}
```

- **Return object:**

```
{
"cid": 4711,
"data":{
"subscription": true,
"datatosend":[
"/iolinkmaster/port[2]/iolinkdevice/productname",
"/iolinkmaster/port[2]/iolinkdevice/pdin",
"/processdatamaster/temperature"],
"callbackurl":"http://192.168.0.44:80/temp",
"duration":"lifetime"},
"code":200
}
```

Service: gettree

61193

Name: gettree

Description: The service reads the device description of the IO-Link master and outputs it as a JSON object. The output can be limited to a subtree of the device description.

Request data ("data" field):

Data field	Mandatory field	Data type	Description
adr	optional	STRING	Root element of the subtree
level	optional	STRING	max. level up to which the subtree is output ▪ no entry: all levels will be displayed ▪ 0: do not display sub-elements ("subs") ▪ 1: display sub-elements ▪ 2: display sub-elements up to the 2nd level ▪ 3: display sub-elements up to the 3rd level ... ▪ 20: display sub-elements up to the 20th level

Return data ("data" field):

Data field	Mandatory field	Data type	Description
identifier	mandatory	STRING	Identifier of the root element
type	mandatory	STRING	Type of the element
format	optional	JSON Object	Format of the data content
uid	optional	STRING	
profiles	optional	JSON-Array	
subs	mandatory	JSON-Array	Sub-elements
hash	optional	STRING	

Examples:

- output the complete device description

```
{
"code":"request",
"cid":4,
"adr":"/gettree"
}
```

- output the subtree counter[2] of the device description up to the 2nd level

```
{
"code":"request",
"cid":4,
"adr":"/gettree"
"data":{
"adr":"counter[2]",
"level":2}
}
```

Service: install

52343

Name: install
Description: The service installs the firmware stored in the container area of the device.
Applicable to: container
Request data (data): none
Return data (data): none

Service: iolreadacyclic

34178

Name: iolreadacyclic
Description: The service acyclically reads the parameter value of an IO-Link device. The parameter is accessed via IO-Link index and subindex.
Request data (field "data"):

Data field	Required field	Data type	Description
index	mandatory	NUMBER	IO-Link index of the parameter
subindex	mandatory	NUMBER	IO-Link subindex of the parameter

Response data (field "data"):

Data field	Required field	Data type	Description
value	mandatory	STRING	Value of the parameter; Value in hexadecimal format

Service: iolwriteacyclic

34177

Name: iolwriteacyclic
Description: The service acyclically writes the parameter value of an IO-Link device. The parameter is accessed via IO-Link index and subindex.
Request data (field "data"):

Data field	Required field	Data type	Description
index	mandatory	NUMBER	IO-Link index of the parameter
subindex	mandatory	NUMBER	IO-Link subindex of the parameter
value	mandatory	STRING	New value of the parameter; Value in hexadecimal format

Response data (field "data"): none

Service: querytree

61194

Name: querytree

Description: The service searches a device tree for the criteria profile, type and name and outputs a list with the URLs of the elements found. At least one of the search criteria must be specified. The service can only be executed on the root node of the machine.

Return data ("data" field):

Data field	Mandatory field	Data type	Description
profile	optional	STRING	Profile of the searched element
type	optional	STRING	Type of the searched element
name	optional	STRING	Type of the searched element

Return ("data" field):

Data field	Mandatory field	Data type	Description
urlList	mandatory	Array	Array with URLs of the found elements; URLs are separated by commas

Service: reboot

34176

Name: reboot

Description: The service reboots the device.

Request data (field "data"): none

Return data (field "data"): none

Example:

```
{
"code":"request",
"cid":4,
"adr":"firmware/reboot"
}
```

Service: Reset

61195

Name: Reset

Description: The service resets a connection to the initialisation state.

Request data ("data" field): none

Return data ("data" field): none

Example:

```
{
"code":"request",
"cid":4711,
"adr":"/connections/mqttConnection/MQTTSetup/mqttCmdChannel/status/reset"
}
```

Service: setblock

34186

Name: setblock

Description: The service simultaneously sets the values of several data points of a structure.

Request data (field "data"):

Data field	Required field	Data type	Description
datatoset	mandatory	ARRAY OF OBJECTS	List of data points and their new values; data points must support the service setdata
consistent	optional	BOOL	

Response data (field "data"): none

Example:

Request:

```
{
"code":"request",
"cid":4711,
"adr":"iotsetup/network/setblock",
"data":{
"datatoset":{
"ipaddress":"192.168.0.6",
"subnetmask":"255.255.255.0",
"ipdefaultgateway":"192.168.0.250",
"dhcp":0}
}
}
```

Response:

```
{
"cid":4711,
"code":233
}
```

Service: setdata

34195

Name: setdata
Description: The service sets the value of the data point.
Request data ("data" field):

Data field	Mandatory field	Data type	Description
newvalue	mandatory	STRING	New value of the element/data point
duration	mandatory	STRING	Duration of value storage ▪ lifetime: Value is saved with IoT Core; Value remains valid even after restart of the device ▪ uptime: Value is saved until the next restart of the device

Return data ("data" field): none

Example:

```
{"code": "request",
"cid":4711,
"adr": "devicetag/applicationtag/setdata",
"data":{
"newvalue": "ifm IO-Link master
"duration": "lifetime"}
}
```

Service: signal

33819

Name: signal
Description: The service starts the flashing of the status LEDs of the AL1330.
Request data (field "data"): none
Return data (field "data"): none

Example:

```
{
"code":"request",
"cid":4711,
"adr":"firmware/signal"
}
```

Service: start

61196

Name: start
Description: The service starts a connection.
Request data ("data" field): none
Return data ("data" field): none

Example:

```
{
"code":"request",
"cid":4711,
"adr":"/connections/mqttConnection/MQTTSetup/mqttCmdChannel/status/start"
}
```

Service: start_stream_set

52342

Name: start_stream_set
Description: The service starts the sequential transfer of multiple data segments.
Applicable to: Objects of type data
Request data (data):

Data field	Required field	Data type	Default	Description
size	mandatory	STRING		Total size of data to be transfered (number of bytes)

Return data (data): none

Service: stop

61197

Name: stop
Description: The servicestops a connection.
Request data ("data" field): none
Return data ("data" field): none

Example:

```
{
"code":"request",
"cid":4711,
"adr":"/connections/mqttConnection/MQTTSetup/mqttCmdChannel/status/stop"
}
```

Service: stream_set

52341

Name: stream_set
Description: The service transfers a data segment.
Applicable to: Objects of type data
Request data (data):

Data field	Required field	Data type	Default	Description
value	mandatory	BIN (BASE64)	*	Segment of binary data (BASE64 coded)

Return data (data): none

Service: subscribe

61198

Name: subscribe
Description: The service subscribes to the values of data points. The data points to be subscribed are transferred as a list. The IoT Core sends changes to the data sink defined in callback.



CSV formatted notifications can only be transmitted using the TCP protocol via an activated and configured MQTT channel.

Request data ("data" field):

Data field	Mandatory field	Data type	Description
callback	mandatory	STRING	Address to which IoT Core event notifications are to be sent; URL format: ▪ JSON: http://ipaddress:port/path ▪ JSON: ws:///path ▪ JSON: mqtt://ipadress:port/topic ▪ CSV: tcp://ipaddress:port/path
datatosend	mandatory	ARRAY OF STRINGS	List from URLs of data elements; Elements must support getdata
codec	optional	STRING	Format of the returned data ▪ json: JSON formatted ▪ csv: CSV with standard separator (,) ▪ csv0: CSV formatted with comma separator (,) ▪ csv1: CSV formatted with semicolon separator (;)
DURATION	mandatory	STRING	Duration of value storage ▪ lifetime: Value is saved with IoT Core; Value remains valid even after restart of the device ▪ uptime: Value is saved until the next restart of the device ▪ once: send only one notification, user must unsubscribe immediately

Return data ("data" field): none
Notification: JSON

```
{
"code":"event",
"cid":4711,
"adr":"",
"data":{
```

```
"eventno":"EventNo",
"srcurl":"SrcURL",
"payload":{
"eventurl":{"code":EventStatus,"data":EventData},
"datapointurl_1":{"code":DataStatus_1,"data":DataValue_1},
"datapointurl_2":{"code":DataStatus_2,"data":DataValue_2},
...}}
}
```

Notification: CSV

`SrcURL,EventNo,EventStatus,EventData,DataStatus_1,DataValue_1,DataStatus_2,DataValue_2,...`

- `SrcURL`: Source of the event (data point on which subscribe command was listed)
- `EventNo`: Event number
- `EventStatus`: Status code of the event
- `EventData`: Event data
- DataStatus_1: Status code of the 1st element in list datatosend
- `DataValue_1`: Value of the 1st element in list datatosend
- `DataStatus_2`: Status code of the 2nd element in list datatosend
- `DataValue_2`: Value of the 2nd element in list datatosend
- ...

Service: unsubscribe

34197

Name: unsubscribe

Description: The service deletes an existing subscription. The service unsubcribe is successful if cid and the callback address are registered for an active subscription (subscribe). If the STRING "DELETE" is provided in callback, the IO-Link master deletes all active subscriptions.

Request data (field "data"):

Data field	Required field	Data type	Description
callback	mandatory	STRING	Address to which IoT Core event notifications are to be sent; complete URL: http://ipaddress:port/path

Response data (field "data"): none

Service: validation_useconnecteddevice

52340

Name: validation_connecteddevice

Description: The service checks, whether Device ID and Vendor ID of the connected IO-Link device match with the values of the datapoints `../validation_vendorid` and `../validation_deviceid`.

Applicable to: Objects of type `stucture`

Request data (data): none

Return data (data): none

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