Instruction Manual

Models UT550/UT520 Digital Indicating Controllers

User's Manual for Single-loop Control

IM 05D01C02-41E



<Toc> <Rev>

Introduction

Thank you for purchasing the UT550/UT520 digital indicating controller.

■ How to Use the Manuals

Purpose	Manual Title	Description
Setup	1. Installation	Describes the tasks (installation, wiring, and others) required to make the controller ready for operations.
Basic operation	2. Initial Settings	Describes examples of setting PV input types, control output types, and alarm types. Making settings described herein allows you to carry out basic control.
Operating procedures and troubleshooting	3. Operations 4.1 Troubleshooting	Describes key operation sequences. For operation control through external contact inputs, See "1.5 Terminal Wiring Diagrams"
Brief operation	5.1 Parameter Map	Contains the parameter map used as a guideline for setting parameters.
Function description and setpoint recording	5.2 Lists of Parameters	Briefly describes the functions of parameters. In addition, each parameter table has a User Setting column, where you can record your setpoints when setting them in the controller.

■ Regarding This User's Manual

- (1) This manual should be provided to the end user. Keep an extra copy or copies of the manual in a safe place.
- (2) Read this manual carefully to gain a thorough understanding of how to operate this product before starting operation.
- (3) This manual describes the functions of this product. Yokogawa M&C Corporation (hereinafter simply referred to as Yokogawa) does not guarantee the application of these functions for any particular purpose.
- (4) Under absolutely no circumstances may the contents of this manual, in part or in whole, be transcribed or copied without permission.
- (5) The contents of this manual are subject to change without prior notice.
- (6) Every effort has been made to ensure that the details of this manual are accurate. However, should any errors be found or important information be omitted, please contact your nearest Yokogawa representative or our sales office.

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■ Safety Precautions

The following symbol is indicated on the controller to ensure safe use.



This symbol on the controller indicates that the operator must refer to an explanation in the user's manual in order to avoid the risk of injury or death of personnel or damage to the instrument. The manual describes how the operator should exercise special care to avoid electric shock or other dangers that may result in injury or loss of life.

The following symbols are used in the hardcopy user's manuals and in the user's manual supplied on the CD-ROM.



NOTE

Indicates that operating the hardware or software in a particular manner may damage it or result in a system failure.



IMPORTANT

Draws attention to information that is essential for understanding the operation and/or features of the controller.

■ Regarding Force Majeure

Yokogawa M&C Corporation assumes no liability for any loss or damage, direct or indirect, caused by the use of or unpredictable defects of the product.

Models UT550/UT520 Digital Indicating Controllers User's Manual for Single-loop Control

IM 05D01C02-41E 1st Edition

CONTENTS

1.	Install	lation	1-1
	1.1	Model and Suffix Codes	1-1
	1.2	How to Install	1-2
	1.3	How to Connect Wires	1-5
	1.4	Hardware Specifications	1-7
	1.5	Terminal Wiring Diagrams	1-13
2.	Initial	Settings	2-1
	2.1	Names and Functions of Front Panel Parts	2-2
	2.2	Setting PV Input Type (Setting First at Power-on)	2-3
	2.3	Changing PV Input Type	2-7
	2.4	Setting Control Output Type	
		(except for a Position Proportional Controller)	2-9
	2.5	Calibrating Valve Position	
		(for a Position Proportional Controller Only)	2-11
	2.6	Initializing Parameters	2-13
	2.7	Changing Alarm Type	2-14
	2.8	Description of Multiple Setpoints and PID	2-17
3.	Opera	itions	3-1
	3.1	Monitoring-purpose Operating Displays	
		Available during Operation	3-1
	3.2	Setting Target Setpoint (SP)	3-3
	3.3	Performing/Canceling Auto-tuning	3-3
	3.4	Setting PID Manually	3-5
	3.5	Setting Alarm Setpoints	3-6
	3.6	Selecting Target Setpoint Numbers (SPN)	3-7
	3.7	Switching between Run and Stop	3-8
	3.8	Switching between AUTO and MAN	3-8
	3.9	Manipulating Control Output during Manual Operation	3-9
	3.10	Switching between Remote (REM) and Local (LCL)	3-11

4.	Trouk	oleshoot	ing and Maintenance	4-1
	4.1	Trouble	eshooting	4-1
	4.2	Mainte	nance	4-6
		4.2.1	Cleaning	4-6
		4.2.2	Replacing Brackets	4-6
		4.2.3	Attaching Terminal Cover	4-6
		4.2.4	Replacing Parts with a Limited Service Life	4-8
		4.2.5	Replacing Control Output Relays	4-8
5.	Parar	neters		5-1
	5.1	Param	eter Map	5-1
	5.2	Lists o	f Parameters	5-6
6.	Func	tion Bloc	ck Diagram and Descriptions	6-1

1. Installation

This chapter describes installation, wiring, and other tasks required to make the controller ready for operation.

1.1 Model and Suffix Codes

Before using the controller, check that the model and suffix codes match your order.

Model	Suffix Code	Description					
UT550		Digital indicating controller (provided with retransmission output and 15 VDC loop power supply as standard)					
	-0	Standard type					
	-1	Position proportional type					
Туре	-2	Heating/cooling type					
	-3	Standard type (with 24 V DC loop power supply)					
	-4	Position proportional type (with 24 V DC loop power supply)					
	0	None					
Optional functions 2 3 4		With communication, remote input, 6 additional DIs and 4 additional DOs					
		With communication, remote input, and 1 additional DI					
		With 5 additional DIs and 4 additional DOs					
		With remote input and 1 additional DI					

Model	Suffix Code	Description					
UT520		igital indicating controller (provided with retransmission output and 15 VDC loop power supply as standard)					
Туре	-0	Standard type					
Optional functions	0 7 8	None Communication, remote input, and 2 additional DIs Remote input and 2 additional DIs					

Check that the following items are provided:

■ Correspondence between the Model and Suffix Codes, and the Contact Input/Output Terminals Provided

Check the model ordered and the presence/absence of contact inputs and outputs in the following table.

✓ indicate that the contacts are available.

Model and Suffix			Con	tact inp	ut term	inals				С	ontact	output t	ermina	ls	
Codes	DI1	DI2	DI3	DI4	DI5	DI6	DI7	DI8	DO1	DO2	DO3	DO4	DO5	DO6	DO7
UT550-□0	/	1							1	1	1				
UT550-□1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
UT550-□2	1	1						1	1	1	1				
UT550-□3	1	1	/	1	1	1	1		1	1	1	1	1	1	1
UT550-□4	/	1						1	1	1	1				

Note: For details on the functions of contact inputs/outputs, see "1.5 Terminal Wiring Diagrams" .

✓ indicate that the contacts are available.

Model and Suffix			Con	tact inp	ut termi	nals				С	ontact	output t	ermina	ls	
Codes	DI1	DI2	DI3	DI4	DI5	DI6	DI7	DI8	DO1	DO2	DO3	DO4	DO5	DO6	DO7
UT520-00	1	1							1	1	1				
UT520-07	1	1	1					1	1	1	1				
UT520-08	/	1	1					1	1	1	1				

Note: For details on the functions of contact inputs/outputs, see "1.5 Terminal Wiring Diagrams" .

1.2 How to Install



NOTE

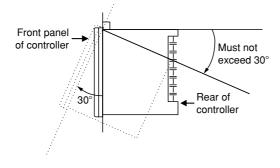
To install the controller, select a location where:

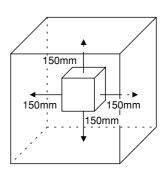
- (1) no one may accidentally touch the terminals,
- (2) mechanical vibrations are minimal.
- (3) corrosive gas is minimal,
- (4) temperature can be maintained at about 23°C and the fluctuation is minimal,
- (5) no direct radiant heat is present,
- (6) no magnetic disturbances are caused,
- (7) no wind blows against the terminal board (reference junction compensation element),
- (8) no water is splashed,
- (9) no flammable materials are around,

Never place the controller directly on flammable items or equipment. If the controller has to be installed close to flammable items or equipment, be sure to provide shielding panels all around the controller, at least 150mm away from every side; the panels should be made of either 1.43mm-thick metal-plated steel plates or 1.6mm-thick uncoated steel plates.

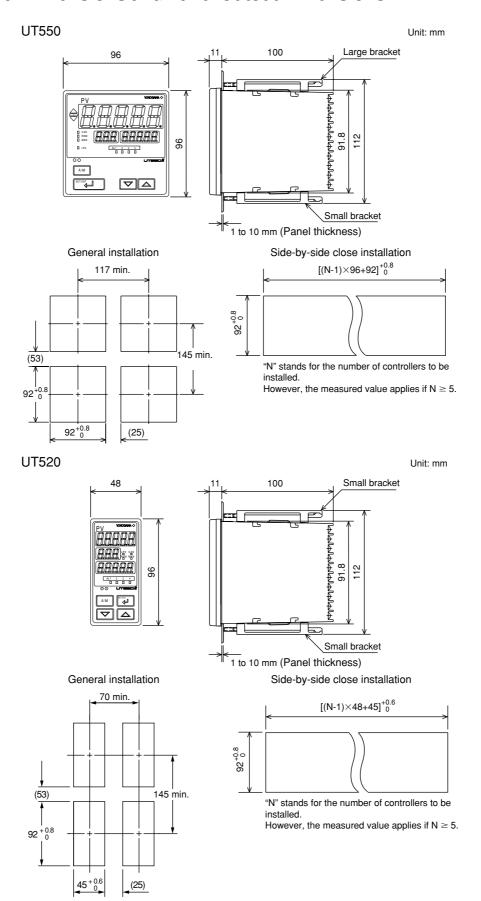
Installation Position

Install the controller at an angle within 30° from horizontal with the front panel facing upward. Do not install it facing downward. The position of right and left sides should be horizontal.





■ External Dimensions and Panel Cutout Dimensions



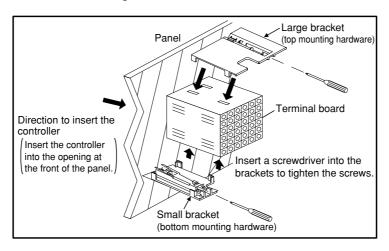
■ How to Install



Turn off the power to the controller before installing it on the panel because there is a possibility of electric shock.

After opening the mounting hole on the panel, follow the procedures below to install the controller:

- 1. Insert the controller into the opening from the front of the panel so that the terminal board on the rear is at the far side.
- 2. Set the brackets in place on the top and bottom of the controller as shown in the figure below, then tighten the screws of the brackets. Take care not to overtighten them.



1.3 How to Connect Wires



1) Before carrying out wiring, turn off the power to the controller and check that the cables to be connected are not alive with a tester or the like because there is a possibility of electric shock.

2) Wiring must be carried out by personnel who have basic electrical knowledge and practical experience.



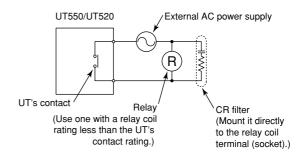
NOTE

- Provide power from a single-phase instrument power supply. If there is a lot of noise in the power line, insert an insulating transformer into the primary side of the line and use a line filter (recommended part: ZAC2205-00U from TDK) on the secondary side. As a countermeasures against noise, do not place the primary and secondary power cables close to each other.
- 2) For thermocouple input, use shielded compensating lead wires for wiring. For RTD input, use shielded wires that have low conductor resistance and cause no significant differences in resistance between the three wires. The cables to be used for wiring, terminal specifications, and recommended parts are as shown below.
- 3) Control output relays may be replaced. However, because they have a life of 100,000 times that of the resistance load, use auxiliary relays to turn on/off a load.
- 4) The use of inductance (L) loads such as auxiliary relays, motors and solenoid valves causes malfunction or relay failure; always insert a CR filter for use with alternating current or a diode for use with direct current, as a spark-removal surge suppression circuit, into the line in parallel with the load.

■ For DC Relay Wiring

UT550/UT520 External DC power supply OC. Relay Diode (Mount it directly to the relay coil terminal (socket).) (Use one with a relay coil rating less than the UT's contact rating.)

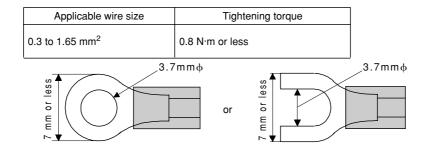
■ For AC Relay Wiring



Cable Specifications and Recommended Cables

Purpose	Name and Manufacturer
Power supply, grounding, relay contact outputs	600 V PVC insulated wires, JIS C 3307, 0.9 to 2.0 mm ²
Thermocouple	Shielded compensating lead wires, JIS C 1610, \(\subseteq X-\subseteq -\subseteq \) (See Yokogawa Electric's GS 6B1U1-E.)
RTD	Shielded wires (three conductors), UL2482 (Hitachi Cable)
Other signals	Shielded wires

Recommended Terminal Lugs



Terminal Covers

Target Model	Part Number	Sales Unit
For UT550	T9115YD	1
For UT520	T9115YE	1

1.4 Hardware Specifications

PV Input Signals

- Number of inputs: 1 (terminals[®]-[®]-[®])
- Input type: Universal input system. The input type can be selected with the software.
- Sampling period: Can be selected from 50, 100, 200 and 500 ms. Initial value: 200 ms
- Burnout detection: Functions at TC, RTD, standard signal (0.4 to 2 V or 1 to 5 V)
 Upscale, downscale, and off can be specified.

 For standard signal, burnout is determined to have occurred if it is 0.1 V or less.
- Input bias current: 0.05 μA (for TC or RTD b-terminal)
- Measurement current (RTD): About 0.13 mA
- Input resistance: 1 M Ω or more for thermocouple or mV input About 1 M Ω for DC voltage input
- Allowable signal source resistance: 250 Ω or less for thermocouple or mV input Effects of signal source resistance: 0.1 μ V/ Ω or less 2 k Ω or less for DC voltage input Effects of signal source resistance: About 0.01%/100 Ω
- Allowable wiring resistance: for RTD input Maximum 150 Ω /wire: Conductor resistance between three wires should be equal However, 10 Ω /wire for a maximum range of -150.0 to 150.0°C. Wire resistance effect: \pm 0.1°C /10 Ω
- Allowable input voltage: ±10 V DC for thermocouple, mV, or RTD input ±20 V DC for DC voltage input
- Noise rejection ratio: 40 dB (50/60 Hz) or more in normal mode 120 dB (50/60 Hz) or more in common mode
- Reference junction compensation error: ±1.0°C (15 to 35°C) ±1.5°C (0 to 15°C, 35 to 50°C)
- Applicable standards: JIS, IEC, DIN (ITS-90) for thermocouples and RTD

Remote Input Signals

Available only for controllers with remote input terminals.

- Number of inputs: 1 (terminals@-@)
- Input type: Settable in a range of 0-2, 0-10, 0.4-2.0, or 1-5 V DC
- Sampling period: 100, 200 and 500 ms
 The sampling period of a remote input signal is associated with the PV input's sampling period. If the PV input's sampling period is 50 ms, however, the sampling period of a remote input signal lengthens to 100 ms.
- Input resistance: About 1 $M\Omega$
- Input accuracy: ±0.3% ±1 digit of input span for 0 to 2 V DC ±0.2%±1 digit of input span for 0 to 10 V DC ±0.375%±1 digit of input span for 0.4 to 2.0 V DC ±0.3%±1 digit of input span for 1 to 5 V DC Under standard operating conditions (23±2°C, 55±10% RH, power frequency of 50/60 Hz)

Feedback Resistance Input

Provided for position proportional type only (terminals \$6-\$-\$7)

• Slide resistance value: 100 Ω to 2.5 k Ω of overall resistance (burnout detection for sliding wire provided)

Measuring resolution: ±0.1% of overall resistance

Loop Power Supply

Power is supplied to a two-wire transmitter.

(15 V DC: terminals @-6); 24 V DC: terminals @-4)

A resistor (10 to 250 Ω) connected between the controller and transmitter converts a current signal into a voltage signal, which is then read via the PV input terminal. Supply voltage: 14.5 to 18.0 V DC, max. 21 mA (provided with a protection circuit against a field short-circuit); 21.6 to 28.0 V DC, max. 30 mA (only for models with 24 V DC loop power supply)

Retransmission Output

Either PV, target setpoint, or control output is output. Either the retransmission output or the loop power supply can be used with terminals (4)-(5).

- Number of outputs: 1 or 2 (terminals [®]-[®]), terminals [®]-[®])
- Output signal: 4-20, 0-20, 20-4, or 20-0 mA DC (where, outputting signal levels of less than 0 mA is not feasible)
- Load resistance: 600 Ω or less
- Output accuracy: ±0.1% of span (±5% of span for 1 mA or less.)
 Under standard operating conditions (23 ±2°C, 55 ±10% RH, power frequency of 50/60 Hz)

Control Output

Universal output system, The output type can be selected with the software. Relay contact output(s) for the position proportional type

Current output (Standard type: terminals ®-®; heating-side output: terminals ®-®, cooling-side output: terminals ®-®)

Number of outputs	1 or 2 (two for heating/cooling type), switched between a voltage pulse output and current output.
Output signal	4-20, 0-20, 20-4, or 20-0 mA DC
Load resistance	600 Ω or less
Output accuracy	$\pm 0.1\%$ of span ($\pm 5\%$ of span for 1 mA or less) Under standard operating conditions (23 \pm 2 °C, 55 $\pm 10\%$ RH, power frequency of 50/60 Hz)

 Voltage pulse output (Standard type: terminals ®-⑦; heating-side output: terminals ®-⑦, cooling-side output: terminals ®-⑦)

Number of outputs	1 or 2 (two for heating/cooling type), switched between a voltage pulse output and current output.
Output signal	On-voltage = 12 V or more (load resistance: 600 Ω or more) Off-voltage = 0.1 V DC or less
Resolution	10 ms or 0.1% of output, whichever is larger

Relay contact output

(Standard type: terminals ①-②-③, heating-side output: terminals ①-②-③, cooling-side output: terminals @-@-⑤, position proportional type: terminals @-@-⑤)

Number of outputs	1 or 2(two for heating/cooling type)
realibor of outputs	1 of Z(two for fleating/cooling type)
Output signal	Three terminals (NC, NO, and common)
Contact rating	250 V AC or 30 V DC, 3 A (resistance load)
Resolution	10 ms or 0.1% of output, whichever is larger

Contact Inputs

- Purpose: Target setpoint selection, remote/local mode switching, and run/stop switching
- Number of inputs: Differs with model and suffix codes as shown in the table below.

Model and Suffix Codes	Number of Inputs
UT550-□0	2
UT550-□1	8
UT550-□2	3
UT550-□3	7
UT550-□4	3
UT520-00	2
UT520-07	4
UT520-08	4

- Input type: Non-voltage contact or transistor open collector input
- Input contact rating: 12 V DC, 10 mA or more
- On/off determination: For non-voltage contact input, contact resistance of 1 k Ω or less is determined as "on" and contact resistance of 20 k Ω or more as "off." For transistor open collector input, input voltage of 2 V or less is determined as "on" and leakage current must not exceed 100 μ A when "off."
- Minimum status detection hold time: PV input's sampling period ×3

Contact Outputs

Purpose: Alarm output, FAIL output, and others

• Number of outputs: Differs with the model and suffix code as shown in the table below.

Model and Suffix Codes	Number of Outputs
UT550-□0	3
UT550-□1	7
UT550-□2	3
UT550-□3	7
UT550-□4	3
UT520-00	3
UT520-07	3
UT520-08	3

Relay contact rating: 240 V AC, 1 A, or 30 V DC, 1 A

Transistor contact rating: 24 V DC, 50 mA

Display Specifications

 PV display:
 5-digit, 7-segment, red LEDs, character height of 20 mm for UT550 and 12 mm for UT520

 Setpoint display: 3-digit and 5-digit, 7-segment, red LEDs, character height of 9.3 mm (for both UT520 and UT550)

· Status indicating lamps: LEDs

Safety and EMC Standards

Safety: Compliant with IEC1010-1: 1990 and EN61010-1: 1992
 Approved by CSA1010
 CSA1010 installation category (overvoltage category): CATII (IEC1010-1)
 Approved by UL508

• EMC standards: This instrument complies with the following EMC standards (the instrument continues to operate at a measuring accuracy of within ±20% of the range during tests):

- EMI (emission), EN55011: Class A Group 1

- EMS (immunity), EN50082-2: 1995

Construction, Installation, and Wiring

 Construction: Only the front panel is dust-proof and drip-proof (protection class IP55)

For side-by-side close installation the controller loses its dust-proof and drip-proof protection.

Material: ABS resin and polycarbonate

· Case color: Black

· Weight: About 1 kg or less

· Dimensions:

UT550 — 96 (W) \times 96 (H) \times 100 (depth from panel face) mm UT520 — 48 (W) \times 96 (H) \times 100 (depth from panel face) mm

- Installation: Panel-mounting type. With top and bottom mounting hardware (1 each)

Panel cutout dimensions: UT550 — $92^{+0.8}_{0}$ (W) \times $92^{+0.8}_{0}$ (H) mm UT520 — $45^{+0.6}_{0}$ (W) \times $92^{+0.8}_{0}$ (H) mm

- Installation position: Up to 30° upward facing (not designed for facing downward)
- Wiring: M3.5 screw terminals (for signal wiring and power/ground wiring as well)

Power Supply Specifications

- Power supply: Rated voltage of 100 to 240 V AC (±10%), 50/60 Hz
- Power consumption: Max. 20 VA (8.0 W max.)
- Data backup: Non-volatile memory (can be written to up to 100,000 times)
- · Withstanding voltage
 - Between primary terminals* and secondary terminals**:

At least 1500 V AC for 1 minute (Note)

- Between primary terminals* and grounding terminal:

At least 1500 V AC for 1 minute (Note)

- Between grounding terminal and secondary terminals**:

At least 1500 V AC for 1 minute

- Between secondary terminals**:

At least 500 V AC for 1 minute

- Primary terminals indicate power terminals and relay output terminals
- **Secondary terminals indicate analog I/O signal, voltage pulse output, and contact input terminals

Note: The withstanding voltage is specified as 2300 VAC per minute to provide a margin of safety.

- Insulation resistance: 20 M Ω or more at 500 V DC between power terminals and grounding terminal
- Grounding: Class 3 grounding (grounding resistance of 100Ω or less)

Signal Isolations

- PV input terminals: Isolated from other input/output terminals. Not isolated from the internal circuit.
- Remote input terminals: Isolated from other input/output terminals and the internal circuit.
- 15 V DC loop power supply terminals: Not isolated from analog current output nor voltage pulse control output. Isolated from other input/output terminals and internal circuit.
- 24 V DC loop power supply terminals: Isolated from 4-20 mA analog output, other input/output terminals and the internal circuit.
- Analog current output terminals (for control output and retransmission): Not isolated between current outputs nor from 15 V DC loop power supply and voltage pulse control output. Isolated from other input/output terminals and internal circuit.
- Voltage pulse control output terminals: Not isolated from current outputs and 15 V DC loop power supply. Isolated from other input/output terminals and internal circuit.
- Relay contact control output terminals: Isolated between contact output terminals and from other input/output terminals and internal circuit.
- Contact input terminals: Not isolated between contact input terminals and from communication terminals. Isolated from other input/output terminals and internal circuit.

• Relay contact output terminals: Not isolated between relay contact outputs. Isolated from other input/output terminals and internal circuit.

- Transistor contact output terminals: Not isolated between transistor contact outputs. Isolated from other input/output terminals and internal circuit.
- RS-485 communication terminals: Not isolated from contact input terminals. Isolated from other input/output terminals and internal circuit.
- Feedback slide resistance input terminals: Not isolated from analog current output terminals (control, retransmission), 15 V DC loop power supply, and voltage pulse control outputs. Isolated from other input/output terminals and internal circuit.
- Power terminals: Isolated from other input/output terminals and internal circuit.
- Grounding terminals: Isolated from other input/output terminals and internal circuit.

Environmental Conditions

Normal operating conditions:

Ambient temperature: 0 to 50°C (40°C or less for side-by-side close installation)

Temperature change rate: 10°C/h or less

Ambient humidity: 20 to 90% RH (no condensation allowed)

Magnetic field: 400 A/m or less

Continuous vibration at 5 to 14 Hz: Full amplitude of 1.2 mm or less

Continuous vibration at 14 to 150 Hz: 4.9 m/s² or less Short-period vibration: 14.7 m/s², 15 seconds or less

Shock: 14.7 m/s² or less, 11 ms

Installation height: Height above sea level of 2000 m or less

Warm-up time: 30 minutes or more after power on

Transportation and storage conditions:

Temperature: -25 to 70°C

Temperature change rate: 20°C/h or less

Humidity: 5 to 95% RH (no condensation allowed)

- Effects of changes in operating conditions
 - Effects from changes in ambient temperature:
 - On voltage or thermocouple input, $\pm 1~\mu\text{V/°C}$ or $\pm 0.01\%$ of F.S./°C, whichever is larger
 - On remote input, ±0.02% of F.S./°C
 - On RTD input, ±0.05°C /°C (ambient temperature) or less
 - On analog output, ±0.05% of F.S./°C or less
 - Effects from power supply fluctuation (within rated voltage range)
 - On analog input, $\pm 1 \mu V/10 V$ or $\pm 0.01\%$ of F.S./10 V, whichever is larger
 - On analog output, $\pm 0.05\%$ of F.S./ 10 V or less

1.5 Terminal Wiring Diagrams

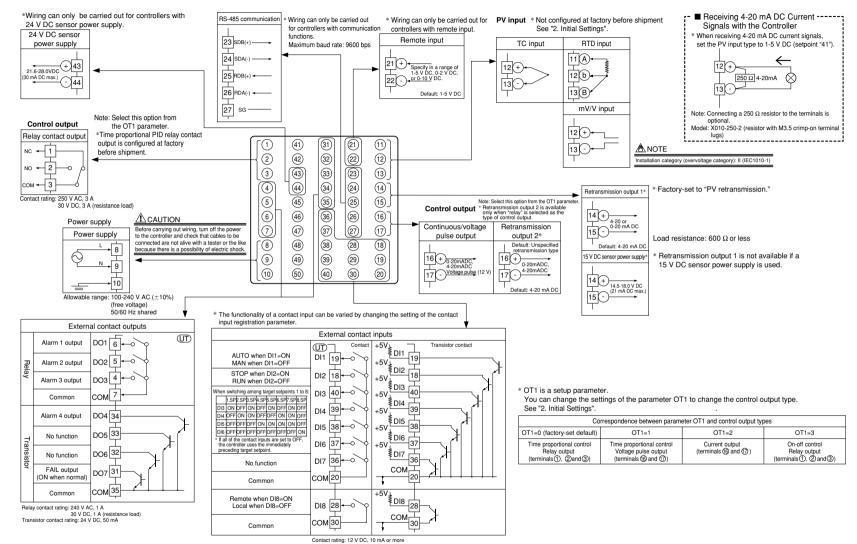


Do not use unassigned terminals as relay terminals.

Terminal wiring diagrams are shown on and after the next page.

IM 05D01C02-41E 1st Edition: Mar. 31, 2000-00

■ UT550 Standard Type (Model: UT550-0 or UT550-3), Single-loop Control



Note: External Contact Input

If the power is turned on when the external contact input is OFF, the mode (SPN, R/L, or A/M) existing before the power is turned off will be continued. (except for RUN/STOP)

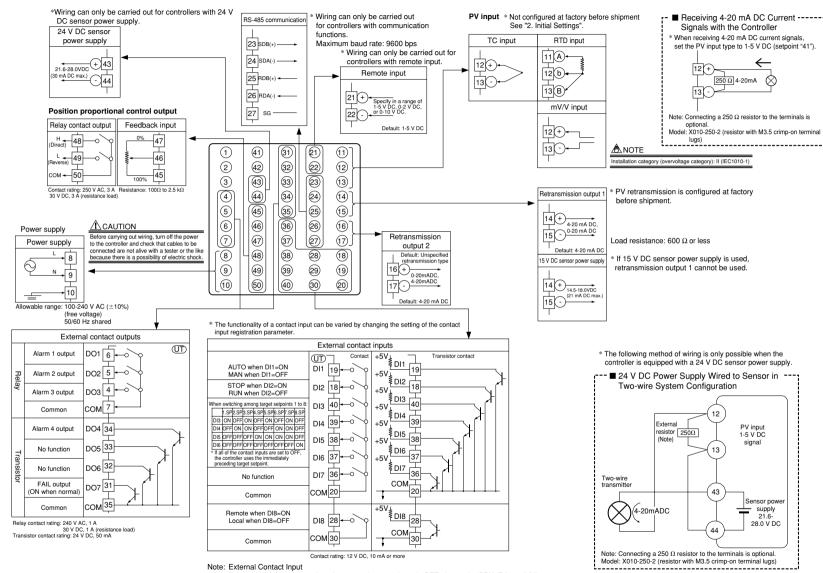
See 2. Illitial Settings .								
	Correspondence between parameter OT1 and heating side output types/cooling side output types							
OT1=4 (factory-set default)	OT1=5	OT1=6	OT1=7	OT1=8	OT1=9	OT1=10	OT1=11	OT1=12
(terminals (1), (2) and (3))	Heating side: Voltage pulse output (terminals (Band (17)) Cooling side: Relay output (terminals (8), (8) and (50))	(terminals@and (7))	Heating side: Relay output (terminals ①, ② and ③) Cooling side: Voltage pulse output (terminals ⑥ and ⑩)	Cooling side: Voltage pulse output	(terminals (6) and (7))		Heating side: Voltage pulse output (terminals (b) and (7)) Cooling side: Current output (terminals (b) and (7))	

The types of control output, "relay output" and "voltage pulse output" shown in the table above refer to those of time proportional control. To change to a relay output for on-off control, select "Relay Terminals" and change the setpoint of the proportional band to "0."

Coo "O Initial Cattings

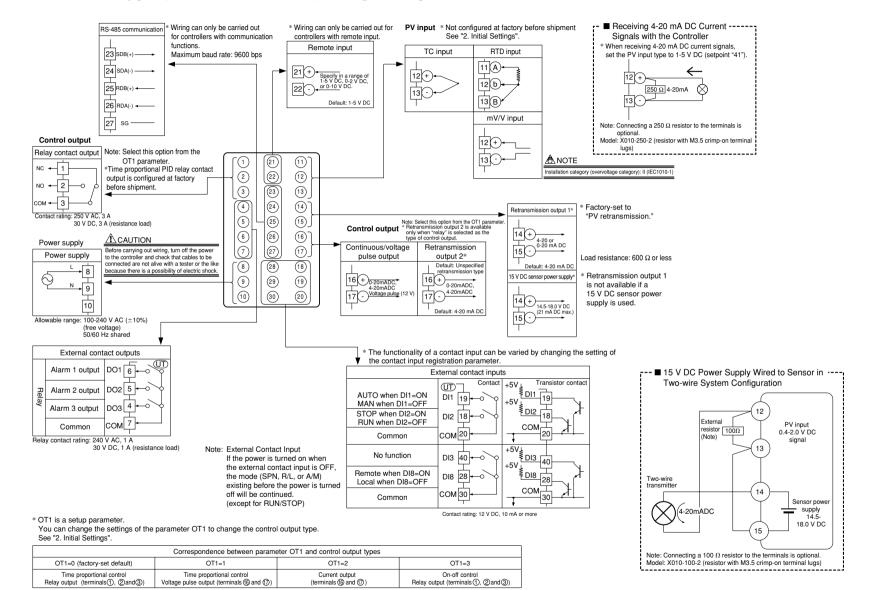
Installation

■ UT550 Position Proportional Type (Model: UT550-1 are uT550-4), Single-loop Position Proportional Control



If the power is turned on when the external contact input is OFF, the mode (SPN, R/L, or A/M) existing before the power is turned off will be continued. (except for RUN/STOP)

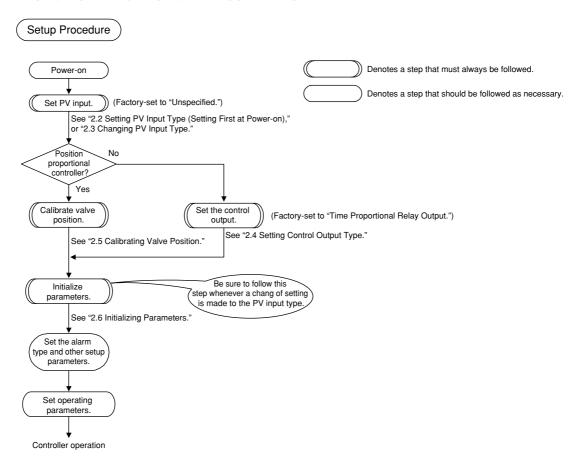
■ UT520 Standard Type (Model: UT520-0 □), Single-loop Control



1. Installation

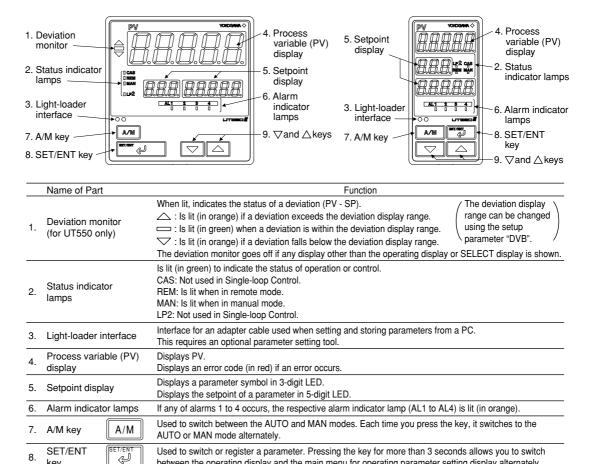
2. Initial Settings

This chapter describes examples of setting PV input types, control output types, and alarm types. Carrying out settings described herein allows you to perform basic control. Refer to examples of various settings to understand how to set parameters required. Refer to "5.1 Parameter Map" for an easy to understand explanation of setting various parameters. If you cannot remember how to carry out an operation during setting, press the key for more than 3 seconds. This brings you to the display (operating display) that appears at power-on.



The following explanation of operation for the UT550's panel, shown in the figure, is the same as that of the UT520's panel.

Names and Functions of Front Panel Parts 2.1



 ∇ and \triangle keys

kev

between the operating display and the main menu for operating parameter setting display alternately. Used to change numerical values. On setting displays for various parameters, you can change target setpoints, parameters, and output values (in manual operation). Pressing the ∇ key decreases a numerical value, while pressing the Δ key causes it to increase. You can hold down a key to gradually increase the speed of change. To change from the parameter setting (operating or setup) display to the menu or from the setup parameter setting display menu to operating parameter setting display menu, press the ∇ and \triangle keys simultaneously.

Setting of Main Parameters at the Factory before Shipment

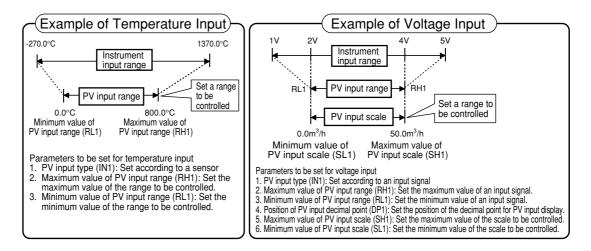
Item	Factory-shipped values for standard type controllers	Factory-shipped values for heating/cooling type controllers	Factory-shipped values for position proportional type controllers	
Remote input signal (only for controllers with remote inputs)	1 to 5 V DC (variable)			
Control output	Time proportional PID relay output (variable)	Heating side: Time proportional PID relay output (variable) Cooling side: Time proportional PID relay output (variable)	Relay output (fixed)	
Control action	Reverse action (variable) Not specified			
PID parameter	P = 5.0%, I = 240 seconds, D = 60 seconds.			
Alarm output	Alarm-1: PV high limit, Alarm-2: PV low limit, Alarm-3: PV high limit, Alarm-4: PV low limit			

2.2 Setting PV Input Type (Setting First at Power-on)



• The controller displays an operating display when the power is turned on. The submenu "IN" appears at this point if the type of PV input has not been defined yet. In this case, first press the key once to display the parameter "IN1" for the PV input type, and use the key to display the input range code to use, then press the key to register it. Then, set the maximum value (RH1) and minimum value (RL1) of the PV input range (for voltage input, set the maximum value (SH1) and minimum value (SL1) of the PV input scale). See the operating procedure below for more details.

 The controller is configured to the default of each parameter at the factory before shipment.
 First check these defaults listed in "5.2 Lists of Parameters", and change their values if necessary.

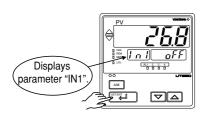


The following operating procedure describes an example of setting a K-type thermocouple (-200.0 to 500.0 °C) and a measurement range of 0.0 to 200.0 °C.

1. Display view at power-on



2. Press the key once to display the parameter IN1 (PV input type).



3. Press the or key to display the required setpoint.

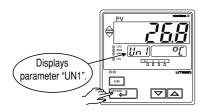
The figure below shows an example of setting a K-type thermocouple (-200.0°C to 500.0°C). See "Instrument Input Range Codes."



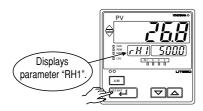
4. Press the key once to register the setpoint.



5. Press the key once to display the parameter "UN1" (PV input unit).



6. Press the key once to display the parameter "RH1" (maximum value of PV input range).



7. Press the a or key to display the required setpoint.

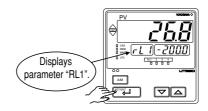
The figure below shows an example of setting the maximum value of the PV input range to 200.0°C.



8. Press the setpoint.



9. Press the key once to display the parameter "RL1" (minimum value of PV input range).



10. Press the △ or ▽ key to display the required setpoint.

The figure below shows an example of setting the minimum value of the PV input range to 0.0°C.



11. Press the key once to register the setpoint.



If the type of input is voltage, also configure the PV Input Decimal Point Position (DP1), Maximum Value of PV Input Scale (SH1) and Minimum Value of PV Input Scale (SL1) parameters that follow this step.

12. Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below).



The PV display in the figure above shows the error code for input burnout (b.o Ut) if PV input wiring is not yet complete. The error code disappears when you wire the PV input terminals correctly.

■ Instrument Input Range Codes

Input	Туре	Instrument Input Range Code	Instrument Input Range	Measurement Accuracy		
Unspecified		OFF	Set the data item PV Input Type "IN1" to the OFF option to leave the PV input type undefined.			
	К	1	-270.0 to 1370.0°C -450.0 to 2500.0°F			
		2	-270.0 to 1000.0°C -450.0 to 2300.0°F	±0.1% of instrument range ±1 digit at 0°C or more		
		3	-200.0 to 500.0°C -200.0 to 1000.0°F	±0.2% ±1 digit for temperatures below 0°C, where the accuracy is: ±2% of instrument range ±1		
	J	4	-200.0 to 1200.0°C -300.0 to 2300.0°F	digit for temperatures below -200.0°C for a type-K thermocouple, or $\pm 1\%$ of instrument range ± 1 digit		
	Т	5	-270.0 to 400.0°C -450.0 to 750.0°F	temperatures below -200.0°C for a type-T thermocouple.		
	'	6	0.0 to 400.0°C -200.0 to 750.0°F			
	В	7	0.0 to 1800.0°C 32 to 3300°F	±0.15% of instrument range ±1 digit at 400°C or motion ±5% of instrument range ±1 digit at less than 400°C		
	s	8	0.0 to 1700.0°C 32 to 3100°F	±0.15% of instrument range ±1 digit		
	R	9	0.0 to 1700.0°C 32 to 3100°F	, ,		
Thermocouple	N	10	-200.0 to 1300.0°C -300.0 to 2400.0°F	$\pm 0.1\%$ of instrument range ± 1 digit $\pm 0.25\%$ of instrument range ± 1 digit for temperatures below 0°C		
	E	11	-270.0 to 1000.0°C -450.0 to 1800.0°F			
	L(DIN)	12	-200.0 to 900.0°C -300.0 to 1600.0°F	$\pm 0.1\%$ of instrument range ± 1 digit at 0°C or more $\pm 0.2\% \pm 1$ digit for temperatures below 0°C, where the		
	U(DIN)	13	-200.0 to 400.0°C -300.0 to 750.0°F	accuracy is: $\pm 1.5\%$ of instrument range ± 1 digit for temperatures below -200.0°C for a type-E thermocouple		
		14	0.0 to 400.0°C -200.0 to 1000.0°F			
	w	15	0.0 to 2300.0°C 32 to 4200°F	±0.2% of instrument range ±1 digit		
	Platinel 2	16	0.0 to 1390.0°C 32.0 to 2500.0°F	±0.1% of instrument range ±1 digit		
	PR20-40	17	0.0 to 1900.0°C 32 to 3400°F	$\pm 0.5\%$ of instrument range ± 1 digit at 800°C or more No accuracy is guaranteed at less than 800°C		
	W97Re3- W75Re25	18	0.0 to 2000.0°C 32 to 3600°F	±0.2% of instrument range ±1 digit		
	JPt100	30	-200.0 to 500.0°C -300.0 to 1000.0°F	±0.1% of instrument range ±1 digit (Note 1) (Note 2)		
		31	-150.00 to 150.00°C -200.0 to 300.0°F	±0.2% of instrument range ±1 digit (Note 1)		
	Pt100	35	-200.0 to 850.0°C -300.0 to 1560.0°F	\pm 0.1% of instrument range \pm 1 digit (Note 1) (Note 2)		
		36	-200.0 to 500.0°C -300.0 to 1000.0°F	,		
	0.44-01/	37	-150.00 to 150.00°C -200.0 to 300.0°F	±0.2% of instrument range ±1 digit (Note 1)		
Standard	0.4 to 2 V	40	0.400 to 2.000 V			
signal	1 to 5 V	41	1.000 to 5.000 V	±0.1% of instrument range ±1 digit		
	0 to 2 V	50	0.000 to 2.000 V	Display range is scalable in a range of -19999 to 30000.		
DC voltage	0 to 10 V	51	0.00 to 10.00 V	Display span is 30000 or less.		
	-10 to 20 mV	55	-10.00 to 20.00 mV	, , , , , , , , , , , , , , , , , , , ,		
	0 to 100 mV	56	0.0 to 100.0 mV			

Model: X010-250-2 (resistor with M3.5 crimp-on terminal lugs)

^{*} Performance in the standard operating conditions (at 23±2°C, 55±10%RH, and 50/60 Hz power frequency)

Note 1: The accuracy is ±0.3°C of instrument range ±1 digit for a temperature range from 0°C to 100°C.

Note 2: The accuracy is ±0.5°C of instrument range ±1 digit for a temperature range from -100°C to 200°C.

* To receive a 4-20 mA DC signal, select a standard signal of 1 to 5 V DC and connect it to a 250Ω resistor. This resistor



NOTE

The controller may automatically initialize the registered operating parameter setpoints if any change is made to the data item PV Input Type (IN1), Maximum Value of PV Input Range (RH1), Minimum Value of PV Input Range (RL1), PV Input Decimal Point Position (DP1), Maximum Value of PV Input Scale (SH1) or Minimum Value of PV Input Scale (SL1). After a change has been made to any of these data items, be sure to verify the registered operating parameter setpoints to ensure that they are correct. If any data item has been changed to its default, set it to a required value.



How to return to a menu

IM 05D01C02-41E 1st Edition: Mar. 31, 2000-00

2.3 Changing PV Input Type

The following operating procedure describes an example of changing the setting of K-type thermocouple (-200.0 to 500.0 °C) to RTD Pt100

(-200.0 to 500.0°C) and a measurement range of 0.0 to 200.0°C.

1. Bring the operating display into view (display appears at power-on).



2. Press the key for more than 3 seconds to call up the main menu "MODE".



3. Press the key once to display the main menu "STUP".



4. Press the key once to display the main menu "LOOP1".



5. Press the key once to display the main menu "UTMD".



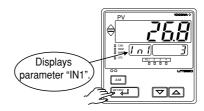
6. Press the key once to display the submenu "MD".



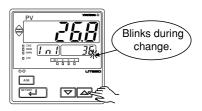
7. Press the key once to display the submenu "IN".



8. Press the key once to display the parameter "IN1" (PV input type).



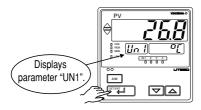
9. Press the or key to display the required setpoint. The figure below shows an example of setting the PV input type to a Pt100 resistance temperature detector (-200.0°C to 500.0°C).



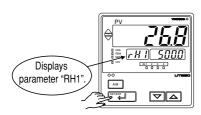
10. Press the key once to register the setpoint.



11. Press the key once to display the parameter "UN1".



12. Press the key once to display the parameter "RH1" (maximum value of PV input range).



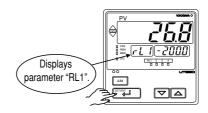
13. Press the or key to display the required setpoint. The figure below shows an example of setting the maximum value of the PV input range to 200.0°C.



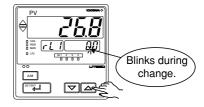
14. Press the key once to register the setpoint.



15. Press the key once to display the parameter "RL1" (minimum value of PV input range).



16. Press the △ or ▽ key to display the required setpoint. The figure below shows an example of setting the minimum value of the PV input range to 0.0°C.

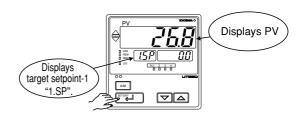


17. Press the key once to register the setpoint.



If the type of Input is voltage, also configure the PV Input Decimal Point Position (DP1), Maximum Value of PV Input Scale (SH1), and Minimum Value of PV Input Scale (SL1) parameters that follow this step.

18. Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below).

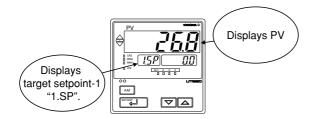


2.4 Setting Control Output Type (except for a Position Proportional Controller)

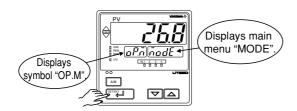
The following operating procedure describes an example of changing time proportional PID relay output (0: factory-shipped value) to continuous output (2).

For details on the output terminals for heating/cooling control, see "1.5 Terminal Wiring Diagrams".

1. Bring the operating display into view (display appears at power-on).



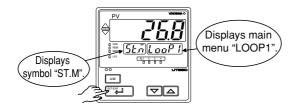
2. Press the key for more than 3 seconds to call up the main menu "MODE".



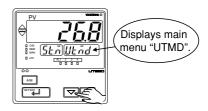
3. Press the key once to display the main menu "STUP".



4. Press the key once to display the main menu "LOOP1".



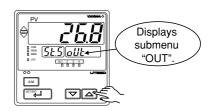
5. Press the key once to display the main menu "UTMD".



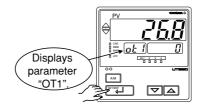
6. Press the key once to display the submenu "MD".



7. Press the key twice to display the submenu "OUT".



8. Press the key once to display the parameter "OT1" (control output type).



9. Press the a or we key to display the required setpoint. The figure below shows an example of setting to continuous output (4 to 20 mA DC).



10. Press the key once to register the setpoint.



11. Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below).



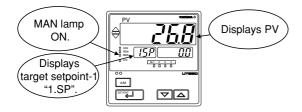
● List of Control Output Types

Parameter Symbol	Name of Parameter	Setpoint	Control Output Types
		0	Time proportional PID relay contact output (terminals ① - ② - ③)
		1	Time proportional PID voltage pulse output (terminals (6) - (7))
		2 Current output (terminals ® - ⑦)	
		3	On/off control relay contact output (terminals ① - ② - ③)
		The following 4 to 12 are displayed only for heating/ cooling type controllers.	
OC 1	Control output type	4 Heating-side relay output (terminals ① - ② - ③), cooling-side relay output (terminals ® - 5 Heating-side pulse output (terminals ® - ①), cooling-side relay output (terminals ® - ® - ® - ® - ® - ® - ® - ® - ® - ®	
(OT1)			
		6	Heating-side current output (terminals 6 - 7), cooling-side relay output (terminals 6 - 6)
		7	Heating-side relay output (terminals ① - ② - ③), cooling-side pulse output (terminals ⑥ - ⑥)
		8	Heating-side pulse output (terminals 6 - 7), cooling-side pulse output (terminals 6 - 7)
		9	Heating-side current output (terminals 6 - 7), cooling-side pulse output (terminals 6 - 7)
		10	Heating-side relay output (terminals ① - ② - ③), cooling-side current output (terminals ⑥ - ⑥)
		11	Heating-side pulse output (terminals 6 - 7), cooling-side current output (terminals 6 - 7)
		12	Heating-side current output (terminals (6) - (7)), cooling-side current output (terminals (6) - (7))

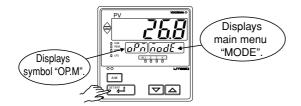
2.5 Calibrating Valve Position (for a Position Proportional Controller Only)

The following operation describes a procedure of inputting a feedback signal from a control valve to calibrate the full closed and full open positions of the valve automatically. To calibrate the valve position, you need to carry out wire connections and bring the controller into manual mode. For connections, see "1.5 Terminal Wiring Diagrams" and for entering the manual mode, see "3.8 Switching between AUTO and MAN".

1. Bring the operating display into view (display appears at power-on).



2. Press the key for more than 3 seconds to call up the main menu "MODE".



3. Press the key once to display the main menu "STUP".



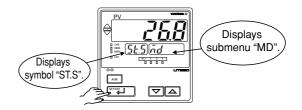
4. Press the key once to display the main menu "LOOP1".



5. Press the key once to display the main menu "UTMD".



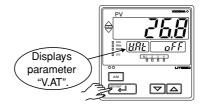
6. Press the key once to display the submenu "MD".



7. Press the key three times to display the submenu "VALV".



8. Press the key once to display the parameter "V.AT".



9. Press the key to display "ON".



10. Press the key once. The controller automatically calibrates the valve position (fully open or closed).



11. The controller is viewed as shown below when the valve position is being automatically calibrated.

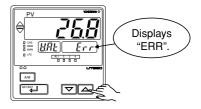


12. Calibration has ended successfully when the indication changes from "ON" to "OFF". Go to step [14].

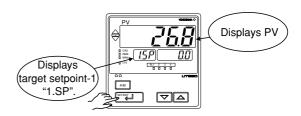


13. Calibration has ended unsuccessfully if the indication changes from "ON" to "ERR".

Check the feedback input wiring and carry out automatic calibration again.



14. Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below).



2.6 Initializing Parameters

Be sure to follow the steps below after a change of setting has been made to the data item PV Input Type, PV Input Range or PV Input Scale.

1. Bring the operating display into view (display appears at power-on).



2. Press the key for more than 3 seconds to call up the main menu "MODE".



3. Press the key once to display the main menu "STUP".



4. Press the key once to display the main menu "LOOP1".



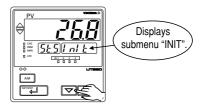
5. Press the key once to display the main menu "UTMD".



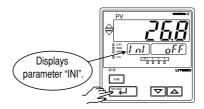
6. Press the key once to display the submenu "MD".



7. Press the key twice to display the submenu "INIT".



8. Press the key once to display the parameter "INI".



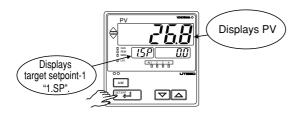
9. Press the A key to display "ON".



10. Press the key once. The display momentarily becomes blank (which is normal), indicating the parameters have been initialized.



11. Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below).



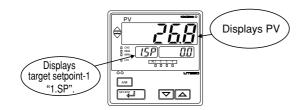
2.7 Changing Alarm Type

The following operating procedure describes an example of changing alarm 1 (factory-set to the PV high limit alarm) to the PV low limit alarm.

When you have changed alarm type, the alarm setpoint will be initialized; set the alarm setpoint again.

Alarm output terminals	Factory-shipped settings
Alarm-1 (terminal numbers 6-7)	PV high limit alarm
Alarm-2 (terminal numbers ⑤- ⑦)	PV low limit alarm
Alarm-3 (terminal numbers 4-7)	PV high limit alarm
Alarm-4 (terminal numbers 49-36)	PV low limit alarm

1. Bring the operating display into view (display appears at power-on).



2. Press the key for more than 3 seconds to call up the main menu "MODE".



3. Press the ☑ key once to display the main menu "STUP".



4. Press the key once to display the main menu "LOOP1".



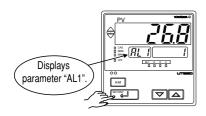
5. Press the key once to display the submenu "SP".



6. Press the key once to display the submenu "ALM".



7. Press the key once to display the parameter "AL1" (alarm-1 type).



8. Press the a or we key to display the required setpoint. The figure below shows an example of setting the PV lower-limit alarm.



9. Press the key once to register the setpoint.



You can take the same steps for alarm-2 type (AL2), alarm-3 type (AL3), and alarm-4 type (AL4) that are displayed after this.

10. Press the ^{□□□□□} key for more than 3 seconds. This returns you to the display shown at power-on (figure below).



11. When setting alarm setpoints, see "3.5 Setting Alarm Setpoints".

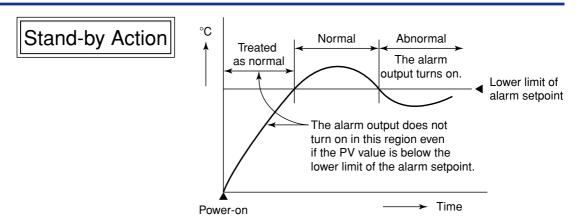
■ List of Alarm Types

The table below shows the alarm types and alarm actions. In the table, codes 1 to 10 are not provided with stand-by actions, while codes 11 to 20 are provided with stand-by actions.

	Alarm action	Alarm ty	pe code		Alarm action	Alarm ty	pe code
Alarm type	"Open/close" shows status of relay contact, and "lit" and "unlit" shows status of lamp	Contact closes if alarm occurs Contact opens if alarm occurs		Alarm type	"Open/close" shows status of relay contact, and "lit" and "unlit" shows status of lamp	Contact closes if alarm occurs	Contact opens if alarm occurs
No alarm		0	FF		Hysteresis	/	
PV high limit	Open (unlit) Closed (lit)	1		De-energized on deviation low limit alarm	Open (lit) Deviation Target SP Closed (unlit) PV		6
PV low limit	Closed (lit) Open (unlit) Alarm setpoint PV	2		Deviation high and low limits	Hysteresis Hysteresis Closed Open (unlit) Closed (lit) PV Target SP	7 17	
Deviation high limit	Open (unlit) PV Deviation setpoint Target SP	3		Deviation within high and low limits	Hysteresis Open (unlit) Deviation setpoint! Target SP	8	
Deviation low limit	Hysteresis Closed (lit) Open (unlit) Deviation setpoint A PV Target SP	4 14		De-energized on PV high limit	Closed Open (lit) PV Alarm setpoint		9
De-energized on deviation high limit alarm	Closed (unlit) PV Pv Deviation Target SP		5 15	De-energized on PV low limit	Open (lit) Closed (unlit) Alarm setpoint PV		10 20
	Upward (hour/minute)	21		Sensor grounding alarm	Sensor grounding alarm	25	
Timer function	Downward (hour/minute)	22	/	Fault diagnosis output (Note1)	Fault diagnosis output	26	
(Alarm-1 only)	Upward (minute/second) Downward (minute/second)	23		FAIL output (Note2)	The controller stops when in a FAIL state. The control output is set to "OFF" or "0%" and the alarm output is set to "OFF".	27	
SP high limit	Open (unlit) Alarm setpoint	28		Output high limit	Open (unlit) Output value Hysteresis Closed (lit) Alarm setpoint	30	
SP low limit	Hysteresis Closed (lit) Open (unlit) Alarm setpoint SP	29		Output low limit	Hysteresis Closed (lit) Open (unlit) Alarm setpoint Output value	31	

Note 1:The fault diagnosis output turns on in case of input burnout, A/D converter failure, or reference junction compensation (RJC) failure. For input burnout or A/D converter failure, the control output is set to the setpoint of the Preset Output Value operating parameter (PO).

Note 2:The FAIL output is on during normal operation and turns off in case of failure.



2.8 Description of Multiple Setpoints and PID

The UT550/UT520 has a maximum of eight target setpoints, and has PID for each of these setpoints. The following shows the correspondence between the target setpoint numbers (SPN), target setpoints (SP), and PID parameters.

For example, if you have set "2" to the target setpoint number (SPN), the control parameters available are target setpoint (2.SP), proportional band (heating-side proportional band) (2.P), integral time (heating-side integral time) (2.I), derivative time (heating-side derivative time) (2.D), cooling-side proportional band (2.Pc), cooling-side integral time (2.Ic), and cooling-side derivative time (2.Dc).

To use multiple target setpoints, see the table below to check the corresponding parameters.

Target setpoint	Target			PID pai	rameter		
number (SPN)	setpoint (SP)	Proportional band (heating-side proportional band)	Integral time (heating-side integral time)	Derivative time (heating-side derivative time)	Cooling-side proportional band	Cooling-side integral time	Cooling-side derivative time
SPN=1	1.SP	1.P	1.l	1.D	1.Pc	1.lc	1.Dc
SPN=2	2.SP	2.P	2.1	2.D	2.Pc	2.lc	2.Dc
SPN=3	3.SP	3.P	3.1	3.D	3.Pc	3.lc	3.Dc
SPN=4	4.SP	4.P	4.1	4.D	4.Pc	4.lc	4.Dc
SPN=5	5.SP	5.P	5.I	5.D	5.Pc	5.lc	5.Dc
SPN=6	6.SP	6.P	6.1	6.D	6.Pc	6.lc	6.Dc
SPN=7	7.SP	7.P	7.1	7.D	7.Pc	7.lc	7.Dc
SPN=8	8.SP	8.P	8.1	8.D	8.Pc	8.lc	8.Dc

Operations

This chapter describes key entries for operating the controller. For operations using external contact inputs, see "1.5 Terminal Wiring Diagrams". If you cannot remember how to carry out an operation during setting, press the wey for more than 3 seconds. This brings you to the display (operating display) that appears at poweron.

3.1 Monitoring-purpose Operating Displays Available during Operation

The monitoring-purpose operating displays available during operation are roughly classified into two groups depending on the types of controller and control output. One group is operating displays for standard and position proportional controllers and the other group is operating displays for a heating/cooling controller.

■ Operating Displays for Standard and Position Proportional Controllers

SP display

The PV input value appears on the PV display.

The target setpoint value (1.SP) appears on the Setpoint display.

OUT Display

The PV input value appears on the PV display.

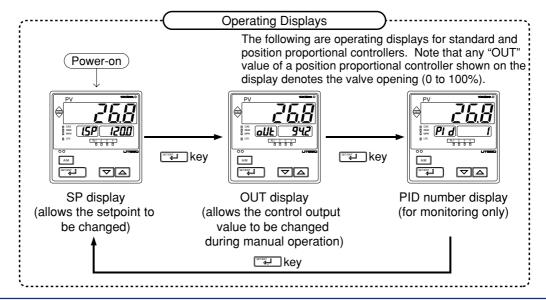
The control output value (OUT) appears on the Setpoint display.

When in position proportional control, the Setpoint display shows the valve opening (0% to 100%).

PID Number Display

The PV input value appears on the PV display.

The PID number (PID) being used appears on the Setpoint display.



■ Operating Displays for a Heating/Cooling Controller

SP display

The PV input value appears on the PV display.

The target setpoint value (1.SP) appears on the Setpoint display.

Heating/Cooling OUT Display

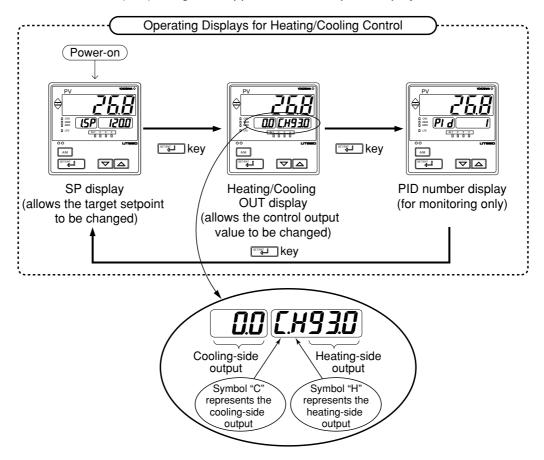
The PV input value appears on the PV display.

The heating and cooling sides control output value (C.H) appears on the Setpoint display.

PID Number Display

The PV input value appears on the PV display.

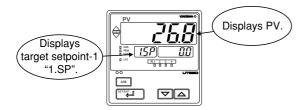
The PID number (PID) being used appears on the Setpoint display.



3.2 Setting Target Setpoint (SP)

The following operating procedure describes an example of setting 150.0 to a target setpoint. In automatic operation, the controller starts control using set target setpoints.

1. Bring the operating display into view (display appears at power on).



2. Press the \(\triangle \) or \(\triangle \) key to display the required setpoint.



3. Press the key once to register the value



3.3 Performing/Canceling Auto-tuning

Auto-tuning should be carried out after setting a target setpoint (SP). Make sure the controller is in automatic operation mode (AUTO) and in running state (RUN) before carrying out auto-tuning. See "3.8 Switching between AUTO and MAN," to change to AUTO and "3.7 Switching between Run and Stop," to change to Run.



NOTE

When on-off control is being used, auto-tuning cannot be carried out. Moreover, do not perform auto-tuning when controlling any of the following processes.

- Control processes with quick response such as flow control or pressure control
- Processes where even temporary output on/off results in inconvenience
- Processes where a large output change at control element results in inconvenience
- Processes where variations in PV may exceed an allowable range, adversely affecting product quality

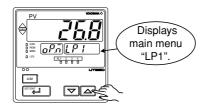
1. Bring the operating display into view (display appears at power on).



2. Press the key for more than 3 seconds to call up the main menu "MODE".



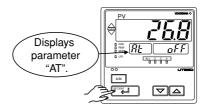
3. Press the key once to display the main menu "LP1".



4. Press the key once to display the submenu "PAR".



5. Press the key once again to display the parameter "AT".



6. Press the △ or ▽ key to display the required setpoint. Tuning for 1.SP is AT = 1.



To cancel auto-tuning, set AT = OFF.

7. Press the key once to register the setpoint. (This starts auto-tuning.)

If the key is pressed when AT = OFF, auto-tuning will be cancelled. In this case, PID contains the value existing before auto-tuning.



8. During auto-tuning, the panel indications become as shown below.



Auto-tuning is complete when the MAN lamp goes off.

3.4 Setting PID Manually

If you know the values to be set or if suitable PID constants cannot be obtained by autotuning, follow the procedure below to set values.

1. Bring the operating display into view (display appears at power on).



2. Press the key for more than 3 seconds to call up the main menu "MODE".



3. Press the key once to display the main menu "LP1".



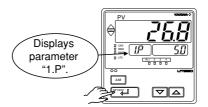
4. Press the key once to display the submenu "PAR".



5. Press the key once to display the submenu "1.PID".



6. Press the key six times to display parameter "1.P" (proportional band for 1.SP).



7. Press the or key to display the required setpoint.



8. Press the key once to register the setpoint.



The same steps can be used for integral time (1.l), derivative time (1.D) that are displayed after this.

[TIP]

For the PID parameter number you set in step 5, select: the submenu "1.PID" if the PID constants are for 1.SP; the submenu "2.PID" if the PID constants are for 2.SP; the submenu "3.PID" if the PID constants are for 3.SP; and the submenu "4.PID" if the PID constants are for 4.SP.

9. Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below).



3.5 Setting Alarm Setpoints

The following operating procedure describes an example of setting 160.0 to alarm-1 setpoint. Check alarm type before setting the alarm setpoint.

When changing the alarm type, see "2.7 Changing Alarm Type,".

1. Bring the operating display into view (display appears at power on).



2. Press the key for more than 3 seconds to call up the main menu "MODE".



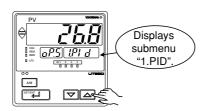
3. Press the key once to display the main menu "LP1".



4. Press the key once to display the submenu "PAR".



5. Press the key once to display the submenu "1.PID".



6. Press the street key twice to display the

Alarm-1 (terminal numbers 6-7)

Alarm-2 (terminal numbers ⑤-⑦).

Alarm-3 (terminal numbers 4-7)

Alarm-4 (terminal numbers 34-35).

Factory-shipped settings

..PV high limit alarm

..PV low limit alarm

..PV high limit alarm

..PV low limit alarm

Alarm output terminals



parameter "1.A1".

7. Press the or key to display the required setpoint.



8. Press the key once to register the setpoint.



You can take the same steps for alarm-2 setpoint(1. A2), alarm-3 setpoint(1. A3), alarm-4 setpoint(1. A4) that are displayed after this.

9. Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below).



3.6 Selecting Target Setpoint Numbers (SPN)

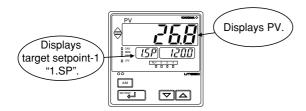
The following operating procedure describes an example of changing a target setpoint number (SPN) from 1 to 2.



NOTE

If a target setpoint number has been switched using contact input, when the contact input is on, that number cannot be selected by keystroke.

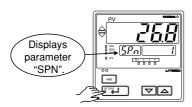
 Bring the operating display into view (display appears at power on).



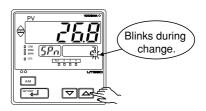
2. Press the key for more than 3 seconds to call up the main menu "MODE".



3. Press the key several times to display the parameter "SPN".



4. Press the \(\triangle \) or \(\triangle \) key to display the required setpoint.



5. Press the key once to register the setpoint.

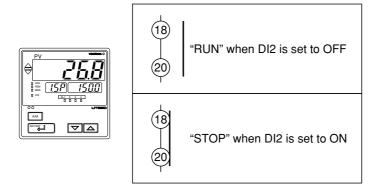


6. Press the key for more than 3 seconds. This returns you to the display shown at power-on (figure below).



3.7 Switching between Run and Stop

Selection between the Run state (RUN) and Stop state (STOP) can be made with contact input 2 (DI2).



When at a stop, the controller behaves as described below:

PV input	Displays the PV value.		
Control output	Provides the preset output value (factory-set to 0%).		
Alarm output	Turns the output on in case of an alarm.		

3.8 Switching between AUTO and MAN



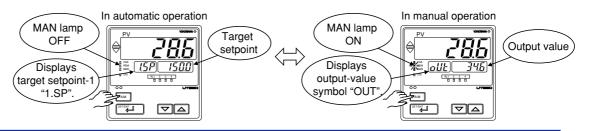
NOTE

If AUTO and MAN have been switched using contact input, when the contact input is ON, switching between AUTO and MAN cannot be achieved by keystroke.

1. Bring the operating display into view (display appears at power on).



2. Each time you press the key on the front panel of the instrument, AUTO and MAN is switched alternately.



3.9 Manipulating Control Output during Manual Operation

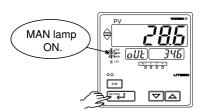


NOTE

Control output cannot be changed if the controller is stopped. In this case, the preset output value (operating parameter PO) will be output.

A control output value is linked with a display value changed using the \triangledown or \triangle key. Note that the control output changes as displayed without requiring the \triangledown key.

1. Bring manual operating display into view. For switching to manual operation, see "3.8 Switching between AUTO and MAN".

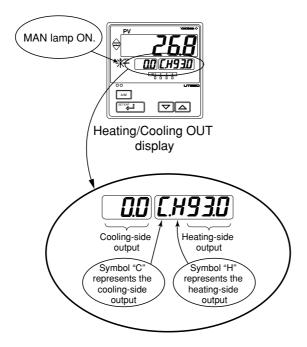


2. Press the or key to change a control output value. You don't need to press the key.



■ Manipulating the Control Output during Heating/Cooling Control

Showing the Heating/Cooling OUT display.



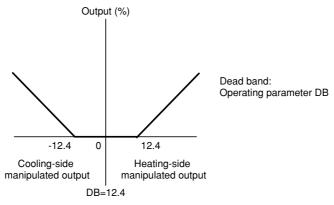
Controller behavior and control output manipulation when the dead band is positive

The following is an example when the DB parameter is set at 12.4%.

If you hold down the \Box key with the heating-side output under manipulation (i.e., cooling-side output C = 0.0%), the heating-side output C = 0.0%, the heating-side output C = 0.0% and C = 0.0% are in the heating-side output C = 0.0%.

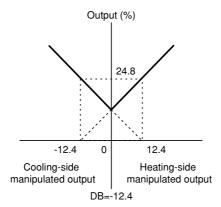
Consequently, both the heating-side and cooling-side outputs change to 0.0%. If you keep the key held down longer, you enter the state of manipulating the cooling-side output, and its value begins to increase.

Inversely, if you hold down the \triangle key with the cooling-side output under manipulation (i.e., heating-side output H = 0.0%), the cooling-side output (C =) decreases. Consequently, both the heating-side and cooling-side outputs go to 0.0%. If you keep the \triangle key held down longer, you enter the state of manipulating the heating-side output, and its value begins to increase.



Change in manipulated output when the dead band is positive

Controller behavior and control output manipulation when the dead band is negative



Change in manipulated output when the dead band is negative

■ Manipulating the Control Output during Position Proportional Control

The controller continues to provide control output <u>as long as the ▼ or △ key is being pressed.</u>

▼ key : Closes the valve.
△ key : Opens the valve.



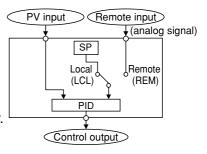
OUT display

3.10 Switching between Remote (REM) and Local (LCL)

The following operating procedure describes an example of switching from Local (LCL) to remote (REM). Switching between REM and LCL is possible for only controllers with remote input feature.

Local:

Performs control using target setpoints set in the controller.



Remote:

Performs control using external analog signals as target setpoints.

Note: The PID group number when the controller is in remote-mode operation is the same as the number set in the Target Setpoint Number (SPN) parameter.



NOTE

If remote status is achieved by external contact input (contact input is ON), switching between REM and LCL cannot be achieved by keystroke.

1. Bring the operating display into view (display appears at power on).



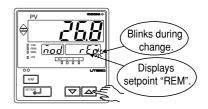
2. Press the key for more than 3 seconds to call up the main menu "MODE".



3. Press the key several times to display the parameter "MOD".



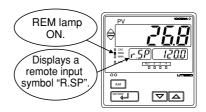
4. Press the △ or ▽ key to display "REM".



5. Press the key once to register the setpoint.



Automatically return to the display shown at power-on (figure below).

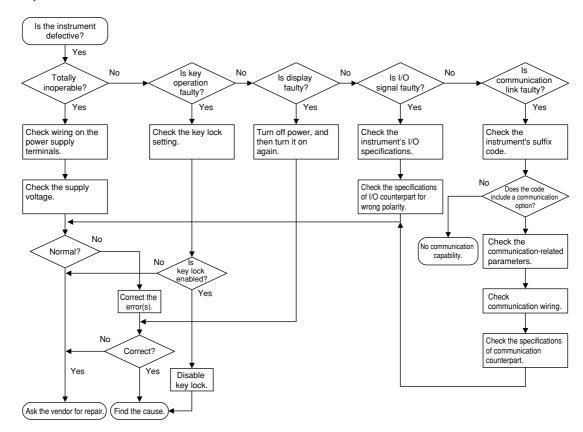


4. Troubleshooting and Maintenance

4.1 Troubleshooting

■ Troubleshooting Flow

If the operating display does not appear after turning on the controller's power, follow the measures in the procedure below. If a problem appears complicated, contact our sales representative.





IMPORTANT

Take note of the parameter settings when asking the vendor for repair.

■ Errors at Power On

The following table shows errors that may be detected by the fault diagnosis function when the power is turned on.

Error indication (on PV display unit)	Description of error	PV	Control output	Alarm output	Retransmission output	Communication	Remedy
E000 (E000)	Faulty RAM	Nissa		055			
E00 I (E001)	Faulty ROM	None	0% or less or OFF	OFF	0% or less	Stopped	Faulty
E002 (E002)	System data error	Undefined	01 01 1	Undefined	Undefined		Contact us
PV decimal point blinks.	Faulty calibration value	Normal action (out of accuracy)		for repair.			
Error code (Note) (See description below.)	Parameter error	Normal action	0% or less or OFF	Normal action	Normal action	Normal action	Check and set the initialized parameters.

Note: An error code is displayed on the setpoint display unit.

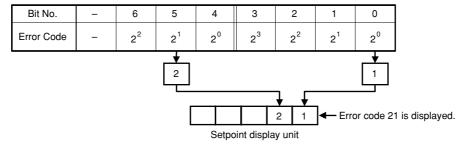
An error code is displayed in the event of an error, according to its type.

An error code is a two-digit figure in which a combination of 6 bits of on and off is converted into a decimal number.

The following shows the relationship between each bit and parameter to be checked for abnormality.

Bit No.	6	5	4	3	2	1	0
Parameter to be checked	Operation mode/output	Operating parameters	Setup parameters	Range data	_	-	Calibration data

For example, if an error occurs with the operating parameter and calibration data, the error code will be as follows:



■ Possible Errors during Operation

The following shows possible errors occurring during operations.

Error indication (on PV display unit)	Description of error	PV	Control output	Alarm output	Retransmis- sion output	Commu- nication	Remedy
Displays "RJC" and PV alternately	RJC error	Measured with RJC=0	Normal action				
Decimal point of item part in SP display unit blinks.	EEPROM error	Normal action	Normal action				Faulty Contact us for repair.
E 300 (E300)	ADC error	105%	In AUTO:				
bollt (B.OUT)	PV burnout error	Dependent on the BSL parameter Up-scale: 105% Down-scale: -5%	Preset value output In MAN: Normal action		Normal action		Check wires and sensor.
aller (OVER) or -aller (-OVER)	Excessive PV Out of -5 to 105%	-5% or 105%	Normal action	Normal action		Normal action	Check process.
E200 (E200)	Auto-tuning failure (Time-out)		Action with PID existing before auto-tuning	action		action	Check process. Press any key to erase error indication.
Setpoint display	Feedback resistor breakdown	Normal action	Stopped		Stopped		Check the feedback resistor.
Left end of SP display unit blinks.	Faulty communication line		Normal action		Normal action		Check wires and communication parameters, and make resetting. Recovery at normal receipt
Decimal point at right end lights.	Runaway (due to defective power or noise)	Undefined	0% or less or OFF	OFF	0% or less	Stopped	Faulty if power off/on does not reset start the unit. Contact us for repair.
All indications off	Power off	None					Check for abnormal power.

■ Remedies if Power Failure Occurs during Operations

The operation status and remedies after a power failure differ with the length of power failure time:

Instantaneous power failure of 20 ms or less

A power failure is not detected. Normal operation continues.

Power failure of about 2 seconds or less

The following show effects caused in "settings" and "operation status."

Alarm action	Continues. Alarm with standby function will enter standby status.
Setting parameter	Set contents of each parameter are retained.
Auto-tuning	Cancelled.
Control action	Action before power failure continues.

Power failure of more than about 2 seconds

The following show effects caused in "settings" and "operation status."

Alarm action	Continues. Ala	Continues. Alarm with standby function will enter standby status.			
Setting parameter	Set contents of	of each parameter are retained.			
Auto-tuning	Cancelled.				
Control action	Differs with se	oiffers with setting of setup parameter "R.MD"(restart mode).			
	R.MD setting	R.MD setting Control action after recovery from power failure			
	CONT	CONT Action before power failure continues. (factory-shipped setting)			
	MAN	MAN Outputs preset output value (PO) as control output and continues action set before power failure in MAN mode.			
	AUTO	AUTO Outputs preset output value (PO) as control output and continues action set before power failure in AUTO mode.			
	For heating/co	poling control, preset output value is 50% of PID computation.			

■ Troubleshooting When the Controller Fails to Operate Correctly

If your control tasks are not successful, check the preset parameters and controller wiring before concluding the controller to be defective. The following show some examples of troubleshooting you should refer to in order to avoid the possibility of other problems.

The controller does not show the correct process variable (PV).

The UT550/UT520 controllers have a universal input.
 The type of PV input can be set/changed using the parameter "IN1". At this point, the controller must be wired correctly according to the selected type of PV input. Check the wiring first if the controller fails to show the correct PV value. To do this, refer to "2. Initial Settings".

With the parameters "RH1", "RL1", "DP1", "SH1" and "SL1", it is possible to scale the input signal and change its number of decimal places. Also check that these parameters are configured correctly.

The controller does not provide any control output or the control output does not change at all.

- The UT550/UT520 controllers have a universal output.
 The type of control output can be set/changed using the parameter "OT1".
 At this point, the controller must be wired correctly according to the selected type of control output. Check the wiring first if the controller provides no control output. To do this, refer to "1.5 Terminal Wiring Diagrams".
 With the parameters "OH" and "OL", it is possible to set/change the high and low limits of control output. The control output may not change at all, however, because of restrictions on these parameters. Also check the restrictions on these parameters.
- The control output can only be changed when the controller is in the MAN mode.
 If the MAN lamp is off (i.e., the controller is in the AUTO mode), you cannot change the control output using key operation.

The control output does not change soon after the target setpoint SP has been changed.

• If this happens, check the setpoint of the parameter "MOD". In cases where fixed-point control is selected as the PID control mode (MOD = 1), tracking based on the I-term works to prevent the control output from changing suddenly even if the target setpoint SP is varied.

The control output therefore may appear to be working incorrectly at first; however it gradually adapts itself to the new target setpoint. Be especially careful when the controller is in the fixed-point control mode; the control output may fail to change and therefore result in a loss of control if you change the target setpoint SP too frequently.

IM 05D01C02-41E 1st Edition: Mar. 31, 2000-00

4.2 Maintenance

This section describes the cleaning and maintenance of the UT550/UT520.

4.2.1 Cleaning

The front panel and operation keys should be gently wiped with a dry cloth.



NOTE

Do not use alcohol, benzine, or any other solvents.

4.2.2 Replacing Brackets

When the brackets are broken or lost, purchase the following brackets for replacement.

Target Model	Part No.	Sales Unit
UT550	T9115NL	A large bracket and small bracket in pair
UT520	T9115NK	Two small brackets in pair

See Also "1.2 How to Install," for how to replace brackets.

4.2.3 Attaching Terminal Cover

When a terminal cover is necessary, purchase the following part.

Target Model	Part No.	Sales Unit
UT550	T9115YD	1
UT520	T9115YE	1

■ Attaching Terminal Cover

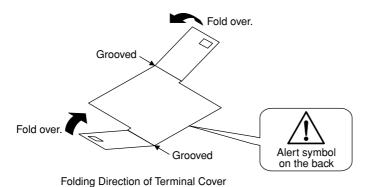
The procedure for attaching the terminal cover is as follows.



Do not touch the terminals on the rear panel when power is being supplied to the controller. Doing so may result in electric shock.

Before attaching the terminal cover, turn off the source circuit breaker and use a terster to check that the power cable is not conducting any electricity.

1. Before attaching the terminal cover, fold it once or twice or that the side which has the "Handle With Care" symbol (\(\frac{1}{2}\)\), is on the outside.

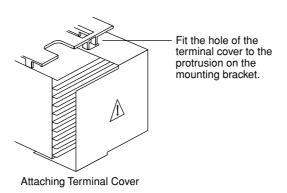




NOTE

Do not fold the terminal cover the wrong way, doing so not only reduces the cover's strength but may also cause the hinge to crack, thereby disabling attachment.

2. With the cover properly folded, fit its top and bottom holes to the protrusion of the mounting brackets.



4.2.4 Replacing Parts with a Limited Service Life

The follwing UT550/UT520 parts have a limited service life. The service life given in the table assume that the controller is used under normal operating conditions.

Part	Service life
Aluminum electrolytic condenser	About 10 years (rated)
EEPROM	About 100,000 times of writings
Alarm output relays	About 100,000 more ON-OFF operations or with resistance load
Control output relays	About 100,000 more ON-OFF operations or with resistance load

If any of these parts, except control output relays, cause a controller failure due to deterioration, contact your dealer for replacement at your cost. Control output relays can be replaced by yourself.

See Also "4.2.5 Replacing Control Output Relays", for how to replace the control output relays.

4.2.5 Replacing Control Output Relays

This section describes how to replace the control output relays.

The replacement must be performed by an engineer qualified for the work.

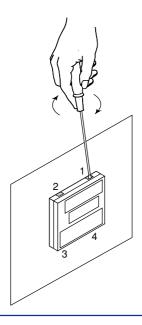


Always turn off the power before starting the work in order to avoid electric shock. Do not pull out the internal unit for any other purpose other than to replace the control output relays.

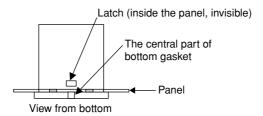
1. Insert a flat-blade screwdriver (tip width of 6mm is recommended) into the opening (4 openings are on the top and bottom of bezel) with the tip in parallel with the front panel, and then turn the screwdriver gently.

Take this procedure to four openings 1, 2, 3, and 4 (see the figure below) on the upper and lower parts of the bezel, in order.

The bezel slightly moves forward from the housing.

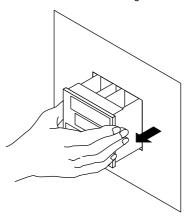


2. Push up the central part of bottom gasket of bezel by a finger to release the latch.

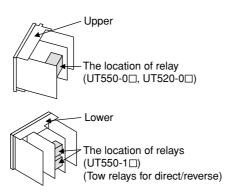


- 3. Insert a flat-blade screwdriver into the openings again, and complete the same procedure as step 1 to move the bezel more forward.
- 4. Hold the bezel and pull it along with the internal unit out of the housing.

Note: Be careful not to damage the RJC sensor.



5. The location and number of the relays differ depending on the model code of the UT550/UT520 Confirm the location of the control output relay to be replaced before pulling out the relay.



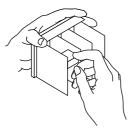
6. Pull out the relay to be replaced.

The control output relays are easy to remove and mount, since they are connected via a socket onto the print boards.

Insert the new relay in the socket.

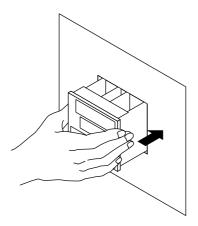
Use the following relay.

Manufacture	OMRON	
Model	G6B-2114P-FD-US-P6B	
Power supply	12 V DC	



7. Insert the internal unit into the housing.

Apply power to the controller and confirm that the initial operating display is shown. If the operating display is not shown properly, turn off the controller and pull out the internal unit. Then, insert it into the housing again.



This completes replacement of the control output relay.

5. Parameters

5.1 Parameter Map

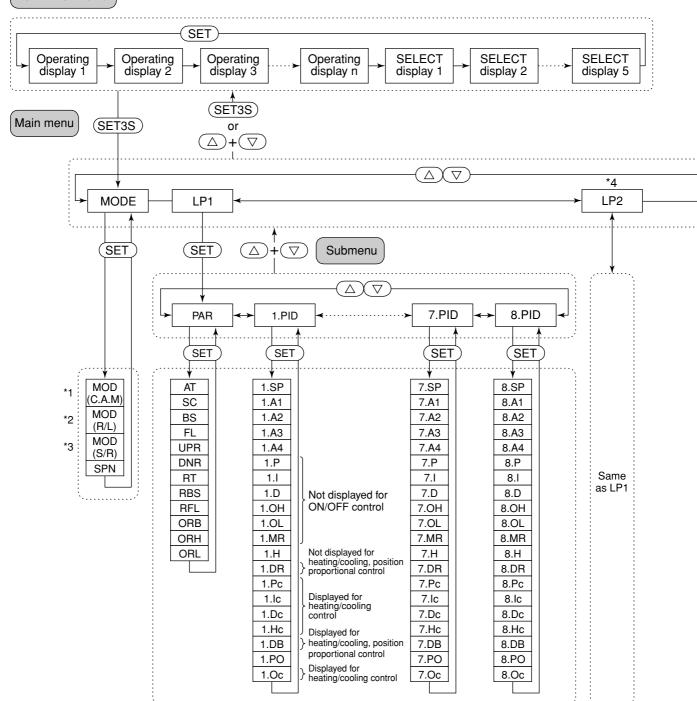
This section contains "Operating Parameter Map" and "Setup Parameter Map" for UT550/UT520 as a guideline for setting parameters.

These maps are helpful in finding the positions of the displays when setting the parameters, and should be used as a quick reference for the entire range of parameter displays.

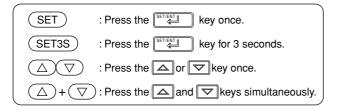
IM 05D01C02-41E 1st Edition: Mar. 31, 2000-00

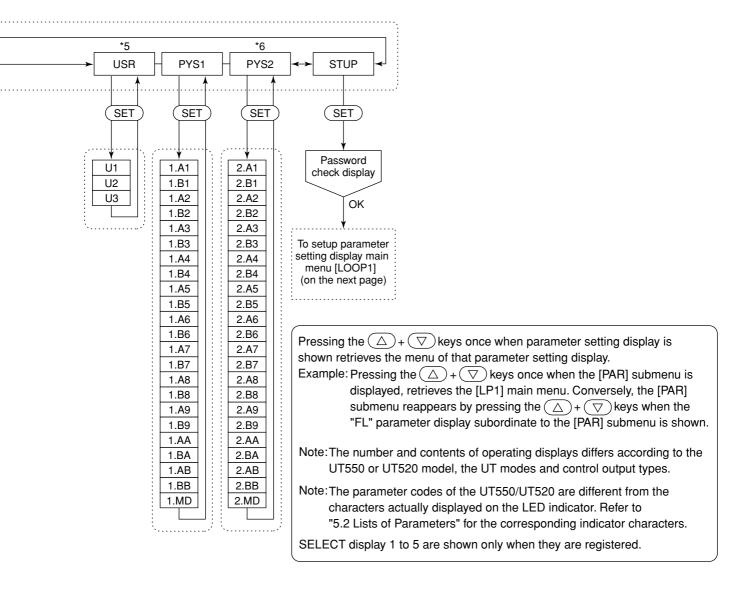
UT550/UT520 Operating Parameter Map

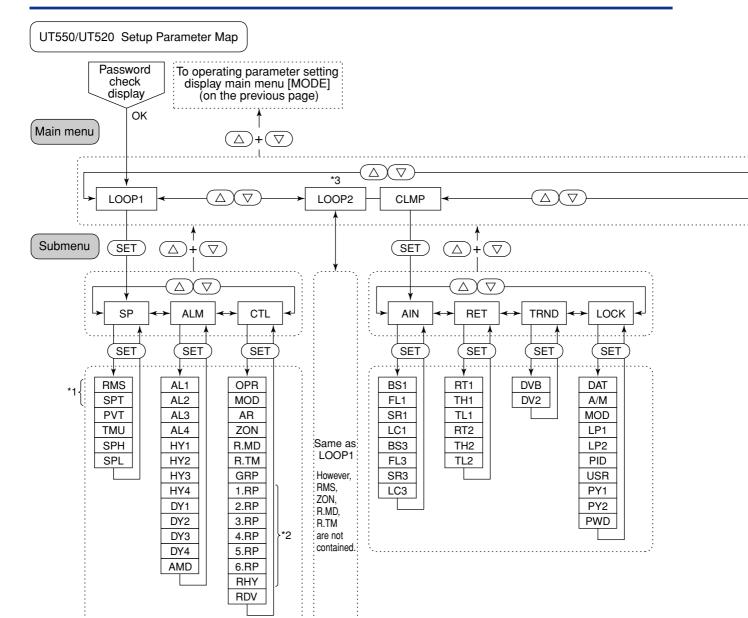
Operating display



- *1 Parameter MOD (C.A.M.) is displayed when UT mode is "Cascade secondary-loop control", or "Cascade control."
- *2 Parameter MOD (R/L) is displayed only for the controller with auxiliary analog (remote) input.
- *3 Parameter MOD (S/R) is displayed when parameter S/R for registering contact input (setup parameter) is "0."
- *4 Main menu LP2 is displayed when UT mode is "Cascade control."
- *5 Main menu USR is displayed when UT mode is "Loop control with PV switching", or "Loop control with PV auto-selector."
- *6 Main menu PYS2 is displayed when UT mode is "Cascade control."



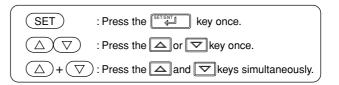


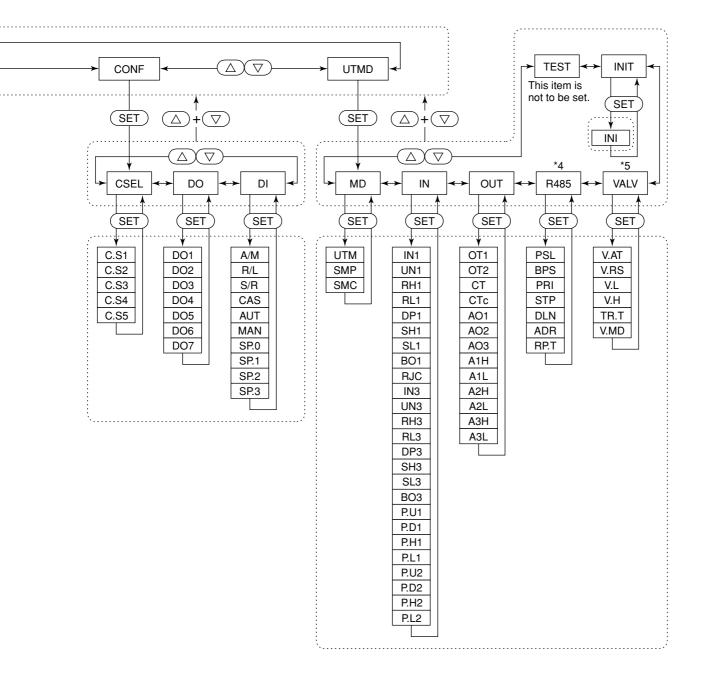


Pressing the \triangle + ∇ keys when a parameter setting display is shown retrieves the menu of that parameter setting display.

Note: The parameter codes of the UT550/UT520 are different from the characters actually displayed on the LED indicator. Refer to "5.2 Lists of Parameters" for the corresponding indicator characters.

- *1 Parameters RMS and SPT are displayed only for the controller with auxiliary analog (remote) input.
- *2 Displayed when parameter ZON is "1."
- *3 Main menu LOOP2 is displayed when UT mode is "Cascade control."
- *4 Submenu R485 is displayed only for the controller with communication.
- *5 Submenu VALV is displayed for the position proportional controller





Note: The parameter items shown on the [TEST] submenu of the setup parameter display are to be used by Yokogawa service personnel to check the controller functions. Users cannot set or change these parameters.

Note: The parameter codes of the UT550/UT520 are different from the characters actually displayed on the LED indicator. Refer to "5.2 Lists of Parameters" for the corresponding indicator characters.

5.2 Lists of Parameters

This section describes the functions of parameters briefly. In addition, each parameter table has a "User Setting" column, where you can record your setpoints when setting them in the controller.

- * Parameters relating to PV or setpoints should all be set in real numbers. For example, use temperature values to define target setpoints and alarm setpoints for temperature input.
- * The "User Setting" column in the table below is provided for the customer to record setpoints.
- * The column "Target Item in CD-ROM" in the table below provides references from User's Manual (Reference) (CD-ROM Version) which describes items in more detail and items that are not contained in this manual.
- * Numbers in () are the parameter setpoints that apply when the communication function is used. ex. REM (1), LCL (0)

■ Operating Parameters

Operation Mode Parameters

Located in: Main menu = (MODE)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
ngd (MOD)	Remote/Local switching	Set to "Local" when carrying out control using the target setpoints of the controller or to "Remote" when using target setpoints acquired via a remote input signal or communication. Use the setup parameter RMS, "Remote Input Selection," to determine whether the target setpoints should be acquired via the remote input signal or communication. REM (1): Remote mode LCL (0): Local mode	LCL (0)		_
(MOD)	Run/Stop switching	Outputs the predetermined (preset) fixed value when the controller stops. A preset output value can be defined for each target setpoint using the operating parameter "PO". Stop (1): Stops operation. Run (0): Starts operation.			_
SPN)	Target setpoint number selection	1: Selects target setpoint-1 (1.SP). 2: Selects target setpoint-2 (2.SP). 3: Selects target setpoint-3 (3.SP). 4: Selects target setpoint-4 (4.SP). Likewise, options 5 to 8 select target setpoints 5 (5.SP) to 8 (8.SP).	1		_

Operation-related Parameters

Located in: Main menu = \mathbf{P} \mathbf{P} \mathbf{I} (LP1); Submenu = \mathbf{P} \mathbf{P} (PAR)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
AL (AT)	Auto-tuning	OFF (0): No auto-tuning 1: Auto-tuning for 1.SP 2: Auto-tuning for 2.SP 3: Auto-tuning for 3.SP 4: Auto-tuning for 4.SP 5 to 8: Perform auto-tuning on a group basis in the same way as 1 to 4 9: Performs auto-tuning to all groups 1 to 8.	OFF (0)		_
5 (SC)	"SUPER" function	OFF (0): Disable 1: Overshoot suppressing function Suppresses overshoots generated by abrupt changes in the target setpoint or by disturbances. 2: Hunting suppressing function (Stable mode) Suitable to stabilize the state of control when the load varies greatly, or the target setpoint is changed. Enables to answer the wider characteristic changes compared with Response mode. 3: Hunting suppressing function (Response mode) Enables quick follow-up and short converging time of PV for the changed target setpoint. Note: Use "SUPER" function (SC) 2 or 3 in PID control or PI control. "SUPER" function 2 or 3 is not available in the following controls: 1) ON/OFF control 2) P control (control for proportional band only) 3) PD control (control for proportional band and derivative item only) 4) Heating/cooling control	OFF (0)		Ref.2.1(5) Ref.2.1(6)
65	PV input bias	Do not use hunting suppressing function when control processes with response such as flow or pressure control. -100.0% to 100.0% of PV input range span	0.0% of PV		D-11 1(1)
FL (BS)	PV input filter	Used to correct the PV input value. OFF (0), 1 to 120 sec Used when the PV input value fluctuates.	input range span OFF (0)		Ref.1.1(1) Same as
UPr	Setpoint ramp-up-rate	OFF (0) 0.0% + 1 digit of PV input range span to 100.0% of PV input range span	OFF (0)		above Ref.4.1(4)
(UPR)	Setpoint ramp-down-rate	Set ramp-up-rate or ramp-down-rate per hour or minute. Sets unit in ramp-rate-time unit (TMU). Used to prevent the target setpoint from changing suddenly. The ramp setting function works when: 1. the target setpoint is changed (e.g., "1.SP" is changed from 100°C to 150°C); 2. the target setpoint number (SPN) is changed (e.g., the parameter is changed from 1.SP to 2.SP); 3. the power is turned on or has recovered from a failure; or 4. the operating mode is changed from Manual to Auto. 1.SP 2.SP 2.SP Rate of temperature change of 70°C/min (i.e., 140°C/2 min) Temperature rise time of 2 min	OFF (0)		Same as above
r L	Ratio setting	Switch from 1.SP to 2.SP 0.001 to 9.999 Target setpoint = Remote input × Ratio setpoint + Remote bias	1.000		Ref.1.2(3)
r b5	Remote input bias	-100.0 to 100.0% of PV input range span Used to correct the remote input value.	0.0% of PV input range span		Same as above
rFL (RFL)	Remote input filter	OFF (0), 1 to 120 sec. Used when the remote input value fluctuates.	OFF (0)		Same as above
ORB)	ON/OFF rate detection band	0.0 to 100.0% of PV input range span	1.0% of PV input range span		Ref.3.3(4)
OFH (ORH)	ON/OFF rate high limit	ORL + 1 digit to 105.0%	100.0 %		Same as above
ORL)	ON/OFF rate low limit	-5.0% to ORH - 1 digit	0.0%		Same as above

IM 05D01C02-41E 1st Edition: Mar. 31, 2000-00

● Setpoint-, Alarm- and PID-related Parameters

Located in: Main menu = (LP1); Submenu = (LP1) (1.PID)

The table below lists the Target Setpoint-1 (1.SP) operating parameter and parameters that apply to the 1.SP parameter.

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
(1.SP)	Target setpoint-1	0.0 to 100.0% of PV input range However, between target setpoint limiter lower limit (SPL) and upper limit (SPH).	0.0% of PV input range		Ref.4.1(1)
(1.A1)	Alarm-1 setpoint	PV alarm / SP alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input	PV high limit/SP high limit alarm: 100.0% of PV input range		Ref.4.1(1)
(1.A2)	Alarm-2 setpoint	range span Output alarm: -5.0 to 105.0% Timer alarm (for alarm-1 only):	Deviation alarm: 0.0% of PV input range span Other PV/SP low limit		Same as above
(1.A3)	Alarm-3 setpoint	0.00 to 99.59 (hour, min) or (min, sec) Allows alarms 1 to 4 (1.A1 to 1.A4) to be set for	alarm: 0.0% of PV input range Output high limit		Same as above
(1.A4)	Alarm-4 setpoint	target setpoint 1 (1.SP). Four alarms can also be set for target setpoints 2 to 8.	alarm: 100.0% Output Low limit alarm: 0.0%		Same as above
(1.P)	Proportional band/Heating- side proportional band (in heating/cooling control)	0.1 to 999.9% of PV input range In heating/cooling control: 0.0 to 999.9% (heating-side on/off control applies when 0.0)	5.0%		Same as above
(1.1)	Integral time Heating-side integral time (in heating/cooling control)	OFF (0), 1 to 6000 sec.	240 sec.		Same as above
(1.D)	Derivative time Heating-side derivative time (in heating/cooling control)	OFF (0), 1 to 6000 sec.	60 sec.		Same as above
(1.OH)	Output high limit Heating-side output high limit (in heating/cooling control)	-5.0 to 105.0% Heating-side limiter in heating/cooling control: 0.0 to 105.0% (1.OL < 1.OH)	100% Heating/cooling control: 100.0%		Ref.2.1(3)
(1.OL)	Output low limit Cooling-side output high limit (in heating/cooling control)	-5.0 to 105.0% Cooling-side limiter in heating/cooling control: 0.0 to 105.0% (1.OL < 1.OH) SD (shutdown): Set in manual operation in 4-20 mA control output.	0.0% Heating/cooling control: 100.0%		Ref.4.1(1)
(1.MR)	Manual reset	-5.0 to 105.0% (enabled when integral time "1.I" is OFF) The manual reset value equals the output value when PV = SP is true. For example, if the manual reset value is 50%, the output value is 50% when PV = SP becomes true.	50.0%		Ref.4.1(1)
(1.H)	ON/OFF control hysteresis Heating-side ON/OFF control hysteresis (in heating/cooling control)	In ON/OFF control: 0.0 to 100.0% of PV input range span Position proportional PID control or heating/cooling control: 0.0 to 100.0% Hysteresis can be set in the target setpoint when the controller is performing ON/OFF control.	ON/OFF control: 0.5% of PV input range span Position proportional PID control and heating/cooling control: 0.5%		
		Output On On Off Overland On On On On Off ON/OFF action (Target setpoint) On Off Overland On On Off Overland On On Overland On On On Off Overland On			Same as above
(1.DR)	Direct/reverse action switching	RVS (0): reverse action, DIR (1): direct action Control output 100%	RVS (0)		Detotion
		Reverse Direct action +			Ref.2.1(1)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
! P	Cooling-side proportional band	0.0 to 999.9% of PV input range (Cooling-side ON/OFF control applies when 0.0)	5.0%		Ref.4.1(1)
(1.lc)	Cooling-side integral time	OFF (0), 1 to 6000 sec.	240 sec.		Same as above
!.dc (1.Dc)	Cooling-side derivative time	OFF (0), 1 to 6000 sec.	60 sec.		Same as above
!H _(1.Hc)	Cooling-side ON/OFF control hysteresis	0.0 to 100.0%	0.5%		Same as above
(1.DB)	Dead band	In heating/cooling control: -100.0 to 50.0% In position proportional PID control: 1.0 to 10.0% • When performing heating/cooling control: setting any positive value prohibits both the heating and cooling outputs from turning on; setting any negative value allows both the heating and cooling outputs to turn on; and setting a value of zero either the heating or cooling output to turn on. • When performing position proportional control: set the range so none of the outputs turn on.	3.0%		Same as above
!P _	Preset output/Heating- side preset output (in heating/cooling control)	-5.0 to 105.0% In heating/cooling control: Heating side 0.0 to 105.0% In Stop mode, fixed control output can be generated.	0.0%		Ref.2.1(8)
(1.Oc)	Cooling-side preset output	0.0 to 105.0% In Stop mode, cooling-side fixed control output can be generated.	0.0%		Ref.4.1(1)

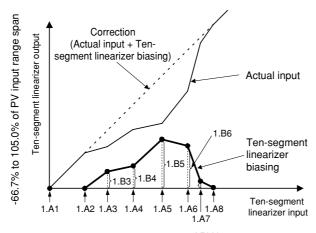
If you are using two or more groups of setpoint, alarm and PID parameters, use the following table to record their values. $\frac{1}{2} \int_{\mathbb{R}^{n}} \frac{1}{2} \int$

Parameter	n=2	n=3	n=4	n=5	n=6	n=7	n=8
n.SP							
n.A1							
n.A2							
n.A3							
n.A4							
n.P							
n.l							
n.D							
n.OH							
n.OL							
n.MR							
n.H							
n.DR							
n.Pc							
n.lc							
n.Dc							
n.Hc							
n.DB							
n.PO							
n.Oc							

● Ten-segment Linearizer Parameters

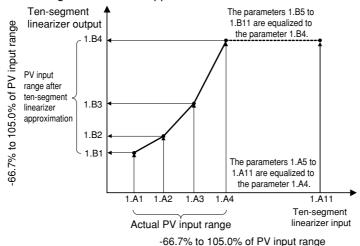
Located in: Main menu =

■ Ten-segment linearizer biasing (factory-set default)



-66.7% to 105.0% of PV input range

● Ten-segment linearizer approximation



Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
(1.A1)	Ten-segment linearizer 1 input-1	-66.7% to 105.0% of PV input range	0.0% of PV input range		Ref.1.1(2)
(1.B1)	Ten-segment linearizer 1 output-1	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.A2)	Ten-segment linearizer 1 input-2	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
(1.B2)	Ten-segment linearizer 1 output-2	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.A3)	Ten-segment linearizer 1 input-3	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
(1.B3)	Ten-segment linearizer 1 output-3	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.A4)	Ten-segment linearizer 1 input-4	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
(1.B4)	Ten-segment linearizer 1 output-4	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.A5)	Ten-segment linearizer 1 input-5	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
(1.B5)	Ten-segment linearizer 1 output-5	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.A6)	Ten-segment linearizer 1 input-6	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
(1.B6)	Ten-segment linearizer 1 output-6	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.A7)	Ten-segment linearizer 1 input-7	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
(1.B7)	Ten-segment linearizer 1 output-7	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.A8)	Ten-segment linearizer 1 input-8	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
(1.B8)	Ten-segment linearizer 1 output-8	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.A9)	Ten-segment linearizer 1 input-9	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
(1.B9)	Ten-segment linearizer 1 output-9	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.AA)	Ten-segment linearizer 1 input-10	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
(1.BA)	Ten-segment linearizer 1 output-10	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.AB)	Ten-segment linearizer 1 input-11	-66.7% to 105.0% of PV input range	0.0% of PV input range		Same as above
(1.BB)	Ten-segment linearizer 1 output-11	-66.7% to 105.0% of PV input range span -66.7% to 105.0% of PV input range when in ten-segment linearizer approximation	0.0% of PV input range span 0.0% of PV input range when in ten-segment linearizer approximation		Same as above
(1.MD)	Ten-segment linearizer 1 mode	Ten-segment linearizer biasing Ten-segment linearizer approximation	0		Same as above

■ Setup Parameters

● Target Setpoint-related Parameters

Located in: Main menu = L_{QQP} (SP)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
rn5	Remote input selection	RSP (1): Uses the value set remotely via remote input (terminals). COM (0): Uses the value set remotely via communication.	RSP (1)		Ref.1.2(1)
5PŁ	SP tracking selection	OFF (0), ON (1) Tracking is performed when the mode changes from Remote to Local (The local setpoint keeps track of the remote setpoint.)	ON (1)		Ref.4.1(3)
PHE	PV tracking selection	Causes the setpoint to keep track of the PV value so the setpoint automatically reverts to its original value at a preset rate of change. The Setpoint Ramp-up (UPR) and Setpoint Ramp-down (DNR) parameters are used in combination. - Operating conditions - 1: Manual operation → Automatic operation; 2: Stop → Start of automatic operation; 3: Power-on; 4: Change SP number OFF (0): Disable ON (1): Enable	OFF (0)		Ref.1.1(7)
L nU	Ramp-rate time unit setting	Time unit of setpoint ramp-up (UPR) and setpoint ramp-down (DNR) HOUR (0): Denotes "per hour." MIN (1): Denotes "per minute."	HOUR (0)		Ref.4.1(4)
5PH (SPH)	Target setpoint limiter upper limit	0.0% to 100.0% of PV input range. Note that SPL < SPH Places limits on the ranges within which the target setpoints	100.0% of PV input range		_
5PL (SPL)	Target setpoint limiter lower limit	(1.SP to 8.SP) are changed.	0.0% of PV input range		_

Alarm-related Parameters

Located in: Main menu = [[[LOOP1]]; Submenu = [[[(ALM)]]

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
AL	Alarm-1 type	OFF (0), 1 to 31 (same as below) Common to all target setpoints.	1		Ref.3.3(3) Ref.3.3(4)
RL2	Alarm-2 type	OFF (0), 1 to 20, 25 to 31 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action)	2		Ref.3.3(4)
AL3	Alarm-3 type	3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action)	1		Same as above
RL4	Alarm-4 type	Deviation low limit (de-energized, no stand-by action) For other alarm types, see "2.7 Changing Alarm Type." Common to all target setpoints.	2		Same as above
H 411	Alarm-1 hysteresis	0.0 to 100.0% of PV input range span Output alarm: 0.0 to 100.0% Allows margins to be set for an alarm setpoint.	0.5% of PV input range span Output		Ref.3.3(2)
H42 (HY2)	Alarm-2 hysteresis	With the hysteresis settings, it is possible to prevent relays from chattering. Hysteresis for PV high limit alarm Output Point of ON/OFF action	alarm: 0.5%		Same as above
HY3)	Alarm-3 hysteresis	On (Alarm setpoint)			Same as above
H44)	Alarm-4 hysteresis	Off Hysteresis PV value			Same as above
dy,	Alarm-1 delay timer	0.00 to 99.59 (min, sec.) (enabled when alarm-1 type "AL1" is 1 to 20 or 28 to 31) An alarm is output when the delay timer expires after the alarm setpoint is reached. External contact Closed Open Open Open Offi Blinking Timer setpoint	0.00		_
442 (DY2)	Alarm-2 delay timer	0.00 to 99.59 (min, sec.) (enabled when alarm-2 type "AL2" is 1 to 20 or 28 to 31)			_
653	Alarm-3 delay timer	0.00 to 99.59 (min, sec.) (enabled when alarm-3 type "AL3" is 1 to 20 or 28 to 31)			_
dy4)	Alarm-4 delay timer	0.00 to 99.59 (min, sec.) (enabled when alarm-4 type "AL4" is 1 to 20 or 28 to 31)			_
And (AMD)	Alarm mode	Allows the alarm function to be enabled or disabled according to the operating condition. 0: Always active 1: Not active when in Stop mode 2: Not active when in Stop mode or manual operation 3: Eight alarms are used and always enabled. 4: Eight alarms are used and disabled when the controller is at a stop. 5: Eight alarms are used and disabled when the controller is at a stop or in manual operation.	0		Ref.3.3(1)

Control Action-related Parameters

Located in: Main menu = $\[\[\[\[\[\[\[\[\] \] \] \] \] \]$ (CTL)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
OPR)	Output velocity limiter	OFF (0) 0.1 to 100.0%/sec can limit control output velocity	OFF (0)		_
nod	PID control mode	O: Standard PID control (with output bump at SP change) 1: Fixed -point control (without output bump at SP change) Choose "Fixed-point Control" when controlling pressure or flow rate.	0		Ref.2.1(2)
AF)	Anti-reset windup (Excess integration prevention)	AUTO (0), 50.0 to 200.0% The larger Setting, the sooner PID computation (integral computation) stops. Used when the control output travels up to 100% or down to 0% and stays at this point.	AUTO (0)		Ref.2.1(4)
ZON)	Zone PID selection	O: SP selection 1: Zone PID If set to "SP selection," allows PID constants to be selected for each target setpoint. If set to "Zone PID," automatically selects PID constants according to the temperature range set in the given Reference Point parameter.	0		Ref.4.1(2)
(R.MD)	Restart mode	CONT (0): Continues action set before power failure. MAN (1): Starts from manual operation status AUTO (2): Continues action set before power failure in automatic operation. Allows you to determine how the controller should recover from a power failure of longer than 2 sec.	CONT (0)		_
r.Ł.n. (R.TM)	Restart timer	0 to 10 sec. Sets time between power on and the instant where controller starts computation.	0 sec.		_
GRP	PID group number	Allows you to determine how many groups of setpoint, alarm and PID parameters the controller should show. 1: Show one set. 2: Show two sets. 3: Show three sets. 4: Show four sets. 5 to 8: Show as many groups of parameters as have been set.	8		Ref.4.1(1)
(1.RP)	Zone PID reference point-1	0.0 to 100.0% of PV input range. Note that $1.RP \le 2.RP \le 3.RP \le 4.RP \le 5.RP \le 6.RP$. Sets reference points at which switching is carried out between groups of PID constants according to the given temperature zone. You can set	100.0% of PV input range		Ref.4.1(2)
2. - P (2.RP)	Zone PID reference point-2	a maximum of six reference points and therefore a maximum of seven temperature zones. To enable this parameter, set the Zone PID Selection (ZON) parameter to "1".			Same as above
3, P (3.RP)	Zone PID reference point-3	The example below sets reference points 1 and 2 to provide 3 zones to switch PID constants automatically.			Same as above
4. P	Zone PID reference point-4	Maximum value of PV input range RH1 Zone 3			Same as above
5. -P	Zone PID reference point-5	Reference point 2 2.RP Setpoint The controller is op the 3rd group of PII Zone 2 The controller is op	O constants.		Same as above
6. RP)	Zone PID reference point-6	Reference point 1 1.RP Minimum value of PV input value PV input value The controller is op the 1st group of PII Time	D constants.		Same as above

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
rHY (RHY)	Zone switching hysteresis	0.0 to10.0% of PV input range span Allows hysteresis to be set for switching at a reference point.	0.5% of PV input range span		Same as above
(RDV)	Reference deviation	Used to select a group of PID parameters according to a deviation from the given target setpoint. The controller uses the PID parameters of the number selected in PID group number (GRP) if the PV input falls outside the given deviation range. The following example shows a case when only the reference deviation is set without setting any reference point. The selected set of PID parameters is as follows. Since region 1 is within the deviation range, the controller uses the 1st group of PID parameters. Since region 2 is outside the deviation range, the controller uses the PID parameters of the number selected in PID group number (GRP). Maximum value of PV input range RH1 A slope is set to vary the target setpoint. Minimum value of PV input range RL1 OFF (0): Disable 0.0% to 100.0% of PV input range span	, ,		Same as above

Analog Input Computation Parameters

Located in: Main menu = $\prod_{i=1}^{n} \prod_{j=1}^{n} \prod_{i=1}^{n} \prod_{j=1}^{n} \prod_{j=1}^{n} \prod_{i=1}^{n} \prod_{j=1}^{n} \prod_{i=1}^{n} \prod_{j=1}^{n} \prod_{i=1}^{n} \prod_{j=1}^{n} \prod_{i=1}^{n} \prod_{j=1}^{n} \prod_{j=1}^{n} \prod_{i=1}^{n} \prod_{j=1}^{n} \prod_{j$

			I		1
Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
5 (BS1)	Analog input-1 bias	Used to correct the PV input value beforehand. When in normal operation, use the PV Input Bias (BS) operating parameter. -100.0% to 100.0% of PV input range span	0.0% of PV input range span		Ref.1.1(6)
FL _(FL1)	Analog input-1 filter	OFF (0): Disable 1 to 120 sec.	OFF (0)		Same as above
(SR1)	Analog input-1 square-root computation	Performs square-root computation for the PV input value. OFF (0): Do not compute the square root ON (1): Compute the square root	OFF (0)		Ref.1.1(3)
[[LC1)	Analog input-1 low signal cutoff	0.0% to 5.0% The slope equals "1" at levels below the low-signal cutoff point.	1.0%		Same as above
(BS3)	Analog input-3 bias	Used to correct the remote input value100. 0% to 100.0% of PV input range span	0.0% of PV input range span		Ref.1.1(6)
FL3	Analog input-3 filter	OFF (0): Disable 1 to 120 sec.	OFF (0)		Same as above
5 , 3 (SR3)	Analog input-3 square-root computation	Performs square-root computation for the remote input value. OFF (0): Do not compute the square root ON (1): Compute the square root	OFF (0)		Ref.1.1(3) Ref.1.2(2)
[LC3]	Analog input-3 low signal cutoff	0.0% to 5.0% The slope equals "1" at levels below the low-signal cutoff point.	1.0%		Same as above

Retransmission Output Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
	Retransmission output-1 type	OFF (0): Disable 1: PV1, 2: SP1, 3: OUT1, 4: LPS loop power supply (15 V), 5: PV2, 6: SP2, 7: OUT2 Setpoints 5 to 7 are not available for single-loop control. Retransmission output 1 is always provided via terminals 14 and 15. In position proportional control, a valve opening signal (0% to 100%) is transmitted if setpoint "3" is selected. In heating/cooling control, an output value before allocation to heating/cooling control (0% to 100%) is transmitted if setpoint "3" is selected. (0% to 50%: Cooling-side output; 50% to 100%: Heating-side output)	1		Ref.2.2(1) Ref.2.2(3)
1-11	Maximum value of retransmission output-1 scale	RT1=1, 2: TL1 + 1 digit to 100.0% of PV input range RT1=3: TL1 + 1 digit to 100.0%	100.0% of PV input range		Ref.2.2(1)
1 (TL1)	Minimum value of retransmission output-1 scale	RT1=1, 2: 0.0% of PV input range to TH1 - 1 digit RT1=3: 0.0% to TH1 - 1 digit	0.0% of PV input range		Same as above
(RT2)	Retransmission output-2 type	Retransmission output-2 is available when the type of control output is not "current" or "voltage pulse." The output is provided via terminals 16 and 17. OFF (0): Disable 1: PV1, 2: SP1, 3: OUT1, 4: LPS loop power supply (15 V), 5: PV2, 6: SP2, 7: OUT2 Setpoints 5 to 7 are not available for single-loop control. In position proportional control, a valve opening signal (0% to 100%) is transmitted if setpoint "3" is selected. In heating/cooling control, an output value before allocation to heating/cooling control (0% to 100%) is transmitted if setpoint "3" is selected. (0% to 50%: Cooling-side output; 50% to 100%: Heating-side output)	OFF (0)		Ref.2.2(1) Ref.2.2(3)
	Maximum value of retransmission output-2 scale	RT2=1, 2: TL2 + 1 digit to 100.0% of PV input range RT2=3: TL2 + 1 digit to 100.0%	100.0% of PV input range		Ref.2.2(1)
L L L	Minimum value of retransmission output-2 scale	RT2=1, 2: 0.0% of PV input range to TH2 - 1 digit RT2=3: 0.0% to TH2 - 1 digit	0.0% of PV input range		Same as above

Deviation Monitor Parameters

Located in: Main menu = $[\ \ \ \ \ \ \ \ \ \ \ \ \ \ \]$ (CMLP) ; Submenu = $[\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \]$ (TRND)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
(DVB)	Deviation display band	0.0 to 100.0% of PV input range span Permits a change in the span of deviation shown on the front-panel deviation monitor.	1.0% of PV input range span		Ref.6.1(3)

Security-related Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
dh.	Front panel data setting (\triangle, ∇) key lock	OFF (0): Unlock ON (1): Lock	OFF (0)		Ref.7.1(2)
A/M)	Front panel A/M key lock	OFF (0): Unlock ON (1): Lock	OFF (0)		Same as above
nod (MOD)	Operating parameter main menu [MODE] lock	OFF (0): Unlock ON (1): Lock	OFF (0)		Same as above
[[LP1)	Operating parameter main menu [LP1] lock	OFF (0): Unlock ON (1): Lock	OFF (0)		Same as above
1 [12]	Although not used in Sir	ngle-loop Control, it is shown on the display.	·		
PID	Operating parameter main menu [PID] lock	OFF (0): Unlock ON (1): Lock	OFF (0)		Same as above
(USR)	Although not used in Sir	ngle-loop Control, it is shown on the display.	·		
FIJ !	Operating parameter main menu [PYS1] lock	OFF (0): Unlock ON (1): Lock	OFF (0)		Same as above
PY2	Although not used in Sir	ngle-loop Control, it is shown on the display.		•	•
(PWD)	Password setting	0: Password not set 1 to 30000	0		Ref.7.1(1)

SELECT Display Parameters

Located in: Main menu = $\begin{bmatrix} \mathbf{L} \mathbf{L} \mathbf{L} \end{bmatrix} \mathbf{F}$ (CONF); Submenu = $\begin{bmatrix} \mathbf{L} \mathbf{L} \mathbf{L} \end{bmatrix} \mathbf{E} \mathbf{L}$ (CSEL)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
[.5]	SELECT display-1 registration	OFF (0), 201 to 1023 Select the desired parameter from among the operating and setup parameters, then register the number	OFF (0)		Ref.6.1(1)
[.5 <i>2</i>]	SELECT display-2 registration	(D register No.) accompanying that parameter. For example, registering "302" for C.S1 allows you to change alarm-1 setpoint in operating display.			Same as above
[.53 (C.S3)	SELECT display-3 registration	Numbers for registering alarm SP parameter for operating display: Alarm-1 setpoint: 302			Same as above
[54]	SELECT display-4 registration	Alarm-2 setpoint: 303 Alarm-3 setpoint: 304 Alarm-4 setpoint: 305 Above numbers are alarm setpoint parameters for target			Same as above
(C.S5)	SELECT display-5 registration	setpoint-1 (1.SP). Set the registration number of the alarm setpoint parameter for target setpoint 2 (2.SP), to a value obtained by adding 25 to the registration number of the alarm setpoint parameter for the parameter 1.SP. Likewise, set the registration number of the alarm setpoint parameter for target setpoint 3 (3.SP), to a value obtained by adding 25 to the registration number of the alarm setpoint parameter for the parameter 2.SP. Likewise, the registration number for 4.SP to 8.SP can be obtained.			Same as above

Contact Output Registration Parameters

Located in: Main menu = $\mathbf{L}_{\mathbf{D}}$ (CONF); Submenu = $\mathbf{L}_{\mathbf{D}}$ (DO)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
(DO1)	Relay output flag registration for DO1	The following setpoints are registration numbers for Single-loop Control only. 5689: Alarm-1 output	5689		Ref.3.2(1)
DO2)	Relay output flag registration for DO2	5690: Alarm-2 output 5691: Alarm-3 output 5693: Alarm-4 output	5690		Same as above
	Relay output flag registration for DO3	1609: FAIL output	5691		Same as above
(DO4)	Open-collector transistor output flag registration for DO4		5693		Ref.3.2(1)
DO5)	Open-collector transistor output flag registration for DO5		0		Same as above
(DO6)	Open-collector transistor output flag registration for DO6		0		Same as above
do T	Open-collector transistor output flag registration for DO7		1609		Same as above

Contact Input Registration Parameters

Located in: Main menu = $\prod_{n} \prod_{n} F_{(CONF)}$; Submenu = $\prod_{n} I_{(DI)}$

Parameter Symbol	Name of Parameter		Setti	ng Ran	ge and	l Desci	ription			Initial Value	User Setting	Target Item in CD-ROM
(A/M)	Auto/Manual switching	These para make select DI1: 5161		itches		n the I		out to i	use to	5161		Ref.3.1(3)
,- ,-! ; (R/L)	Remote/Local switching	DI3: 5163 DI4: 5164								5168		Same as above
(S/R)	Run/Stop switching	DI5: 5165 DI6: 5166 DI7: 5167								5162		Same as above
CAS)	Switch to Cascade mode (when in cascade control)	DI8: 5168 The contact inp Contact inp	ut 1 (DI	I): Auto	(ON)/	Manua	ıl (OFF) switc		0		Same as above
(AUT)	Switch to Auto mode (when in cascade control)	Contact input	ts 3 to 6	(DI3 to	DI6): 8	SP sele	ction (s	ee tab	le below	0		Same as above
(MAN)	Switch to Manual mode (when in cascade control)	SP Selection	n: 2.SP	3.SP	4.SP	5.SP	6.SP	7.SP	8.SP	0		Same as above
57. 0 (SP.0)	Bit-0 of SP number setting	DI3 ON DI4 OFI DI5 OFI	ON	ON ON OFF	OFF OFF ON	ON OFF ON	OFF ON ON	ON ON	OFF OFF	5163		Same as above
(SP.1)	Bit-1 of SP number setting	DI6 OF	SP para							5164		Same as above
[SP.2)	Bit-2 of SP number setting	"OFF", the	controlle	r uses	tne imi	mediat	eıy pre	ceding	ISP.	5165		Same as above
(SP.3)	Bit-3 of SP number setting									5166		Same as above

UT Mode Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
(UTM)	Controller mode (UT mode)	1: Single-loop Control For another controller mode, see the User's Manual (Reference) (CD-ROM version).	1		_
(SMP)	PV sampling period setting	50, 100, 200 and 500 ms The controller restarts if any change is made to the PV sampling period; this does not affect other parameter settings at all, however.	200 ms		Ref.1.1(4)
SMC)	Sampling period error counter (reading only)	0 to 30000	Shows 0 at power-on.		Ref.1.1(5)

Input-related Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
(IN1)	PV input type (INPUT 1 terminals) Terminals ①, ② and ③	Specify the type of PV input as a range code. OFF (0), 1 to 18, 30, 31, 35 to 37, 40, 41, 50, 51, 55, 56 See "Instrument Input Range Codes" in "2. Initial Settings".	OFF (0)		_
(UN1)	PV input unit	Select the unit of PV input. % (0): Percent °F (5): Fahrenheit °C (1): Degree Celsius - (2): No unit	Depends on the PV input type.		
J- J-J J (RH1)	Max. value of PV input range	Set the instrument input range (RL1 < RH1). - For temperature input -	Depends on the PV input type.		_
(RL1)	Min. value of PV input range	Set the range of temperature that is actually controlled For voltage input - Set the range of a voltage signal that is applied. The scale across which the voltage signal is actually controlled should be set using the parameters Maximum Value of PV Input Scale (SH1) and Minimum Value of PV Input Scale (SL1).			_
DP1)	PV input decimal point position (shown when in voltage-input mode)	Set the position of the decimal point of voltage-mode PV input. 0 to 4	Depends on the PV input type.		_
(SH1)	Max. value of PV input scale (shown when in voltage-input mode)	Set the read-out scale of voltage-mode PV input19999 to 30000, where SL1 < SH1	Depends on the PV input type.		_
(SL1)	Min. value of PV input scale (shown when in voltage-input mode)				
(BO1)	Selection of PV input burnout action	Allows the PV input value to be determined as shown below in case of PV input burnout. • 105% of PV input range if set to "Upscale" • -5.0% of PV input range if set to "Downscale" OFF (0): Disable UP (1): Upscale DOWN (2): Downscale	Depends on the PV input type.		_
(RJC)	Presence/absence of PV input reference junction compensation	Allows input compensation to be applied to thermocouple input. OFF (0): Absent ON (1): Present	ON (1)		_
(IN3)	Remote input type (INPUT 3 terminals) Terminals ② and ②	Specify the type of remote input as a range code. 40, 41, 50, 51 See "Instrument Input Range Codes" in "2. Initial Settings".	41		Ref.1.2(1)
UN3)	Remote input unit	Select the unit of remote input. % (0): Percent °F (5): Fahrenheit °C (1): Degree Celsius - (2): No unit	% (0)		Same as above
(RH3)	Maximum value of remote input range	Set the range of a voltage signal. (RL3 < RH3)	5.000		Same as above
(RL3)	Minimum value of remote input range		1.000		Same as above
(DP3)	Remote input decimal point position	Set the position of the decimal point for remote input. 0 to 4	Same as the position of the PV input's decimal point		Same as above
(SH3)	Max. value of remote input scale	Set the remote input read-out scale19999 to 30000, where SL3 < SH3 Under normal operation, set the values of these parameters as shown below When PV input is temperature -	Maximum value of PV input scale		Same as above
(SL3)	Min. value of remote input scale	Maximum and minimum values of PV input range - When PV input is voltage - Maximum and minimum values of PV input scale	Minimum value of PV input scale		Same as above

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
LOS)	Remote input burnout action selection	Allows the remote input value to be determined as shown below in case of remote input burnout. • 105% of remote input scale if set to "Upscale" • -5.0% of remote input scale if set to "Downscale" OFF (0): Disable UP (1): Upscale DOWN (2): Downscale	OFF (0)		_
(P.U1)	PV unit	Set the unit of PV. % (0): Percent °F (5): Fahrenheit °C (1): Degree Celsius - (2): No unit	Same as the unit of PV input		Ref.1.1(8)
(P.D1)	PV decimal point position	Under normal operation, set the same value as in the PV Input Decimal Point Position (DP1) parameter. To shift the decimal point for temperature input, use this parameter. For example, set as "P.D1 = 0" to change a temperature reading of one decimal place to that of no decimal places. This involves reconfiguring the P.H1 and P.L1 parameters. 0 to 4	-		Same as above
(P.H1)	Maximum value of PV range	Under normal operation, keep the values of these parameters between the maximum and minimum values of the PV input range19999 to 30000	Maximum value of PV input range or scale		Same as above
F! (P.L1)	Minimum value of PV range	P.L1 < P.H1, where P.H1-P.L1 ≤ 30000	Minimum value of PV input range or scale		Same as above

Output-related Parameters

Located in: Main menu = [] [(UTMD) ; Submenu = [] [(OUT)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
ob (OT1)	Control output type	0 Time proportional PID relay contact output (terminals ① - ② - ③) 1 Time proportional PID voltage pulse output (terminals ⑥ - ⑦) 2 Current output (terminals ⑥ - ⑦) 3 ON/OFF control relay contact output (terminals ① - ② - ③) The following 4 to 12 are displayed only for heating/ cooling type controllers. 4 Heating-side relay output (terminals ① - ② - ③), cooling-side relay output (terminals ⑧ - ⑨) 5 Heating-side pulse output (terminals ⑥ - ⑦), cooling-side relay output (terminals ⑧ - ⑧ - ⑤) 6 Heating-side current output (terminals ⑥ - ⑦), cooling-side relay output (terminals ⑧ - ⑨) 7 Heating-side relay output (terminals ① - ② - ③), cooling-side pulse output (terminals ⑥ - ⑥)	0 Heating/cooling type:4	Conting	_
ĹŁ	Control output cycle	output (terminals (- ()) Heating-side current output (terminals () - ()), cooling-side pulse output (terminals () - ()) Heating-side relay output (terminals () - () - () - ()), cooling-side current output (terminals () - ()) Heating-side pulse output (terminals () - ()), cooling-side current output (terminals () - ()) Heating-side current output (terminals () - ()), cooling-side current output (terminals () - ()), cooling-side current output (terminals () - ())	30 sec.		
(CT)	time Heating-side control output cycle time in heating/cooling control	Relay's Behavior when Cycle Time = 10 sec. For 20% of Control Output For 50% of Control Output For 80% of Control Output 10 sec. On-state duration: 2 sec. Off-state duration: 8 sec. Off-state duration: 5 sec. Off-state duration: 2 sec.			Ref.3.3(4)
[Lc (CTc)	Cooling-side control output cycle time	1 to 1000 sec.	30 sec.		Ref.2.1(7)
Ro (AO1)	Analog output-1 type (OUTPUT 1: Terminals (6) and (7))	Allows control output or retransmission output to be presented as one of the following current signals. 0: 4 to 20 mA	0		Same as above
R _O 2	Analog output-2 type (OUTPUT 2: Terminals (and ())	1: 0 to 20 mA 2: 20 to 4 mA 3: 20 to 0 mA	0		Same as above
Ro3	Analog output-3 type (OUTPUT 3: Terminals (4) and (5)		0		Same as above
F IH	Analog output-1 100% segmental point	Set the values of segmental points for the 0% and 100% output levels at which the values are presented via OUTPUT-1 (terminals ⑥ and ⑦). See "■ Performing Split Computations" below.	100.0 %		Same as above
A IL	Analog output-1 0% segmental point	-5.0% to 105.0%	0.0 %		Same as above

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
R2H (A2H)	Analog output-2 100% segmental point	Set the values of segmental points for the 0% and 100% output levels at which the values are presented via OUTPUT-2 (terminals ⊕ and ⊕). See "■ Performing Split Computations" below.	100.0 %		Same as above
AZL	Analog output-2 0% segmental point	-5.0% to 105.0%	0.0 %		Same as above
73H (A3H)	Analog output-3 100% segmental point	Set the values of segmental points for the 0% and 100% output levels at which the values are presented via OUTPUT-3 (terminals ④ and ⑤). See ■ Performing Split Computations" below.	100.0 %		Same as above
A3L (A3L)	Analog output-3 0% segmental point	-5.0% to 105.0%	0.0 %		Same as above

■ Performing Split Computations

V-mode Output

The following explains an example of letting "Analog OUTPUT-1 (terminals 6 and 0)" and "Analog OUTPUT-3 (terminals 4 and 5)" present the V-mode characteristics of split computations.

- 1. Set the Control Output Type (OT1) parameter to "2". This sets the control output to "current output."
- 2. Set the Retransmission Output 1 (RT1) parameter to "3".

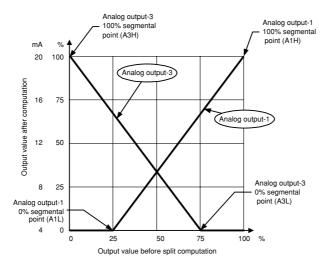
 This sets the retransmission output to "control output retransmission."
- 3. Set the Analog Output-1 100% Segmental Point (A1H) parameter to "100%".
- 4. Set the Analog Output-1 0% Segmental Point (A1L) parameter to "25%".
- 5. Set the Analog Output-3 100% Segmental Point (A3H) parameter to "0%".
- 6. Set the Analog Output-3 0% Segmental Point (A3L) parameter to "75%".

The figure below shows an example where both analog outputs-1 and 3 are set to the current signal of 4 to 20 mA DC. The type of output signal can be determined separately for each of the analog outputs listed above, using the following three parameters.

Analog output-1: Analog output-1 type (AO1)

Analog output-2: Analog output-2 type (AO2)

Analog output-3: Analog output-3 type (AO3)



Parallel-mode Output

The following explains an example of letting "Analog OUTPUT-1 (terminals 6 and 7)" and "Analog OUTPUT-3 (terminals 4 and 5)" present the parallel-mode characteristics of split computations.

- 1. Set the Control Output Type (OT1) parameter to "2". This sets the control output to "current output."
- 2. Set the Retransmission Output 1 (RT1) parameter to "3".

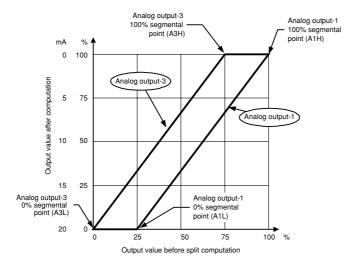
 This sets the retransmission output to "control output retransmission."
- 3. Set the Analog Output-1 100% Segmental Point (A1H) parameter to "100%".
- 4. Set the Analog Output-1 0% Segmental Point (A1L) parameter to "25%".
- 5. Set the Analog Output-3 100% Segmental Point (A3H) parameter to "75%".
- 6. Set the Analog Output-3 0% Segmental Point (A3L) parameter to "0%".

The figure below shows an example where both analog outputs-1 and 3 are set to the current signal of 20 to 0 mA DC. The type of output signal can be determined separately for each of the analog outputs listed above, using the following three parameters.

Analog output-1: Analog output-1 type (AO1)

Analog output-2: Analog output-2 type (AO2)

Analog output-3: Analog output-3 type (AO3)



Communication Parameters

Located in: Main menu = (UTMD); Submenu = (R485)

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
PSL (PSL)	Protocol selection	0: PC link communication 1: PC link communication (with sum check) 2: Ladder communication 3: Coordinated master station 4: Coordinated slave station 7: MODBUS (ASCII) 8: MODBUS (RTU) 10: Coordinated slave station (loop-1 mode) 11: Coordinated slave station (loop-2 mode)	0		_
bP5	Baud rate	600 (0), 1200 (1), 2400 (2), 4800 (3), 9600 (4) (bps)	9600 (4)		_
Pri	Parity	NONE (0): None EVEN (1): Even ODD (2): Odd	EVEN (1)		_
5 <i>L</i> P (STP)	Stop bit	1, 2	1		_
dLn (DLN)	Data length	7, 8; 7 is fixed for MODBUS (ASCII) 8 is fixed for MODBUS (RTU), Ladder	8		_
Rdr (ADR)	Address	1 to 99 However, the maximum number of stations connectable is 31.	1		_
r P.Ł	Minimum response time	0 to 10 (× 10 ms)	0		_

Value Calibration Related Parameters (Displayed for Position Proportional Controllers)

Located in: Main menu = $H_{\text{C}} = H_{\text{C}} = H_{\text{C}$

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
HAL (V.AT)	Automatic valve adjustment	Automatically adjusts the fully-closed and fully-opened positions of a valve. When this function is used, there is no need for adjustment using the parameters V.RS, V.L and V.H. OFF (0): - ON (1): Start automatic adjustment	OFF (0)		_
Kr5 (V.RS)	Valve position setting reset	The parameters V.RS, V.L and V.H are designed for manual adjustment of valve positions. Setting V.RS to 1 resets the valve adjustment settings and causes the indication "V.RS" to blink.	0		_
H L (V.L)	Fully-closed valve position setting	Pressing the SET/ENT key with valve position set to the fully-closed position causes the adjusted value to be stored. When V.L. adjustment is complete, V.L. stops blinking.	Undefined		_
HH	Fully-opened valve position setting	Pressing the SET/ENT key with valve position set to the fully-opened position causes the adjusted value to be stored. When V.H. adjustment is complete, V.H. stops blinking.	Undefined		_
Lr.Ł (TR.T)	Valve traveling time	5 to 300 sec. Used to operate a valve according to the estimated valve position. Set the time required for the valve to open fully from a state of being fully closed. Confirm the valve traveling time by consulting the datasheet of the valve's specifications. The valve traveling time is only effective when Valve Adjustment Mode (V.MD) is set to 1 or 2.	60 sec.		_
Hnd (V.MD)	Valve adjusting mode	O: Valve position feedback type 1: Valve position feedback type (moves to the estimating type if a valve input error or burnout occurs.) 2: Valve position estimating type	0		_

Parameter-initializing Parameters

Located in: Main menu = / // GUTMD); Submenu = / GUTMD); Submenu = / GUTMD)

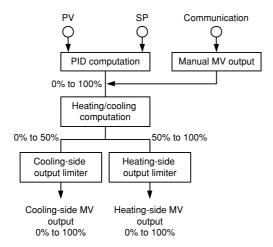
Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
; n;	Parameter initialization	OFF (0): - ON (1): Initialize parameters	OFF (0)		_

■ Tips About Heating/Cooling Control (for heating/cooling controllers only)

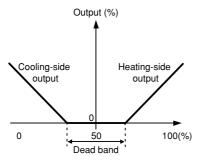
In heating/cooling control, the controller outputs the result of computation after splitting it into heating-purpose and cooling-purpose signals. In addition, the controller can perform PID control or ON/OFF control on the heating and cooling sides separately. When performing ON/OFF control, set the proportional band to "0".

The controller splits the result of computation (0 to 100%) into heating-side and cooling-side signals, as described below.

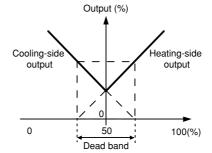
- 0% to 50% of the computation result is presented as a 0% to 100% cooling-side output.
- 50% to 100% of the computation result is presented as a 0% to 100% heating-side output.



Heating/cooling control provides two methods in which either none of the heating- and cooling-side outputs are presented or both of the heating- and cooling-side outputs are presented, as shown in the following figures.



Value of control output before split into heating- and cooling-side outputs



Value of control output before split into heating- and cooling-side outputs

Precautions in Heating/Cooling Control

Keep the ratio of the heating-side proportional band (P) to the cooling-side proportional band (Pc) equal to or below 5.

• If neither the heating-side nor the cooling-side is performing ON/OFF control, setting the integral time (I or Ic) of one side to "0" results in the Integral Time parameters of both sides being set to "OFF", irrespective of the integral time setting of the other side.

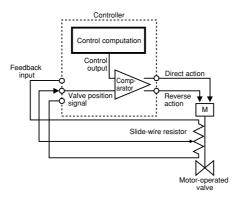
■ Tips About Position Proportional Control (for position proportional controllers only)

Position proportional control can be of either feedback type or estimating type. In feedback-type position proportional control, the controller obtains a valve position signal from a feedback slide-wire resistor attached to a valve.

In estimating-type position proportional control, you set the operating time required for a valve to change from the fully-closed position to the fully-open position beforehand. With the preset operating time, the controller controls the valve by estimating its position. In the case of estimating-type position proportional control, there is no need for feedback input wiring.

Feedback-type position proportional control is superior to the estimating type in terms of control performance. When in manual operation, you can directly manipulate the controller's output terminals. Pressing the \triangle key sends the valve into opening motion while pressing the \bigcirc key sends it into closing motion.

The figure below shows a schematic representation of a loop configured for position proportional control.



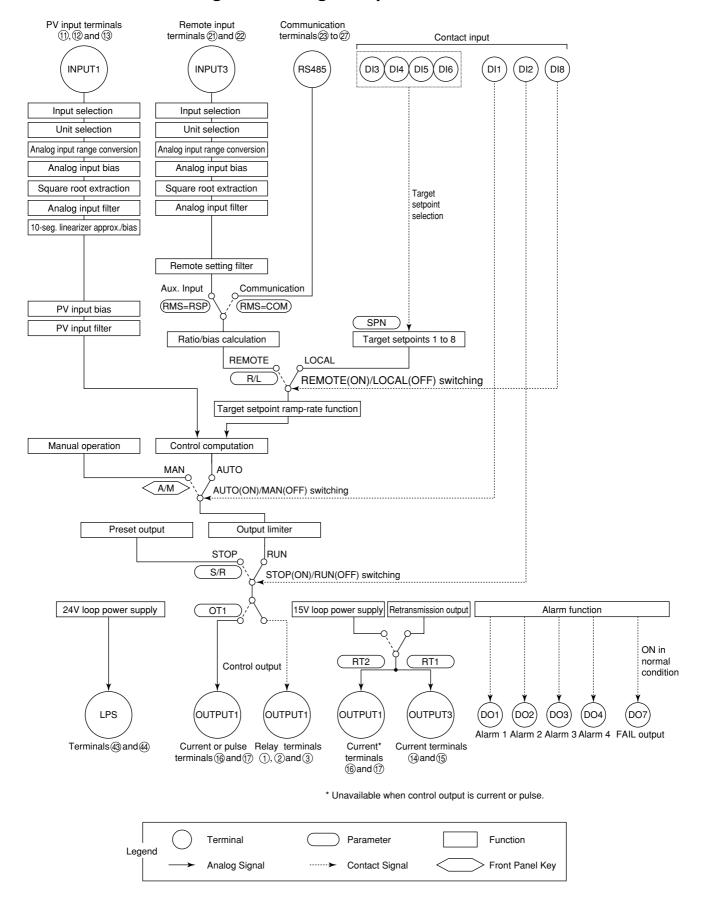
6. Function Block Diagram and Descriptions

This chapter contains the function block diagrams for "Single-loop control", "Single-loop heating/cooling control", and "Single-loop position-proportional control." For details on these function block diagrams, refer to the descriptions mentioned later.

In the function block diagram for "Single-loop control", some contact input/output that UT520 does not have appear. Refer to the function block diagram after confirming the presence/absence of the contact input/output.

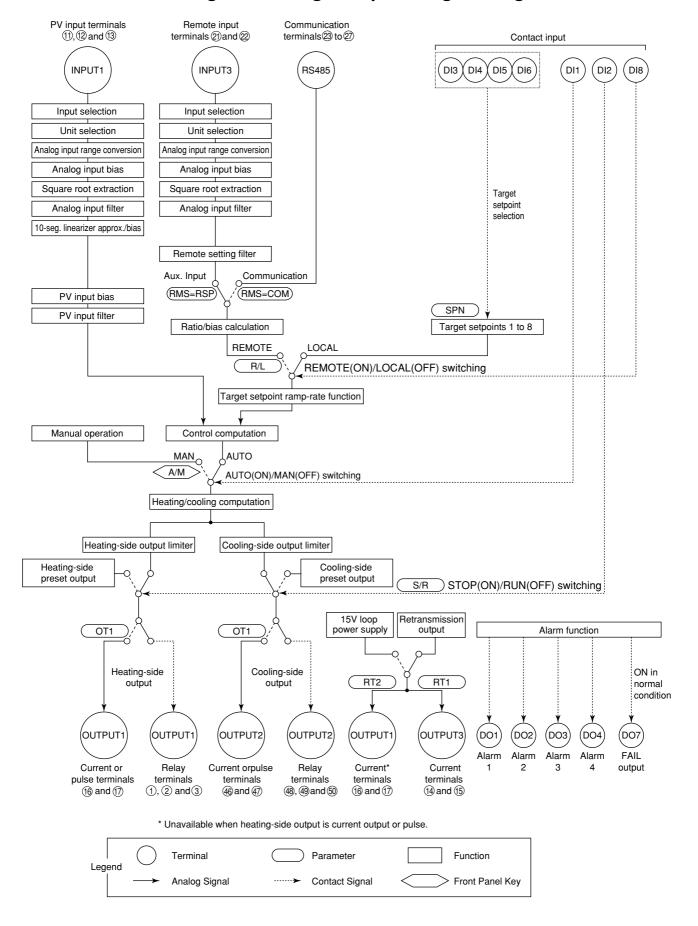
■ Function Block Diagram for Single-loop Control

<Toc>

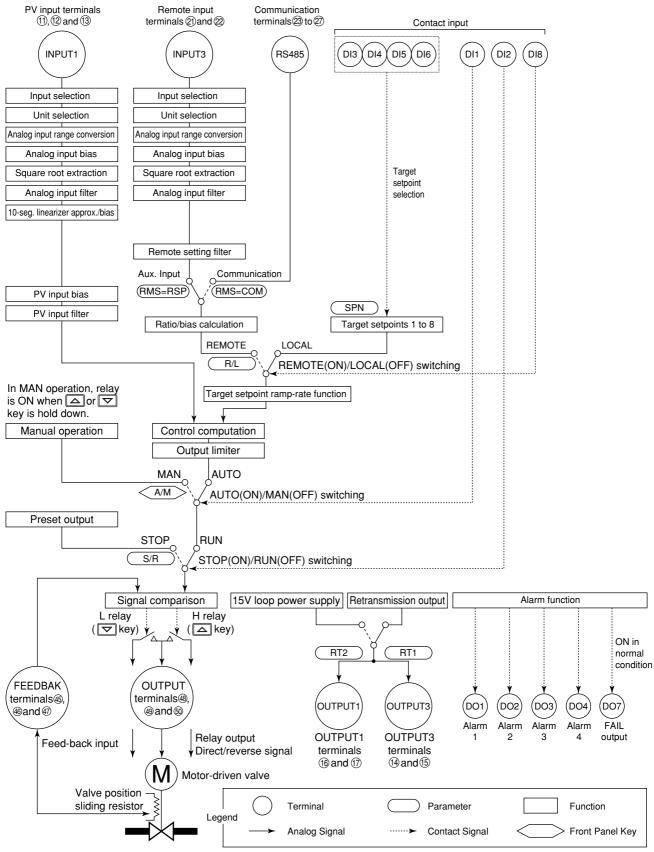


■ Function Block Diagram for Single-loop Heating/Cooling Control

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■ Function Block Diagram for Single-loop Position-proportional Control



Functions and Parameters for "Single-loop Control" in Initial State (Factory-set default)

Functions and parameters in initial state are given in the tables below. For details on each parameter, refer to "5.2 Lists of Parameters."

■ PV Input

PV input (INPUT1) is a universal input, which can receive signals from a thermocouple or RTD, or DC voltage signals. The controller is capable of biasing, square root extraction, first-order lag computation (filtering), ten-segment linearizer approximation, and ten-segment linearizer biasing on input signals.

Each function can be set by the following parameters.

Setup Parameters

Function	Parameter	Main menu	Submenu
Input selection	IN1	UTMD	IN
Unit selection	UN1	UTMD	IN
Analog input range conversion	RH1, RL1(DP1,SH1,SL1)	UTMD	IN
Analog input bias	BS1	CMLP	AIN
Square root extraction	SR1, LC1	CMLP	AIN
Analog input filter	FL1	CMLP	AIN

Operating Parameters

Function	Parameter	Main menu	Submenu
Ten-segment linearizer mode	1.MD	PYS1	None
Ten-segment linearizer approximation/biasing	1.A1 to 1.AB, 1.B1 to 1.BB	PYS1	None
PV input bias	BS	LP1	PAR
PV input filter	FL	LP1	PAR

Note: PV input bias (BS) and PV input filter (FL) among the operating parameters are used as bias and filter when normal operation. Analog input bias (BS1) and analog input filter (FL1) among the setup parameters are used when PV correction value is decided in advance.

■ Remote Input

Remote input (INPUT3) can receive DC voltage signals. The controller is capable of biasing, square root extraction, first-order lag computation (filtering), and ratio biasing on remote input signals.

Each function can be set by the following parameters.

Setup Parameters

Function	Parameter	Main menu	Submenu
Input selection	IN3	UTMD	IN
Unit selection	UN3	UTMD	IN
Analog input range conversion	RH3, RL3 (DP3, SH3, SL3)	UTMD	IN
Analog input bias	BS3	CMLP	AIN
Square root extraction	SR3, LC3	CMLP	AIN
Analog input filter	FL3	CMLP	AIN
Remote input selection	RMS	LOOP1	SP

Note: Remote input signal can be received via communication. For details, refer to "GREEN Series Communication Functions" (IM 05G01B02-01E).

Operating Parameters

Function	Parameter	Main menu	Submenu
Remote setting filter	RFL	LP1	PAR
Ratio bias calculation	RT, RBS	LP1	PAR
Remote/Local switching	MOD(REM/LCL)	MODE	None

■ Contact Input

Automatic (ON) / Manual (OFF) switching function is assigned to DI1 (contact input 1). Manipulated output can be changed using the 🖾 and 🖾 key in manual mode. Run (OFF) / Stop (ON) switching function is assigned to DI2 (contact input 2). Preset output value is output when the operation is stopped. PV input and alarms remain functioning as normal.

It is possible to select one out of eight setpoints by turning the four contact input signals ON or OFF. This function is assigned to DI3 (contact input 3) to DI6 (contact input 6).

Contact		,	Selected	d target	setpoint	number	•		If all contact inputs
input	1	2	3	4	5	6	7	8	are set to "OFF", the controller uses the
DI3	ON	OFF	ON	OFF	ON	OFF	ON	OFF	immediately preceding
DI4	OFF	ON	ON	OFF	OFF	ON	ON	OFF	target setpoint.
DI5	OFF	OFF	OFF	ON	ON	ON	ON	OFF	
DI6	OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	

For example, set contact input 4 (DI4) only to "ON" to change target setpoint 1 to 2. Set contact inputs 3 (DI3) and 4 (DI4) to "ON" to select target setpoint 3.

No function is assigned to DI7 (contact input 7).

Remote/Local mode switching function is assigned to DI8 (contact input 8). External target setpoint can be set via remote input (INPUT3).

■ Target Setpoint and PID

It is possible to use a maximum of eight groups of target setpoints and PID parameters. The target setpoint can be selected by key operation or contact input. For selection by contact input, refer to "Contact Input."

Operating Parameters

Function	Parameter	Main menu	Submenu
Target setpoint number selection	SPN	MODE	None
Target setpoints 1 to 8	n.SP	LP1	n.PID
Proportional band (P)	n.P	LP1	n.PID
Integral time (I)	n.l	LP1	n.PID
Derivative time (D)	n.D	LP1	n.PID
Cooling-side proportional band (Pc)	n.Pc	LP1	n.PID
Cooling-side integral time (Ic)	n.lc	LP1	n.PID
Cooling-side derivative time (Dc)	n.Dc	LP1	n.PID

Note: Parameters n.SP, n.P, n.I, n.D, n.Pc, n.Ic n.Dc (n=1 to 8), and submenu n.PID (n= 1 to 8) correspond to the target setpoint number selected in the target setpoint number selection (SPN).

The target setpoint ramp rate setting function prevents the target setpoint form changing suddenly. It is possible to set the upward and downward changing rate (i.e., ramp rate) independently in the parameters UPR and DNR. The unit of the ramp rate (hour, or minute) is specified in TMU.

Setup Parameters

Function	Parameter	Main menu	Submenu
Ramp-rate time unit setting	TMU	LOOP1	SP

Operating Parameters

Function	Parameter	Main menu	Submenu
Target setpoint ramp-rate setting	UPR, DNR	LP1	PAR

■ Control Output

Control output (OUTPUT1) selects the output type among the current output, voltage pulse output, and relay contact output signal. For heating/cooling control, the cooling-side signals are output to OUTPUT2.

Preset output value is output when the operation is stopped by key operation or contact input, which takes priority over the manual operation.

Each function can be set by the following parameters.

Setup Parameters

Function	Parameter	Main menu	Submenu
Control output type selection	OT1	UTMD	OUT
Control output cycle time	СТ	UTMD	OUT
Cooling-side control output cycle time	CTc	UTMD	OUT
Analog output 1 type	AO1	UTMD	OUT
Analog output 2 type (cooling-side)	AO2	UTMD	OUT

Operating Parameters

Function	Parameter	Main menu	Submenu
Preset output	n.PO	LP1	n.PID
Output limiter	n.OL, n.OH	LP1	n.PID
Cooling-side preset output	n.Oc	LP1	n.PID

Note: Parameters n.PO, n.OL, n.OH, n.Oc (n=1 to 8), and submenu n.PID (n= 1 to 8) correspond to the target setpoint number selected in the target setpoint number selection (SPN).

■ Contact Output

Alarm 1 is output via DO1 (contact output 1).

Alarm 2 is output via DO2 (contact output 2).

Alarm 3 is output via DO3 (contact output 3).

Alarm 4 is output via DO4 (contact output 4).

No function is assigned to DO5 (contact output 5) and DO6 (contact output 6).

FAIL is output via DO7 (contact output 7). ON in the normal condition and OFF in the FAIL condition.

Setup Parameters

Function	Parameter	Main menu	Submenu
Alarm 1 type	AL1	LOOP1	ALM
Alarm 2 type	AL2	LOOP1	ALM
Alarm 3 type	AL3	LOOP1	ALM
Alarm 4 type	AL4	LOOP1	ALM

Operating Parameters

Function	Parameter	Main menu	Submenu
Alarm 1 setpoint	n.A1	LP1	n.PID
Alarm 2 setpoint	n.A2	LP1	n.PID
Alarm 3 setpoint	n.A3	LP1	n.PID
Alarm 4 setpoint	n.A4	LP1	n.PID

Note: Submenu n.PID (n= 1 to 8) corresponds to the target setpoint number selected in the target setpoint number selection (SPN).

■ Retransmission Output

PV, target setpoint, or control output can be output to retransmission output 1 (OUTPUT3). Retransmission output 2 (OUTPUT1) can be used when the control output is relay. Each function can be set by the following parameters.

Setup Parameters

Function	Parameter	Main menu	Submenu
Retransmission output 1 type	RT1	CMLP	RET
Retransmission output 1 scale	TH1, TL1	CMLP	RET
Retransmission output 2 type	RT2	CMLP	RET
Retransmission output 2 scale	TH2, TL2	CMLP	RET

■ 15V DC Loop Power Supply

The 15V DC loop power supply (OUTPUT3) uses the same terminal as retransmission output 1 or 2. The 15V DC loop power supply can not be used when retransmission output 1 or 2 is used. To use the 15V DC loop power supply, set "4" in retransmission output 1 type (RT1) or retransmission output 2 type (RT2).

Each function can be set by the following parameters.

Setup Parameters

Function	Parameter	Main menu	Submenu
Retransmission output 1 type	RT1	CMLP	RET
Retransmission output 2 type	RT2	CMLP	RET

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